Actuators breaking free of sliding resistance 0



LCM LCG LCW LCX STM STG STS/STL

STS/STL STR2 UCA2 ULK* JSK/M2 JSG JSC3/JSC4

USSD UFCD USC UB JSB3 LMB

HCM HCA LBC CAC4 UCAC2 CAC-N UCAC-N

UCAC-N RCS2 RCC2 PCC SHC MCP GLC MFC

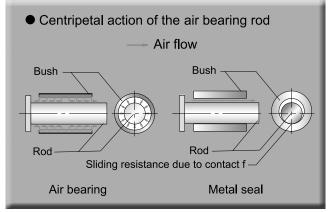
BBS RRC GRC RV3* NHS HRL LN

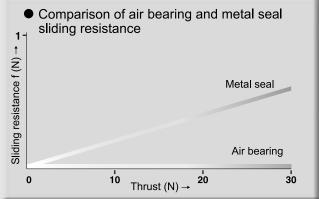
Hand
Chuk
MecHnd/Chuk
ShkAbs
FJ
FK
SpdContr

Minimum control load 0.01 N

Air static pressure type soft actuator LBC Series based on non-contact air bearing mechanism with zero sliding resistance.

The actuator enables sensitive and precise load control when combined with an electro-pneumatic regulator (EV).





Appropriate for clean environments

Non-contact, non-lubricated air driving method without generating dust. The product is appropriate for clean environments.

Soft touch

Due to allowable minimum load control of 0.01 N, a soft touch on the workpiece is possible. The workpiece is not exposed to impact or damaged.

Optimum load for workpiece

The best load according to the purpose and application will be applied to the workpiece.

Excellent response

The rod (moving part) made of light aluminum alloy enables excellent response.

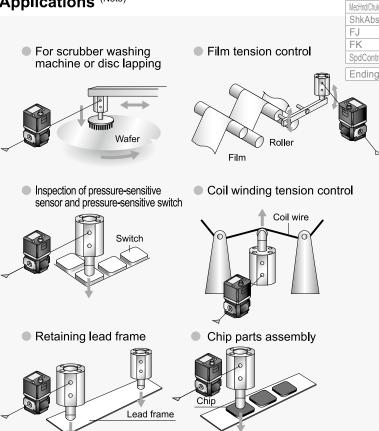
Space-saving & compact

(Note) Rod return mechanism is not provided. If returning the rod is necessary in horizontal or vertical downward applications, combine any other cylinder to return the LBC itself.

High precision linear control

As there is no sliding resistance, high precision linear load control is possible with the electro-pneumatic regulator (EV-FL).

Applications (Note)



997

LCM LCR LCG LCW

I CX STM

STR2

UCA2

JSK/M2

JSC3/JS UFCD UB

JSB3

LMB

LBC

CAC4 UCAC2 CAC-N UCAC-N RCS2

RCC2

SHC

MCP **GLC MFC** BBS

RRC

NHS

HRL LN

Hand

Chuk

I MI **HCM**