



Grippers for collaborative robots Long stroke

RHLF -YS SERIES

With speed controller, cylinder switch
Port size: $\varnothing 4$ push-in fitting



Specifications

Descriptions		RHLF
Bore size	mm	$\varnothing 16 \times 2$
Actuation		Double acting
Working fluid		Compressed air
Max. working pressure	MPa	0.7
Min. working pressure	MPa	0.2
Port size		$\varnothing 4$ push-in fitting
Ambient temperature	$^{\circ}\text{C}$	5 to 50
Operating stroke length	mm	32
Repeatability	mm	± 0.03
Weight	kg	1.0
Display lamp		Blue/green
Cylinder switch		With T2H (Lit when red LED is ON)

Note: When manufacturing the attachment according to the workpiece, refer to page 4.

How to order

RHLF - 16CS - F Y2V - YS

A Robot flange B Accessories YASKAWA Robot
Compatible with HC10DTP Series

Code	Description
A Robot flange	
Blank	Without robot flange
F	With robot flange (*1)
B Accessories	
Blank	No accessories
Y2	Test attachment (*2)
V	Directional control valve/tube (*3)

*1: Robot flange mounting bolts included

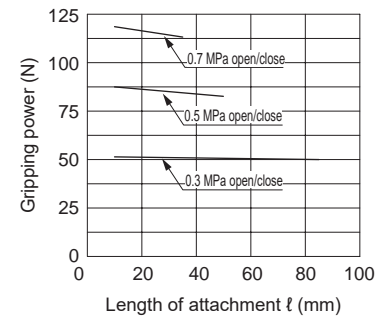
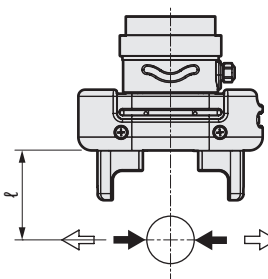
*2: Use it for grip tests as it is made of resin. (Weight: 30 g per piece)

*3: Directional control valves are with $\varnothing 4$ push-in fitting (air supply port, A/B port), silencer (R1/R2 port) and mounting plate. Outer diameter $\varnothing 4$ length 2.5 m x 2 tubes
For details on the directional control valve, refer to the end of this section.

Gripping power performance data

- Gripping power is the thrust (one finger) in the direction of the arrow shown in the figure.
- The gripping force acting in the opening and closing directions of the gripper's attachment length ℓ when the supply pressure is 0.3, 0.5 and 0.7 MPa.

• Open direction (\leftarrow), closed direction (\rightarrow) — (shown with continuous line)



Dimensions

