

INSTRUCTION MANUAL SUPER MICRO CYLINDER Position locking type SCM-Q

- Please read this instruction manual carefully before using this product, particularly the section describing safety.
- Retain this instruction manual with the product for further consultation whenever necessary.

For Safety Use

To use this product safety, basic knowledge of pneumatic equipment, including materials, piping, electrical system and mechanism, is required (to the level pursuant to JIS B 8370 Pneumatic System Rules).

We do not bear any responsibility for accidents caused by any person without such knowledge or arising from improper operation.

Our customers use this product for a very wide range of applications, and we cannot keep track of all of them. Depending on operating conditions, the product may fail to operate to maximum performance, or cause an accident. Thus, before placing an order, examine whether the product meets your applications, requirements, and how to use it.

This product incorporates many functions and mechanisms to ensure safety. However, improper operation could result in an accident. To prevent such accidents, read this operation manual carefully for proper operation.

Observe the cautions on handling described in this manual, as well as the following instructions:

CAUTION :

- Before performing an overhaul inspection on the actuator, deactivate residual pressure completely.
- While the actuator is operating, do not step into or place hands in the driving mechanism.
- To prevent an electric shock, do not touch the electric wiring connections (exposed live parts) of the actuator equipped with a solenoid valve or switch.
 - Perform an overhaul inspection with the power off. Also, do not touch these live parts with wet hands.

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SCM-Q

Super micro cylinder Position Locking type

Manual No. SM-230478-A

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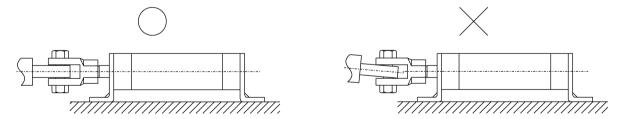
1. UNPACKING

- 1) Make sure that the type No. on the nameplate of the delivered Super Micro Cylinder matches the type No. you ordered.
- 2) Check the appearance for any damage.
- 3) Stop up the piping port with a sealing plug to prevent the entry of foreign substances into the cylinder. Remove the sealing plug before piping.

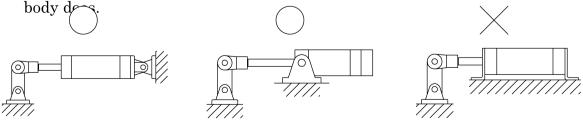
2. INSTALLATION

2.1 Installation

- 1) The ambient temperature for this cylinder is -10 to 60°C.
- 2) Consult CKD, when the cylinder is used in the dusty atmosphere, because there may be a case that foreign substances go inside through breathing hole of locking mechanism and cause malfunction.
- 3) Carefully avoid other object from hitting the tube. Otherwise, it may get the tube distorted and cause malfunction of the cylinder.
- 4) When cylinder is fixed and rod end is guided:
 In case the piston rod of cylinder and the load are misaligned, the bushes and packings of the cylinder are extremely worn out. Hence, connect them with CKD floating connector (spherical bearing).
- 5) When cylinder is fixed and rod end is connected with pin joint:
 In case the load acting direction is not parallel with the rod axial center, the rod and tube may get entangled causing seizure, etc. Hence, make sure that the rod axial center and the load transfer direction are aligned to each other.



When the load acting direction changes with the cylinder operation:
Use an oscillating cylinder (clevis type or trunnion type) capable of making revolution to a certain angle. Furthermore, install the rod and connecting metal (knuckle) so that it moves in the same direction as the cylinder main body does

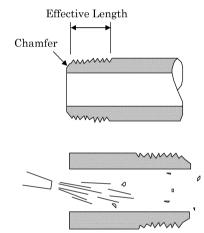


Clevise type Trunnion type Foot mount type

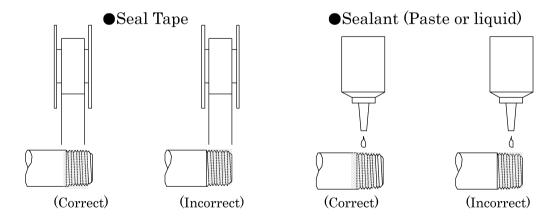


2.2 Piping

- 1) For piping beyond the filter, use pipes that are tough against corrosion such as galvanized pipes, nylon tubes, rubber tubes, etc. If the operating ambient temperature exceeds 60°C, use copper pipes.
- 2) See to it that the pipe connecting cylinder and solenoid valve has effective cross-sectional area which is needed for the cylinder to drive at the specified speed.
- 3) Install filter preferably adjacent to the upper-stream to the solenoid valve for eliminating rust, foreign substance in the drain of the pipe.
- 4) Be sure observe the effective thread length of gas pipe and give a chamfer of approx. 1/2 pitch from the threaded end.
- 5) Flush air into the pipe to blow out foreign substances and chips before piping.



6) Refrain from mapplying sealant or sealing tape approx. two pitches of thread off the tip of pipe to avoid residual substances from falling into piping system.

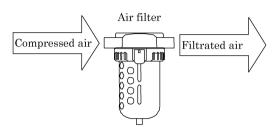


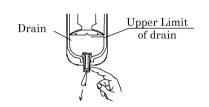
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2.3 Fluid

- It is necessary to use dehumidified air that has been filtered from compressed air. Carefully select an adequate filter that has an adequate filtration rate (preferably 5μ m or less), flow rate and its mounting location (as nearest to the directional control valve as possible).
- 2) Be sure to drain out the accumulation in the filter periodically.
- 3) Note that the intrusion of carbide for the compressor oil (such as carbon or tarry substance) into the circuit causes malfunction of the solenoid valve and the cylinder. Be sure to carry out thorough inspection and maintenance of the compressor.

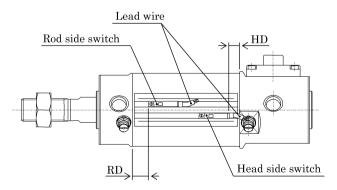




4) This cylinder does not require lubrication. It is recommended, however, to use Turbine oil Grade 1, ISO VG32 as a lubricant, if and when lubrication is needed.

2.4 Location of mounting Switches on a Cylinder

1) Location of mounting switches on a cylinder. (Common items)



(1) At the stroke end

Refer the illustration above. Mount switches within the rod side dimension RD as well as the head side dimension HD for the purpose of having switches function at the points of the maximum sensitive position. (Refer to Tables 1 and 2.)



(2) Intermediate of stroke

Move the piston where it is anticipated to stop and fix it tentatively Slide a switch carefully along the side of cylinder over the piston to find out the spot where switch turns on. This type spot should be located on both side of piston. The intermediate spot between those posits is of the maximum sensitive position and where the switch is supposed to be installed.

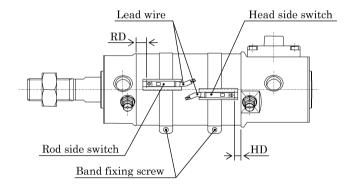
(3) Relocation of switch

Slide switch body along cylinder tube after loosening mounting screws and tighten screws when located the maximum sensitive position. (Apply tightening torque of 0.1 to $0.2N \cdot m$)

(4) Replacing switch

Take out switch out of groove after loosening mounting screws. Slide new replacing switch into groove and tighten screws upon placing the switch at the maximum sensitive position. (Apply tightening torque of 0.1 to 0.2N·m)

2) Switch mounting position (Band method)



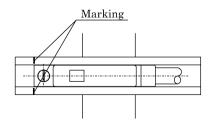
(1) Fine adjustment of switch mounting position

When the switch is mounted by means of the band method, the one-color indication switch is finely adjusted about ±3 mm back and forth from the mounting position, which has been set before shipment.

If the adjustment range exceeds ± 3 mm or the fine adjustment of the two-color indication switch is performed, move the band.

(2) Replacement of switch

A marking is provided at a position where is 4 mm far from the end face of the switch rail. When replacing the switch, this marking is used as reference mounting position. Additionally, the marking of the switch rail has been set at the maximum sensitive position before shipment from the factory.



As the switch type is changed or the band is moved, the maximum sensitive position is changed. If this happens, adjust the mounting position appropriately.



(3) Movement of switch(Circumference direction)

Loosen the band fixing screws and move the switch rail in the circumference direction. Secure the rail at the specified position by tightening the fixing screws. At this time, the tightening torque is 0.6 to 0.8 N·m.

(4) Movement of band

Loosen the band fixing screws and move the switch rail and band along with the cylinder tube. Secure the rail and band at the specified position by tightening the fixing screws. At this time, the tightening torque is 0.6 to 0.8 N·m.

3) Operating range

The switch turns on first and turns off as the piston moves along its stroke. Precise operating range deviate slightly depending upon the direction of piston movement as shown right.

The center of the range is the mostly sensitive position. Setting switch at this point eliminates majority of external disturbance and provides the most stabile actuation of switch.

4) Hysteresis

- (1) Precise operating range deviate slightly depending upon the direction of piston movement as shown right.
- (2) Switch is apt to be disturbed its accuracy by external effect when piston stops within this range. Carefully avoid designing stopping location of piston.

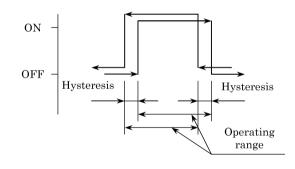


Table1 (Rail method)

(mm)

	Solid st	ate switch (te switch (T2H/T2V, T3H/T3V) Reed switch (T0H/T0V, T5H/T5V)				T5V)	
Bore size (mm)	(mm) position Operating Hysteresis			n sensitive tion	Operating	Hysteresis		
	RD	RD	range		$_{ m HD}$	RD	range	
φ 20	7.0	7.5	3 to 8		4.0	6.5	6 to 14	
φ 25	6.0	8.5	3 to 9		3.0	7.5	5 to 14	
φ 32	7.0	9.5	3 to 8		4.0	8.5	5 to 12	
φ 40	9.0	11.5		1.5 or less	6.0	10.5	6 to 14	3 or less
φ 50	11.5	13.0	3 to 9	1.5 or less	8.0	12.5	0 10 14	5 or less
φ 63	11.5	13.0			8.0	12.5	7.4.15	
φ 80	13.0	20.0	4 to 10		10.5	19.5	7 to 15	
φ 100	13.5	19.5	4 10 10		11.0	18.5	9 to 15	



Table2 (Band method)

(mm)

	Solid state switch (T2H/T2V, T3H/T3V) Reed switch (T0H/T0V, T5H/			T5V)				
Bore size (mm)			position Operating Hysteresis		Maximum sensitive position		Operating	Hysteresis
	HD	RD	range		HD	RD	range	
$\phi 20$	6.5	7.5	3 to 8		5.5	6.5	6 to 14	
$\phi 25$	5.5	8.5	3 to 9		4.5	7.5	5 to 14	
φ 32	6.5	9.5	3 to 8		5.5	8.5	5 to 12	
ϕ 40	8.5	11.5		1.5 or less	7.5	10.5	6 to 14	3 or less
φ 50	11.0	13.0	3 to 9	1.5 or less	10.0	12.5	6 to 14	5 or less
ϕ 63	11.0	15.0			10.0	12.5	74015	
φ 80	13.0	20.0	4 to 10		12.0	19.0	7 to 15	
φ 100	13.5	19.5	4 10 10		12.5	18.5	9 to 15	

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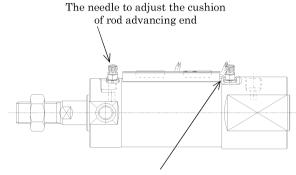
3. OPERATION

3.1 Operating the Cylinder

- 1) The working pressure for this type of cylinder is specified in "Product Specifications". Operate the system within this range.

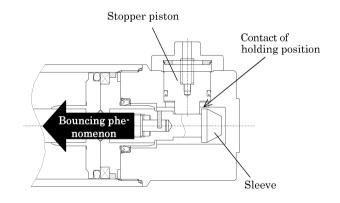
 Let the load factor of the cylinder be 50 % or less.
- 2) Though the cushion has been adjusted at no load when delivered, adjust the cushion needle when the change of cushion effect is required. Tightening the needle (clockwise) makes cushion more effective. Tighten the needle lock nut all the way after adjustment.

However, if kinetic energy such as load is heavy or speed is too fast, exceeding the values given in Table 3, consider of providing a shock absorber.



The needle to adjust the cushion of rod retracting end

If the cushion adjusting needle on the locking mechanism side is fastened too tight, the piston bounces on the stroke end to bring the sleeve and the stopper piston into contact with a bump, thereby resulting in damage in the locking mechanism. On the other hand, if the cushion adjusting needle is opened too much, the piston bounces on the end of stroke, it also causes damage to the mechanism. Make adjustments of the needles for the cushion so as not to allow bouncing of the piston.



When an external cushion dumper (such as a shock absorber) is used to stop the piston, it is also needed to make adjustments so as not to allow bouncing of the piston.

Conduct periodic inspections once or two times a year to check for damage on the holding portion by this phenomenon.



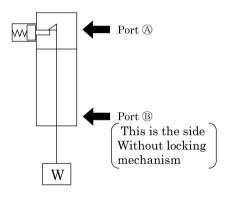
Table 3 Table of cushion characteristics

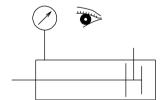
	Rubber cushion	Air cushion		
Bore size (mm)	Allowable energy absorption (J)	Effective air cushion length (mm)	Allowable energy absorption (J)	
$\phi 20$	0.11	8.1	0.8	
$\phi 25$	0.2	0.1	1.26	
ϕ 32	0.53	8.6	2.5	
φ 40	0.91	0.0	3.7	
ϕ 50	1.0		8	
ϕ 63	1.6	13.4	14.4	
φ 80	3.3	15.4	25	
φ 100	5.8	10.4	46	

- 3) Adjust the working piston speed with the speed controller mounted.
- 4) To release the locking, be sure to remove the load to locking mechanism by supplying pressure to the port B first where no locking mechanism is installed.

It is quite dangerous to supply pressure to the A direct while piston is being locked after both ports A and B are exhausted because the piston rod is apt to pop out all the sudden due to the load on the tip of piston rod. When the port A is pressurized, at the same moment, pilot line releases the locking mechanism.

5) Confirm by an air gage, before starting daily operation, that the cylinder chamber where no locking device mounted (port B) is adequately pressurized.

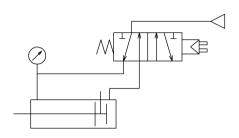




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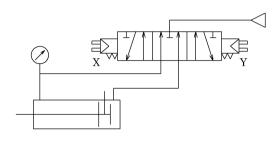


- 6) During the design of circuit layout, make sure the pressure delivery just before starting daily operation is so arranged as shown on the illustration.
 - (A) A satisfactory layout



(B) A sample of layout which requirs a particular consideration to start a system. Piston rod is apt to pop out when Y solenoid is energized first. Design the circuit which energizes X solenoid first then dose Y

solenoid.



- 7) There is a tendency that it takes some lengthy time before locking when the exhausting air speed is excessively slow from the chamber of locking mechanism side. (For instance, speed control is set at low speed while piping is long and small diameter.)
- 8) There is approx. 1mm play along piston rod axis under locking status.
- 9) It only locks when piston comes to its stroke end of mechanism side.

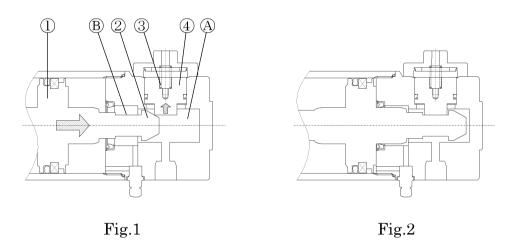


3.2 Principle of Mechanical Motion

1) Locking Motion

- (a) Stopper piston ④ is pushed up by the slant of sleeve tip ② as the piston ① of cylinder approaches to its stroke end. (Fig. 1)

 The stopper piston, however, is held up by the pressure when the pressure within the chamber ⑥ is Min. working pressure or higher.
- (b) When the piston of cylinder further comes closer to its stroke end and the groove ® of sleeve matches to the tail of stopper piston, the stopper piston drops back to the groove ® due to expansion force of spring ③, generating an effect of locking the piston of cylinder. (Fig. 2)



2) Unlocking Motion

The stopper piston, when compressed air is supplied through the port, floats up against the force of the spring ③ and comes off the groove ⑤ of sleeve, generating an effect of unlocking the piston of cylinder. (Fig. 3)

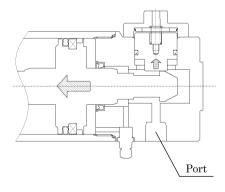


Fig.3

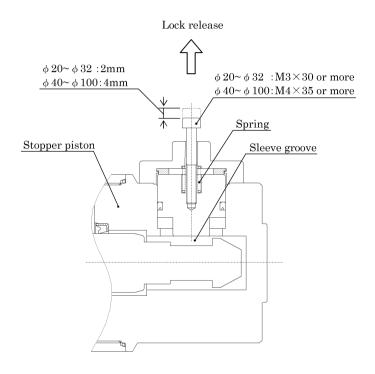
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3) Unlocking Procedures by Manual control

Screw a hexagon socket head cap screw (ϕ 20 to ϕ 32 : M3 × 30 or more, ϕ 40 to ϕ 100 : M4 × 35 or more) into the stopper piston, and pull the bolt up ϕ 20 to ϕ 32 : 2mm, ϕ 40 to ϕ 100 :4mm with a force of 2 kgf or more. The stopper piston moves and the lock is released.

When the hand is released, if the stopper piston is returned by the internal spring and enters the piston rod groove, the piston locks.





3.3 How to use the Switches

3.3.1 Common items

1) Magnetic environment

Do not operate this product in a place where a strong magnetic field or large current (large magnet or spot welder, etc.) exists. If a cylinder with the switch is installed in parallel to this product or the magnetic substance moves near the cylinder, the mutual interference may occur and affect the detection accuracy.

2) Protection of lead wire

Pay consideration to eliminate rapeating bending stress or stretching of lead wire while laying the wire.

To the moving portion, use such cord of flexibility as for building a robot.

Operating temperature

Do not operate the product at a high temperature (60°C)

Always avoid operation of the product in a hot place due to temperature characteristics of magnetic and electronics parts.

4) Intermediate position detection

When activating the switch halfway of the stroke, the relay may not respond if the working piston speed is too fast.

5) Impact

Do not apply a large vibration or impact to the product when transporting the cylinder, or mounting or adjusting the switch.

6) Changing switch lead wire colors

The colors of the switch lead wires have been changed, as shown in the following table, in response to the revision of the JIS standard and the subsequent revision of the NECA (Nippon Electric Controllers Association) standard

		Before change	After change
	2-wire	White (+)	Brown (+)
MCDATIVI	type	Black (-)	Blue (—)
M, S, R, A, T, K, V, H Series	3-wire	Red (+)	Brown (+)
Beries		White (output)	Black (output)
	type	Black (-)	Blue (—)
		White (+)	Brown (+)
	3-wire	Yellow (preventive	Orange (preventive
m IZ	type	maintenance output)	maintenance output)
T, K Series		Black (—)	Blue (—)
(Equipped with preventive		Red (+)	Brown (+)
maintenance output)	4-wire	White (regular output)	Black (regular output)
manivenance output)	type	Yellow (preventive	Orange (preventive
	суре	maintenance output)	maintenance output)
		Black (—)	Blue (—)



3.3.2 Operational Cautions, Solid state switch (T2, T3)

1) Connection of lead cord

Comply with the color coding specified on the illustrations. Be sure to turn the power off before starting connecting work.

An erroneous wiring or short circuiting of load causes damage to not only switches, but also load side circuit. Wiring work without shutting electricity off may cause damage to the load side circuit

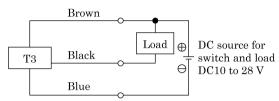


Fig.1 Fundamental circuit Example (1) of T3 (In case the same source of power is used.)

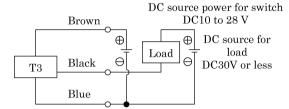


Fig.2 Fundamental circuit Example (2) of T3 (In case individual sources of power are used.)

2) Protection of output circuit

Install some protective circuit as illustrated in Fig. 3 when inducing type load (Relay or solenoid valve) are to be used because those types apt to generate surge current switch off.

Install some protective circuit as illustrated in Fig. 4 when capacitor type load (Capacitor type) are to be used, because these types apt to generate a dash current when turning the switch ON.

Install some protective circuit as illustrated in Fig. 5 or 6 (in case of model T2) and Fig 7 (in case of model T3).

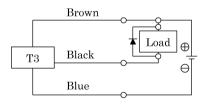
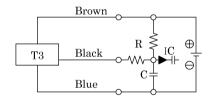


Fig.3 An example of using inducing load together with surge absorptive element (diode). (Hitachi Mfg. made diode V06C or equivalent is recommended.)



Flg.4 An example of using capacitor type load together with current regulating resister R. Comply with the following formula to figure out required R. $\frac{V}{0.05} = R(\Omega)$

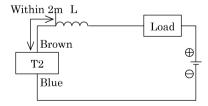


Fig.5 \cdot Choke coil

L= a couple hundred μ H to a couple mH surpassing high frequency characteristic · Install it near by a switch (within 2m).

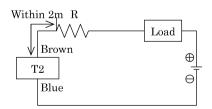


Fig.6 · Dash current restriction resister.

R= As much large resister as the load circuit can afford.

· Install it near by a switch (within 2m).



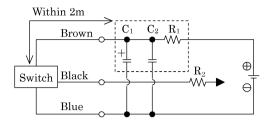


Fig7 · Electric power noise absorptive circuit. C_1 =20 to 50 μ F electrolytic capacitor (Withstand voltage 50V or more) C_2 =0.01 to 0.1 μ F ceramic capacitor R_1 =20 to 30 Ω

- Dash current restriction resister.
 R₂=As much large resister as the load circuit can afford.
- · Install it nearby the switch (Within 2m)
- 3) Connection to a programmable controller (Sequencer).

 Type of connection varies depending upon the model of the programmable controller. Refer to the following Fig. 8 to 12 respectively.

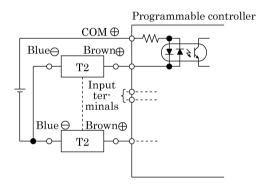


Fig.8 An example of T2 connection to source input type (an external power source)

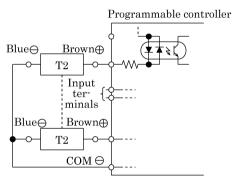


Fig. 8 An example of T2 connection to source input type (an internal power source)

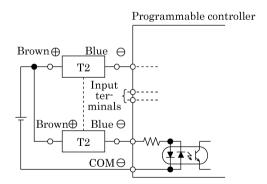


Fig.10 An example of T2 connection to source input type

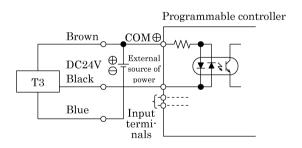


Fig.11 An example of T3 connection to source input type (an internal power source)

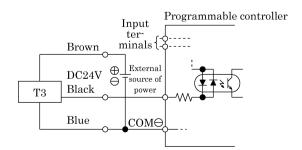


Fig.12 An example of T3 connection to source input type (an internal power source)



4) Series connection

The total voltage will decrease when the T2 switches connections have a leak. Therefore, confirm the input specifications for the programmable controllers, which are the connecting load. However, dimming or total failure of the indicator light may exist.

T3 switches hardly ever leak. When less than 10μ A, then leakage may occur. Usually dimming and failure of the indicator light do not occur.



3.3.3 Reed switch (T0, T5)

1) Lead wire connections

Do not connect the lead wires of the switch to the power supply directly. Always connect the loads in series. For T0 switch, carefully check following items (A), (B).

- A When using the switch for DC power supply, connect the brown and blue lines to the positive and negative sides, respectively. If these lines are connected reversely, the switch is activated, but the indicator light is not lit.
- B When the switch is connected to an AC relay or a programmable controller input, the indicator light on the switch is not lit if the half-wave rectification is performed in the connected circuit. If this occurs, reverse the polarities of the switch lead wire connection. The indicator light may then be lit.

2) Contact protective measures When an inductive load, such as relay is used or the wire length exceeds that stated in Table 1, always install a contact protective circuit.

Table1					
Electric power	Length of wire				
DC	100m				
AC	10m				

(1) Protective circuit when connecting an inductive type load.

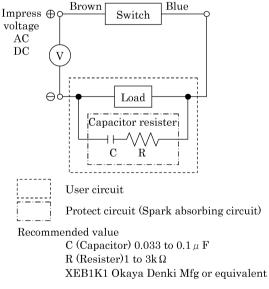
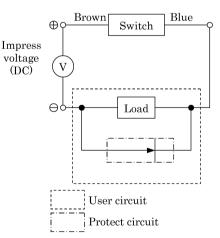


Fig.1 When capacitor resister is used.

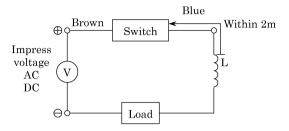


Rectifying diode, general use Hitachi Mfg. product V06C or equivalent

Fig.2 When diode is used.

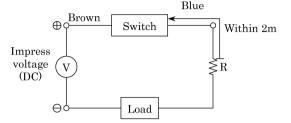


(2) Protective circuit when the wire length exceeds that stated Table 1



- Choke coil
 L=a couple hundred μ H to a couple mH surpassing high frequency characteristic
- · Install it near by a switch (within 2m).

Fig.3



- Dash current restriction resister
 R=As much large resister as the load circuit can afford.
- · Install it near by a switch (within 2m).

Fig.4

3) Contact capacity

Do not use a load exceeding the maximum contact capacity of the switch. Additionally, if the current is lower than the rated current value, the indicator light may not be lit.

4) Relay

Always use the relays listed below.

Omron Corporation ······ MY type

Fuji Electric Co., Ltd. · · · · · · HH5 type

Panasonic, Ltd. ······ HC type

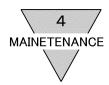
5) Serial connection

Total voltage loss, when connected T0 switches in series, equals to the sum of respective voltage loss of each switch.

The total voltage loss becomes equivalent to one T0 (approx. 2.4V) when connecting the combination of one T0 for actuation confirming and rest of T5 switches. Indicator light is lit only when all switches turn on.

6) Parallel connection

There is no restriction in parallel connection number of switches of these types. Multi number connection of model T0, sometimes, cause a dimmed indicator light or complete indicator light failure.



4. MAINTENANCE

4.1 Periodical Inspection

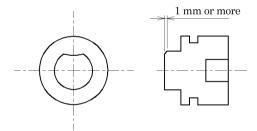
- In order to upkeep the cylinder in optimum condition, carry out periodic inspection once or twice a year.
 - Before starting an inspection, take appropriate measures separately to prevent a load from falling down under its own weight.

2) Inspection items

- (1) Check the bolts and nuts fitting the piston rod end bracket and mounting bracket for slackening.
- (2) Check to see that the cylinder operates smoothly.
- (3) Check any change of the working piston speed and cycle time.
- (4) Check for internal and/or external leakage.
- (5) Check the piston rod for flaw (scratch) and deformation.
- (6) Check the stroke for abnormality.
- (7) Check if the position locking mechanism is securely locked.
- (8) Check for scratches, wear and tear on the position locking mechanism (sleeve, stopper piston, stopper packing, coil spring, etc.)

When a permanent deformation of 1 mm or more is observed on the stopper piston, the stopper piston needs to be replaced.

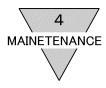
Since this may be caused by a permanent deformation of the sleeve, the sleeve also needs to be checked in this case.



See "Trouble shooting", 5 should there be any trouble found, also carry out additional tightening if bolts, nuts, etc. are slackened.

Since the position locking mechanism is a safety mechanism, disassemble it and check for scratches, wear and tear on it without fail.

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4.2 Disassembly Procedure

1) This cylinder is able to be disassembled.

Replace component parts listed in Expendable parts List by disassembling cylinder referring to internal structure diagram when air leakage is ever occurred.

- (1) Shut off the fluid and remove the residual pressure.
- (2) Disconnect cylinder from piping and load.
- (3) Tuck a cover, either head cover ② or rod cover ⑤, onto a pair of vise.
- (4) Remove the cover by holding the unfixed width across the flats of the cover with a spanner or monkey wrench.

For tools required to remove the cover, see Table 5.

Table 5

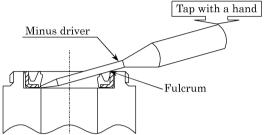
Bore size (mm)	Pair face of cover (mm)			Recommen	ded hand to	ools	
φ 20	24	Spann	ner 24Ac	ljustable w	rench 250 F	Pipe wrench	250
φ 25	29	"	29	"	250	11	350
φ 32	36	11	36	11	375	"	350
φ 40	44			"	375	"	450
φ 50	55					11	600
φ 63	69					"	900
φ 80	80					11	1200
φ 100	100					"	1200

Note · Pipe wrench may sometimes give defects to cover.

- Fairly large torque (350N·m or more) is required for ϕ 80, ϕ 100. Using rigid enough vise to fix the cylinder, also apply a piece of pipe of approx. 1.5monto the handle of spanner, adjustable wrench or pipe wrench to loosen cylinder cover.
- (5) Remove rod packing ③, piston packing ⑨ ④, cylinder gasket ⑩ & wear ring ⑰ using sharp pointed tool such as standard driver or bodkin.



- (6) To replace cushion packing on the cover with cushion which was not disassembled, tuck pair face of the cover onto a pair of vise and loosen the tube by applying pipe wrench to OD of the tube as near to the cover as possible. (Beware that cylinder tube may be scratched by pipe wrench.)
- (7) To remove cushion packing, tuck the pair face of cover with a pair of vise, then ply it out with a minus driver by tapping the handle of screw driver with a hand upon inserting the tip under the loin of packing while making the corner edge of cover a fulcrum.



4.3 Assembly Procedure

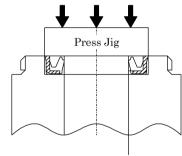
- 1) Clean each component parts.
- 2) Take reversed sequence of disassembly to assemble cylinder after cleaning parts. Carefully avoid giving damage to packings to prevent malfunction or air leakage.
- 3) Assembling cushion packings.
 To prevent a damage to packing also a tilt of it, use a jig and carefully press it in the

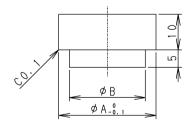
of it, use a jig and carefully press it in the place. Make sure to press it down so as the upper edge of its metal ring sink about 0.5mm below the top surface of the cover.

Table 6 and the illustration is an example of the jig.

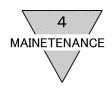
Make it a reference of jig fabrication.

Table 6 Press J	Table 6 Press Jig dimension				
Bore size	A	В			
φ 20	14.5	9.5			
φ 25	17	12			
φ 32	20	14			
φ 40	28	20			
ϕ 50, ϕ 63	32	24			
φ 80, φ 100	45	35			



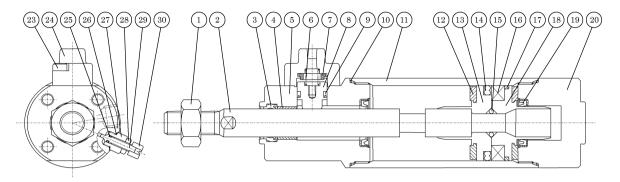


- 4) Apply a film of high grade grease (Litium alkali base) over the inner surface of cylinder tube, outer surface of piston and packings.
- 5) When tightly assembling rod cover and head cover onto tube, make sure, for tight finishing, to turn the cover approx. 2° beyond former position before disassembling. (As for both end angle mounting type, carefully select tight finishing position so as to have both mounting faces of bracket become flat.)

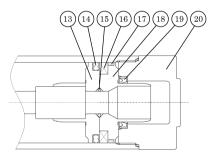


4.4 Internal structure drawings and Expendable parts list

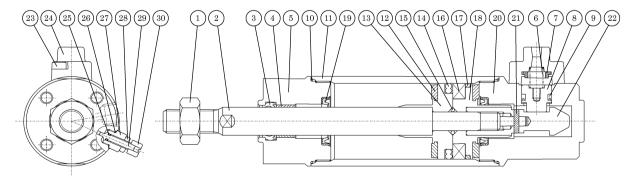
- 1) Double acting, rod side position locking type: Internal structure
 - ϕ 20 to ϕ 40



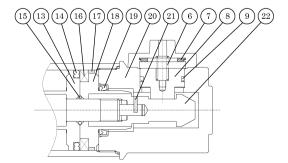
• ϕ 50 to ϕ 100



- 2) Double acting, head side position locking type: Internal structure
 - ϕ 20 to ϕ 40



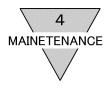
• ϕ 50 to ϕ 100





Part No.	Part Name	Material	Remarks
1	Rod nut	Steel	Nickering
2	Piston rod	ϕ 20 to ϕ 25 :Stainless steel ϕ 32 to ϕ 100 :Steel	Industrial chrome planting
3	Rod packing	Nitrile rubber	
4	Bush	Oil impregnated bearing alloy	
5	Rod cover	Aluminum alloy	Rod side position locking: Black alumite Head side position locking: Black alumite (\$\phi\$ 50 \cdot \phi\$ 63 only painting)
6	Spring	Steel	
7	Cushion rubber (B)	Urethane rubber	
8	Stopper piston	ϕ 20 to ϕ 80: Stainless steel ϕ 100: Steel	
9	Piston seal (B)	Nitrile rubber	
10	Cylinder gasket	Nitrile rubber	
11	Cylinder tube	Aluminum alloy	Hard alumite disposal
12	Cushion rubber (A)	Urethane rubber	
13	Piston R	Aluminum alloy	
14	Piston seal (A)	Nitrile rubber	
15	Piston gasket	Nitrile rubber	
16	Magnet	Plastic	
17	Wear ring	Acetarl resin	
18	Piston H	Aluminum alloy	
19	Cushion packing seal	Nitrile rubber/steel	
20	Head cover	Aluminum alloy	Rod side position locking: Black almite (φ 50 · φ 63 only painting)
			Head side position locking: Black almite
21	Spring pin	Steel	
22	Sleeve	ϕ 20 to ϕ 63:Stainless steel ϕ 80 · ϕ 100:Steel	ϕ 80 · ϕ 100: Industrial chrome planting
23	Hexagon socket head cap screw	Alloy steel	Blackening
24	Stopper cover	Aluminum alloy	
25	Needle gasket	Nitrile rubber	
26	Holder gasket	Nitrile rubber	
27	Needle holder	Aluminum alloy	
28	Lock nut	Steel	Nickering
29	Needle	Stainless steel	
30	Dial	Aluminum alloy	

 $\begin{array}{c} \text{[SM-230478-A]} & -24- \end{array}$



Expendable parts list (Specify the kit No. on your purchase order.)

	Parts No.	3	7	9	10
Bore size (mm)	Parts name Kit No.	Rod packing	Cuchion rubber	Piston seal(B)	Cylinder gasket
φ 20	SCM-Q-20BK	PDU-8Z			O ring φ 20× φ 1.3
φ 25	SCM-Q-25BK	PDU-10Z	F4-659143	MYP-12	O ring φ 24.99× φ 1.27
φ 32	SCM-Q-32BK	PDU-12Z			O ring φ 31.93× φ 1.35
φ 40	SCM-Q-40BK	PDU-16Z			AS568-030
φ 50	SCM-Q-50BK	PDU-20Z			AS568-033
φ 63	SCM-Q-63BK	1 DO 20Z	F4-659049	MYN-22	AS568-037
φ 80	SCM-Q-80BK	PDU-25Z			AS568-042
φ 100	SCM-Q-100BK	PDU-30Z			AS568-155

	Parts No.	12	(4)	17)	19
Bore size (mm)	Parts name Kit No.	Cushion rub- ber(A)	Piston packing	Wear ring	Cushion pack- ing seal
φ 20	SCM-Q-20BK	F4-161693	PSD-20	F4-125610	F4-161817
φ 25	SCM-Q-25BK	F4-161714	PSD-25	F4-161716	F4-161818
φ 32	SCM-Q-32BK	F4-161731	PSD-32	F4-161733	F4-161819
φ 40	SCM-Q-40BK	F4-161747	PSD-40	F4-650239	PCS-20
φ 50	SCM-Q-50BK		PSD-50	F4-650240	PCS-24
φ 63	SCM-Q-63BK	_	PSD-63	F4-650241	FCS-24
φ 80	SCM-Q-80BK	_	PSD-80	F4-650242	F4-436640
φ 100	SCM-Q-100BK		PSD-100	F4-650243	r 4 400040



5. TROUBLE SHOOTING

1) Cylinder

Trouble	Causes	Remedies
D	No pressure or inadequate pressure.	Provide an adequate pressure source.
	Signal is not transmitted to direction control valve.	Correct the control circuit.
Does not operate.	Improper or misalignment of installation.	Correct the installation state and/or change the mounting style.
	Broken piston packing	Replace the piston packing.
	Speed is below the low speed limit	Limit the load variation.
	Improper or misalignment of installation.	Correct the installation state and/or change the mounting style.
Does not function smoothly.	Exertion of transverse (lateral) load.	Install a guide. Revise the installation state and/or change the mounting style.
	Excessive load.	Increase the pressure itself and/or the inner diameter of the tube.
	Speed control valve is built in the way of "Meter in" circuit.	Change the meter-out circuit of the speed control valve.
Breakage and / or deformation	Impact force due to high speed operation	Turn the speed down. Reduce the load and/or install a mechanism with more secured cushion effect (e.g.external cushion mechanism).
deformation	Exertion of transverse load.	Install a guide. Reverse the installation state and/or change the mounting style.

2) Cylinder position locking mechanism

Trouble	Causes	Remedies	
	No operation up to the stroke end.	Operate the cylinder up to the stroke end.	
No locking.	Residual pressure is present inside the cylinder room on the locking mechanism side.	Reduce the residual pressure to zero.	
No lock is released	The external force is applied to the stopper piston.	After pressurizing the cylinder side on the side without position locking unit, actuate the cylinder.	
	No pressure the pressure is insufficient.	Maintain the pressure source.	
	No pressure: the pressure is insufficient.	Maintain the pressure source.	
Does not operate.	Signal is not transmitted to direction control valve.	Correct the control circuit.	
	Broken stopper packing.	Replace the piston packing.	
Daniel Cartin	Excessive load.	Increase the pressure itself and/or the inner diameter of the tube.	
Does not function smoothly.	Speed control valve is built in the way of "Meter in" circuit.	Change the meter-out circuit of the speed control valve.	
	Grease shortage.	Grease is spread.	
D 1 1/	Impact force due to high speed operation	Turn the speed down. Reduce the load and/or install a mechanism with more secured cushion effect (e.g.external cushion mechanism).	
Breakage and / or deformation	Excessive load.	Increase the pressure itself and/or the inner diameter of the tube.	
	Speed control valve is built in the way of "Meter in" circuit.	Change the meter-out circuit of the speed control valve.	
	Bounce on the end of stroke.	Eliminate a bounce on the end of stroke.	

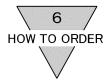
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2) Switch

Troubles	Causes	Remedies	
	Deposited contact point	Replace the switch.	
Indicator light is	Excessive load than rated capacity	Replace the relay with a recommended one or replace the switch.	
not lit.	Damaged indicator light	Replace the switch.	
	Inadequate incoming signal	Review the external signal circuit and remove the causes.	
	Broken circuit	Replace the switch.	
	Inadequate incoming signal	Review the external signal circuit and remove the causes.	
	Improper voltage	Correct voltage to specified.	
	Incorrect location of switch	Correct its location.	
Switch does not function right.	Aberrant position of switch	Set it back to original position and tighten the mounting device.	
	Incorrect direction of switch mounting	Correct the direction of the switch mounting.	
	Relay is unable to respond properly	Turn the speed down. Replace the relay with a recommended one.	
	Excessive load than rated capacity	Replace the relay with a recommended one or replace the switch.	
	Piston is not moving	Make the piston move.	
	Deposited contact point	Replace the switch	
Switch does not	Excessive load (relay) than rated capacity	Replace the relay with a recommended one or replace the switch.	
Switch does not return.	The ambient temperature is out of the specification range	Adjust the ambient temperature within the range of -10 to $60^\circ\!\mathrm{C}$	
	Existence of a foreign magnetic field	Shield the magnetic field.	
	Inadequate incoming signal	Review the external signal circuit and remove the causes.	

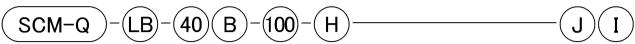
Note 1.Refer "2.4 Location of mounting Switches on a Cylinder" as for replacing a switch and correcting its location.



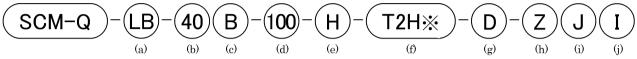
6. HOW TO ORDER

6.1 Product Number Coding

• Without switch



• With switch



Super micro cylinder Position locking type, equipped

(a) Mounting style (Note1)		(b) Bore size (mm)		(c) Cushion	
00	Basic type	20	φ 20	В	With air cushion at both ends
LB	Foot mount type, along axis	25	φ 25	R	With air cushion at rod side
FA	Rod side flange type	32	φ 32	Н	With air cushion at head side
FB	Head end flange type	40	φ 40		
CA	Single clevis type (ϕ 20 to ϕ 63)	50	φ 50		
$^{\mathrm{CB}}$	Double clevis type (ϕ 80 to ϕ 100)	63	φ 63		
TA	Rod side trunnion type (ϕ 20 to ϕ 63)	80	φ 80		
ТВ	Head end trunnion type (ϕ 20 to ϕ 63)	100	φ 100]	

(d) Stroke (mm)	(e) Posi	ition locking mechanism		(f) Switch m	nodel No. (Not	te2)			
25	R	Rod side	side position locking			D 1: 11 1	h		, ,
50	Н	Head sid	side position locking		Axial lead wire	Radial lead wire	Switch type	Indicator light	Lead wire
75					Wife	wire			wire
100					тонж	T0V*	þe	1 color indicator	
125				Т5НЖ	T5V※	Reed	1 color indicator	2 wire	
200					T2H ※	T2V*		1 1	
250		₩ Le	ad wire length		Т3НЖ	T3V※	state	1 color indicator	3 wire
300		Blank	1m(standard)		T2YH※	T2YV*		01 '1'+	0
	•	3	3m(option)		ТЗҮНЖ	T3YV※	Solid	2 color indicator	2 wire
		5	5m(option)		T2JH※	T2JV※	0,2	Off delay type	2 wire

(g) Swi	itch Qty.(Note3, 4)	(h) Switch	mounting method	(i) Op	tion	(j) Acc	essory
R	One on rod side	Blank	Rail method	6	Switch rail attached	I	Rod eye
Н	One on head side	Z	Band method	ષ	at delivery	Y	Rod clevis
D	Two					В1	Eye bracket
Т	Three					DI	(φ 80 to φ 100)
4	4					Do	Clevis bracket
		-				B2	$(\phi 20 \text{ to } \phi 63)$

Note1: Mounting bracket is attached to the product at shipment.

Note3: Specify the number of switches if four or more switches are to be used.

Note4: For details of switch model coding, see the next page.

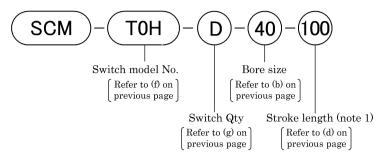
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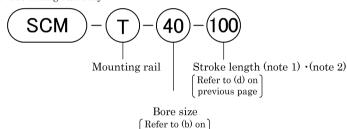
6.2 Component parts Model coding

⟨Switch mounting method : Rail method⟩

• Switch body + Set of mounting rail



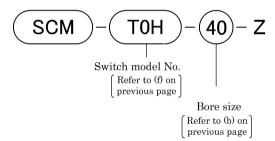
Mounting rail only



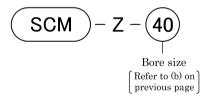
previous page

⟨Switch mounting method : Band method⟩

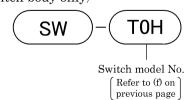
Switch body + mounting rail + Band



Mounting rail + Band



(Switch body only)



Note1:When making an order for a single switch whose stroke is more than 300 mm, enter "X". A short rail (switch's adjustable traveling distance 100 mm) accompanies each switch with a stroke of more than 300mm.

Note2:When making an order only for rails for switches represented by "X", the number of rails must be equivalent to the number of switches to be used.

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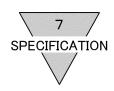
2) Model coding of mounting bracket

Bore size (mm) Mounting bracket	$\phi~20$	$\phi~25$	φ 32	φ 40
End angle type (LB)	SCM-LB-20	SCM-LB-25	SCM-LB-32	SCM-LB-40
Flange type (FA/FB)	SCM-FA-20	SCM-FA-25	SCM-FA-32	SCM-FA-40
Single clevis type (CA)	SCM-CA-20	SCM-CA-25	SCM-CA-32	SCM-CA-40
Double clevis type (CB)	_	_	_	_
Trunnion type (TA/TB)	SCM-TA-20	SCM-TA-25	SCM-TA-32	SCM-TA-40

Bore size (mm) Mounting bracket	φ 50	φ 63	φ 80	φ 100
End angle type (LB)	SCM-LB-50	SCM-LB-63	SCM-LB-80	SCM-LB-100
Flange type (FA/FB)	SCM-FA-50	SCM-FA-63	SCM-FA-80	SCM-FA-100
Single clevis type (CA)	SCM-CA-50	SCM-CA-63	_	_
Double clevis type (CB)	_	_	SCM-CB-80	SCM-CB-100
Trunnion type (TA/TB)	SCM-TA-50	SCM-TA-63	_	_

Note: Required mounting bolts are attached to bracket.

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7. SPECIFICATION

7.1 Product Specifications

Model			SCI	<i>Л</i> -О	
Item		Son Q			
Bore size	mm	φ 20	$\phi 25$	ϕ 32	φ 40
Actuation			Position lo	cking type	
Working fluid			Compre	ssed Air	
Max. working pressu	ure MPa		1.	.0	
Min. working pressu	ire MPa		0.	15	
Proof pressure	MPa		1.	.6	
Ambient temperatur	re °C		-10 to 60 (N	lo freezing)	
Port size		N	1 5	Re	:1/8
Stroke tolerance	mm		$^{+1.4}_{0}$ (less than 1	1000)	$\begin{pmatrix} +1.4 \\ 0 \end{pmatrix}$ (less than 1500)
Working piston spee	d mm/s	30 to 500 (Set th	e speed within the ra	ange of allowable er	nergy absorption.)
Cushion			Air cus	hioned	
Lubrication		Not required (Use	Grade 1 ISO VG 32	Turbine oil, if lubri	cation is preferred)
Position locking med	hanism	Rod side or head side			
Holding force	N	Max. thrust $ imes 0.7$			
Allowable energy	With air cushion	0.8	1.2	2.5	3.7
absorption J	Without cushion	·—·	_	_	_

Model			g C T	M-Q	
Item			501	M-Q	
Bore size	mm	φ 50	φ 63	φ 80	φ 100
Actuation			Position lo	cking type	
Working fluid			Compre	ssed Air	
Max. working press	ure MPa		1	.0	
Min. working pressu	ıre MPa		0	.1	
Proof pressure	MPa	1.6			
Ambient temperatur	re °C		-10 to 60 (N	No freezing)	
Port size		Rc	1/4	Rc3/8	Rc1/2
Stroke tolerance	mm	+ 1.4 0	(less than 1000),	$^{+\ 1.8}_{\ 0}$ (less than	1500)
Working piston spee	ed mm/s	30 to 500 (Set the	e speed within the r	ange of allowable en	ergy absorption.)
Cushion			Air cus	shioned	
Lubrication		Not required (Use	Grade 1 ISO VG 32	Turbine oil, if lubric	cation is preferred)
Position locking med	chanism	Rod side or head side			
Holding force	N	Max. thrust $ imes 0.7$			
Allowable energy	With air cushion	8.0	14.4	25.4	45.6
absorption J	Without cushion	0.057	0.057	0.112	0.153



7.2 Switch Specifications

D	Reed 2 wire					
Descriptions	T0H/V		T5H/V			
Applications	Programmable controller, relay		Programmable controller, re IC circuit (without indicator l series connection			
Power supply voltage		_				
Load Voltage	DC12/24V	AC110V	DC5/12/24V	AC110V		
Load Current	5 to 50mA (Note 2)	7 to 20mA (Note 2)	50mA or less	20mA or less		
Current consumption		_				
Internal voltage drop	2.4V c	or less	0V			
Indicator light	LED (ON	lighting)	Without indicator light			
Leakage current		0m.	A			
Lead wire length (Note1)	Standard 1	lm (Oil resistant vinyl c	abtire cord 2 conducto	or 0.2mm²)		
Shock resistance		294m	n/s ²			
Insulation resistance		$20 \mathrm{M}\Omega$ over at D	C500V megger			
Withstand voltage	No failure impressed at AC1000V for one minute					
Ambient temperature	−10 to 60°C					
Degree of protection	IEC Standards IP67, JIS C0920 (water tight type), oil resistance					
	· 	Solid state	0 :			

Descriptions		Solid state 2 wire				
Descriptions	T2H/V	T2JH/V	T2YH/V			
Applications		Programmable controller				
Power supply voltage		_				
Load Voltage		DC10 to 30V				
Load Current		5 to 20mA (Note 2)				
Current consumption						
Internal voltage drop	4V or less					
Indicator light	LED (ON lighting) Red/green LED (ON lighting)					
Leakage current		1 mA or less				
Lead wire length (Note1)	Standard 1m (Oil resistant vinyl cabtire cord 2 conductor 0.2mm)	Standard 1m (Oil resis conducto	tant vinyl cabtire cord 2 or 0.3mm)			
Shock resistance		$980 \mathrm{m/s^2}$				
Insulation resistance	$\begin{array}{c c} 20 M \Omega \text{over at DC500V} \\ \text{meggeer} \end{array} \qquad \qquad 100 M \Omega \text{over at DC500V megger} \\ \end{array}$					
Withstand voltage	No failure impressed at AC1000V for one minute					
Ambient temperature	-10 to 60℃					
Degree of protection	IEC Standards IP67, JIS C0920 (water tight type), oil resistance					

Descriptions	Solid sta	te 3 wire		
Descriptions	T3H/V	T3YH/V		
Applications	Programmable	controller, relay		
Power supply voltage	DC10	to 28V		
Load Voltage	DC30V	or less		
Load Current	100 mA or less	50mA or less		
Current consumption	10mA or less at DC24V			
Internal voltage drop	0.5V or less			
Indicator light	LED (ON lighting)	Red/green LED (ON lighting)		
Leakage current	$10\mu\mathrm{A}$	or less		
Lead wire length (Note1)	Standard 1m (Oil resistant vinyl	cabtire cord 3 conductor 0.2mm²)		
Shock resistance	9801	m/s^2		
Insulation resistance	$20 \mathrm{M}\Omega$ over at DC500V meggeer	$100 \mathrm{M}\Omega$ over at DC500V megger		
Withstand voltage	No failure impressed at AC1000V for one minute			
Ambient temperature	-10 to 60°C			
Degree of protection	IEC Standards IP67, JIS C0920 (water tight type), oil resistance			

Note 1:3m or 5m long lead wire is optionally available.

Note 2: Max. load current above is value at 25 °C. The current will be lower if the temperature around switch is higher than 25 °C. (50% at 60°C)

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