

# LCX

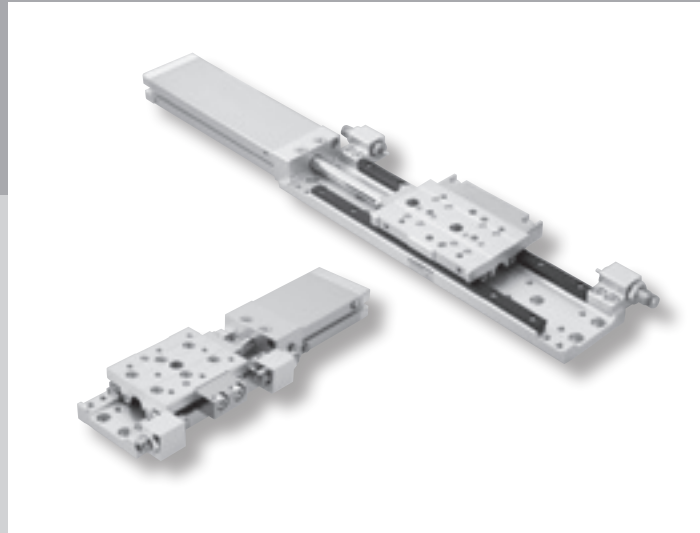
## Linear slide cylinder

ø25/ø32

### Combined functions

#### Overview

Thin, light, rigid linear slide cylinder perfect for narrow space.



### CONTENTS

Product introduction	174
● Double acting/single rod clean room specifications (LCX-P7*)	176
● Double acting/single rod clean room specifications/long stroke (LCX-*L-P7*)	182
Selection guide	188
⚠ Safety precautions	196

SCPD3

SCM

SSD2

MDC2

SMG

LCM

LCR

LCG

**LCX**

STM

STG

STR2

MRL2

GRC

Cylinder  
Switch

MN3E  
MN4E

4GA/B

M4GA/B

MN4GA/B

F.R. (module  
unit)

Clean  
F.R

Precision  
R

Press gauge  
Diff. press gauge

Electro-  
pneumatic R

Speed  
controller

Auxiliary  
valve

Fitting/  
tube

Clean  
air unit

Pressure  
sensor

Flow rate  
sensor

Valve for  
air blow

Ending

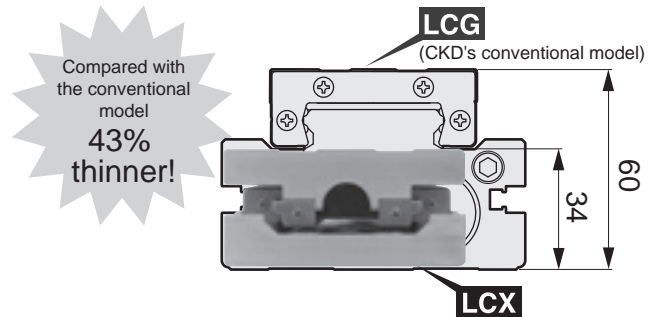
# Thin, light, rigid LCX Series

- SCP3D
- SCM
- SSD2
- MDC2
- SMG
- LCM
- LCR
- LCG
- LCX**
- STM
- STG
- STR2
- MRL2
- GRC
- Cylinder switch
- MN3E  
MN4E
- 4GA/B
- M4GA/B
- MN4GA/B
- F.R (module unit)
- Clean F.R
- Precision R
- Press gauge  
Diff. press gauge
- Electro-pneumatic R
- Speed controller
- Auxiliary valve
- Fitting/tube
- Clean air unit
- Pressure sensor
- Flow rate sensor
- Valve for air blow
- Ending

A wide variety of option variations are available for use in more applications.

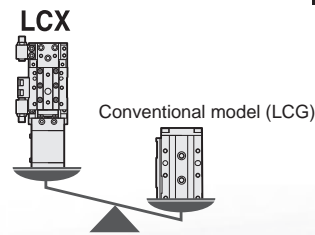
## Thin

About 50% thinner than the conventional model (LCG).  
The height **reduced from 60 mm to 34 mm**.  
The extremely thin body can fit to narrow space.



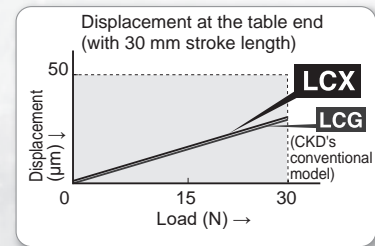
## Lightweight

**50% lighter** than the conventional model (LCG).  
The moving part becomes lighter and thus enables efficient, energy-saving equipment.



## Rigid

The separate linear guide provides **the same level of rigidity as the conventional model (LCG)**, even with the thin and light body.



## A wide range of variations

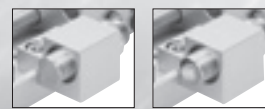
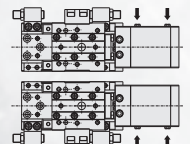
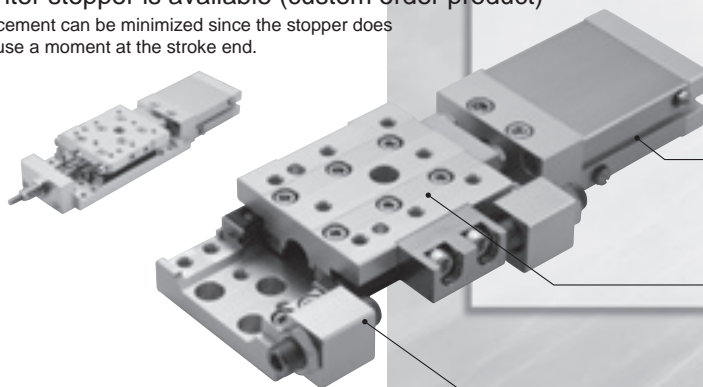
■ A center stopper is available (custom order product)  
Displacement can be minimized since the stopper does not cause a moment at the stroke end.

■ Laterally symmetrical  
Pipes and stoppers can be installed on both the right and left sides.  
← shows the piping direction.

■ Compatible with T switch  
The proximity 2-color display switch is available.

■ Anti-rust  
Anti-rust treated as standard.

■ Different of stoppers



■ Metal stopper    ■ Rubber cushion stopper

# LCX Series

Linear slide cylinder

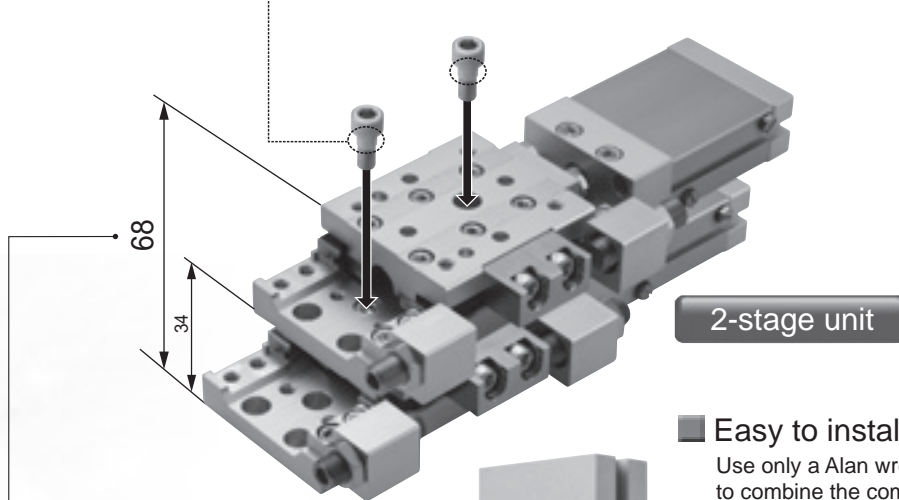
CKD

## Integrated units - simple, secure, high precision

Components can be combined as desired. Select from various options such as the position locking, long stroke (max. 150 mm) and with a positioning hole. Use the integrated units in a wide range of uses including conveyor and positioning so as to improve productivity of multiple products.

### High precision positioning mechanism

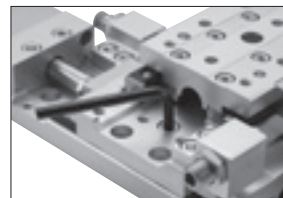
Components can be simply combined with high precision positioning holes and a special bolt for **positioning**. Adjusting the positions is not necessary.



**Only 68 mm even when components are stacked**  
Direct mount without connecting plates enables thin profile design.

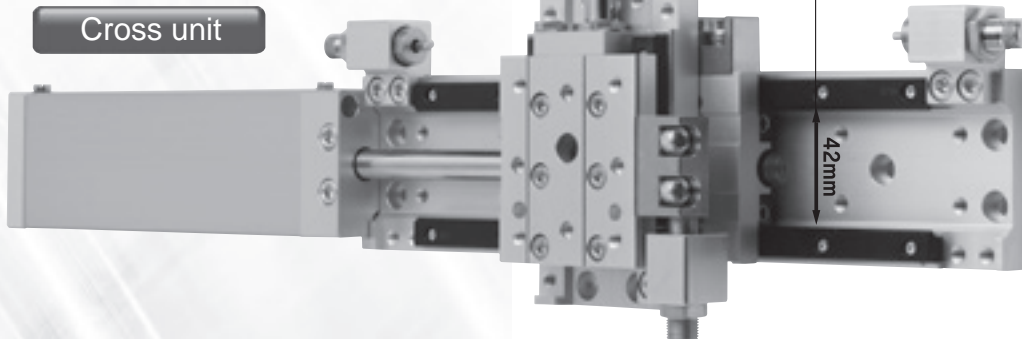
### Easy to install

Use only a Alan wrench to combine the components.



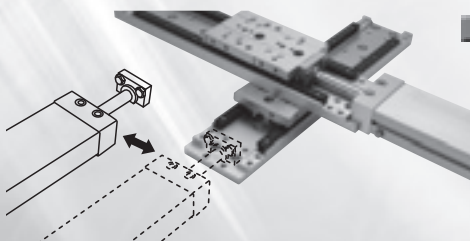
### Rigid, wide guide

42 mm wide rail fits inside.



### Large reduction in maintenance time

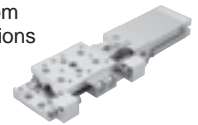
The cylinder can be replaced with the body installed on the equipment.



### LCX product variations

#### LCX-P7\*

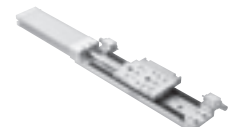
Double acting/single rod  
Clean room specifications



∅ 25, ∅ 32  
Stroke length: 10 to 50 mm

#### LCX-\*L-P7\*

Double acting/single rod  
clean room specifications  
Long stroke

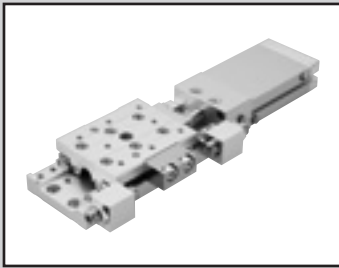


∅ 25, ∅ 32  
Stroke length: 75 to 150 mm

\* The picture shows the standard product.

SCPD3
SCM
SSD2
MDC2
SMG
LCM
LCR
LCG
<b>LCX</b>
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Cylinder Switch
MN3E MN4E
4GA/B
M4GA/B
MN4GA/B
F.R. (module unit)
Clean F.R
Precision R
Press gauge Diff. press gauge
Electro-pneumatic R
Speed controller
Auxiliary valve
Fitting/tube
Clean air unit
Pressure sensor
Flow rate sensor
Valve for air blow
Ending

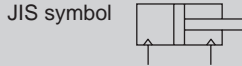
SCPD3  
SCM  
SSD2  
MDC2  
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Clean air unit  
Pressure sensor  
Flow rate sensor  
Valve for air blow  
Ending



Linear slide cylinder Double acting/single rod clean room specifications

# LCX Series

● Bore size:  $\phi 25/\phi 32$



## Specifications

Descriptions		LCX-P7*	
Bore size	mm	$\phi 25$	$\phi 32$
Actuation		Double acting	
Working fluid		Compressed air	
Max. working pressure	MPa	0.7	
Min. working pressure	MPa	0.15	
Proof pressure	MPa	1.05	
Ambient temperature	°C	-10 to 60 (no freezing) (*1)	
Port size		M5	
Port size (relief port)		M5	
Stroke tolerance	mm	+2.0 0 (*2)	
Working piston speed	mm/s	20 to 500	
Cushion		With rubber cushion	
Lubrication		Not available	
Allowable energy absorption	J	Refer to table 3 on page 189.	

## Structure and material restriction

	Structure	Model No.
P7 Series	Exhaust treatment	<b>P72</b>
	Vacuum treatment	<b>P73</b>

## Stroke length

Bore size (mm)	Standard stroke length (mm)
$\phi 25$	10, 20, 30, 40, 50
$\phi 32$	10, 20, 30, 40, 50

Note: Stroke lengths other than above are not available.

- \*1: Contact CKD if the use environment is always cold (5°C or less) or hot (40°C and over).  
\*2: Note that there will be a slight gap between the end plate and floating bush if no stopper is attached.  
\*3: Keep within 20 to 200 mm/s when using a metal stopper.

## Theoretical thrust table

Refer to page 188.

## Switch specifications

● 1-color/2-color display

Descriptions	Reed 2-wire				Proximity 2-wire		Proximity 3-wire		
	T0H/T0V		T5H/T5V		T2H/T2V	T2WH/T2WV	T3H/T3V	T3PH/T3PV	T3WH/T3WV
Applications	Programmable controller, relay		Programmable controller, relay IC circuit (without indicator lamp), serial connection		Programmable controller		Programmable controller, relay		
Output method	-		-		-		NPN output	PNP output	NPN output
Power supply voltage	-		-		-		10 to 28 VDC		
Load voltage	12/24 VDC	110 VAC	5/12/24 VDC	110 VAC	10 to 30 VDC	24 VDC $\pm$ 10%	30 VDC or less		
Load current	5 to 50 mA	7 to 20 mA	50 mA or less	20 mA or less	5 to 20 mA (*2)		100 mA or less		50 mA or less
Indicator lamp	LED (Lit when ON)		Without indicator lamp		LED (Lit when ON)	Red/green LED (Lit when ON)	LED (Lit when ON)	Yellow LED (Lit when ON)	Red/green LED (Lit when ON)
Leakage current	0 mA				1 mA or less		10 $\mu$ A or less		
Weight	g 1 m: 18 3 m: 49 5 m: 80				g 1 m: 18 3 m: 49 5 m: 80		g 1 m: 18 3 m: 49 5 m: 80		

- \*1: Refer to page 309 for detailed switch specifications and dimensions.  
\*2: The maximum load current of 20 mA is for 25°C. The current will be lower than 20 mA when operating ambient temperature around the switch is higher than 25°C. (5 to 10 mA at 60°C)

## Cylinder weight

● Clean room specifications

(Unit: g)

Bore size (mm)	Basic Stroke length (mm)				
	10	20	30	40	50
$\phi 25$	1,010	1,040	1,060	1,180	1,200
$\phi 32$	1,060	1,090	1,110	1,240	1,260

● Weight of variation/option (stopper)

(Unit: g)

Bore size (mm)	Option/stopper code			
	S1 to S4	M1 to M4	S5/S6	M5/M6
$\phi 25$	170		240	
$\phi 32$	170		240	

## How to order

Without switch (Magnet for switch incorporated)



With switch (Magnet for switch incorporated)



Model No.

A Bore size

B Stroke length

F Option

G Clean room specifications

C Switch model No.  
\*7

D Switch quantity

E Stopper

### ⚠ Precautions for model No. selection

- \*1: To change the adjustable stroke length, use a discrete rubber cushion stopper or metal stopper on page 178.
- \*2: Can be selected for the type with stopper only.
- \*3: The alloy steel stopper block (code: T) is recommended for a metal stopper.
- \*4: Combination of the rubber cushion stopper and metal stopper is custom order.
- \*5: Keep within 20 to 200 mm/s when using a metal stopper.
- \*6: Refer to page 179 for a discrete cylinder model No.
- \*7: Be careful of the lead wire direction when designing the 30 mm or less stroke length of axial lead wire and the 20 mm stroke length of radial lead wire since a switch is installed in each groove of the body.

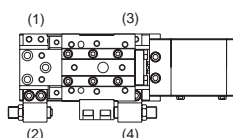
### [Example of model No.]

#### LCX-25-40-T2H-R-S1TEP72

Model No.: Linear slide cylinder Double acting/  
single rod (clean room specifications) LCX-P7\*

- A Bore size :  $\phi 25$
- B Stroke length : 40 mm
- C Switch model No.: Proximity/2 wires/Lead wire 1 m  
Lead wire straight
- D Switch quantity : 1 (on rod end)
- E Stopper : Rubber cushion stopper  
Stopper position (1)  
Material, alloy steel (nitriding)
- F Option : With positioning hole
- G Clean room specifications : Exhaust treatment

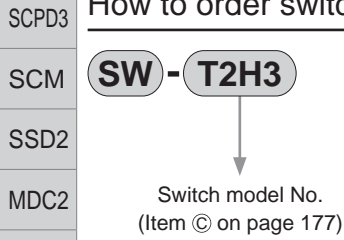
● Stopper position



Code	Content					
<b>A Bore Code size</b>						
25	$\phi 25$					
32	$\phi 32$					
<b>B Stroke length (mm)</b>						
10	10					
20	20					
30	30					
40	40					
50	50					
<b>C Switch model No.</b>						
Lead wire straight	Lead wire L-shaped	Contact	Voltage		Display	Lead wire
			AC	DC		
T0H*	T0V*	Reed	●	●	1-color display Without indicator lamp	2 wires
T5H*	T5V*		●	●		
T2H*	T2V*	Proximity		●	1-color display	2 wires
T3H*	T3V*			●		3 wires
T3PH*	T3PV*			●	1-color display (PNP output)	3 wires
T2WH*	T2WV*			●	2-color display	2 wires
T3WH*	T3WV*			●		3 wires
<b>* Lead wire length</b>						
Blank	1 m (standard)					
3	3 m (option)					
5	5 m (option)					
<b>D Switch quantity</b>						
R	1 (on rod end)					
H	1 (on head end)					
D	2					
<b>E Stopper</b>						
Blank	Without stopper					
<b>S Cushion cushion stopper</b>			<b>*1, *4</b>			
S1*	Stopper position (1) (can be changed to (4))				Stopper mounting position	
S2*	Stopper position (2) (can be changed to (3))					
S3*	Stopper position (3) (can be changed to (2))					
S4*	Stopper position (4) (can be changed to (1))					
S5*	Stopper position (1), (3)					
S6*	Stopper position (2), (4)					
<b>M Metal stopper</b>			<b>*1, *3, *4, *5</b>			
M1*	Stopper position (1) (can be changed to (4))				Stopper mounting position	
M2*	Stopper position (2) (can be changed to (3))					
M3*	Stopper position (3) (can be changed to (2))					
M4*	Stopper position (4) (can be changed to (1))					
M5*	Stopper position (1), (3)					
M6*	Stopper position (2), (4)					
<b>* Part</b>						
Blank	Stopper block material: Rolled steel					
T	Stopper block material: Alloy steel (nitriding)		<b>*2</b>			
<b>F Option</b>						
Blank	No option					
E	With positioning hole					
<b>G Clean room specifications</b>						
			Structure			
P72	Exhaust treatment					
P73	Vacuum treatment					

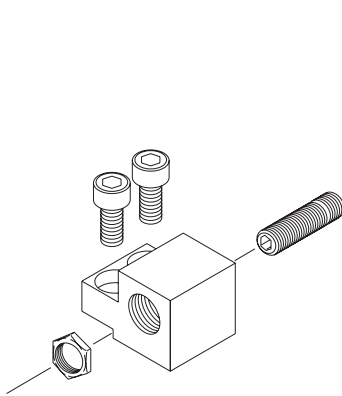
SCPD3
SCM
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<b>LCX</b>
STM
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MRL2
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MN4GA/B
F.R.(module unit)
Clean F.R
Precision R
Press gauge
Diff. press gauge
Electro-pneumatic R
Speed controller
Auxiliary valve
Fitting/tube
Clean air unit
Pressure sensor
Flow rate sensor
Valve for air blow
Ending

## How to order switch



## How to order a stopper set

- A set of a stopper and rubber cushion stopper or metal stopper
- Use this when changing from the standard to the with rubber cushion stopper or metal stopper



**LCX - 25 - S 2 - S02**

Bore size  
(Item ① on page 177)

A Stopper	
<b>S</b>	Cushion stopper
<b>M</b>	Metal stopper

B Stopper mounting position	
<b>1</b>	Stopper position (1) or for (4)
<b>2</b>	Stopper position (2) or for (3)

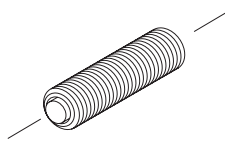
C Stroke adjusting amount	
<b>Blank</b>	Adjustable stroke range 10 mm
<b>S02</b>	Adjustable stroke range 20 mm

(Unit: g)

Model No.				Weight
<b>LCX</b>	25	S1	Blank	70
		S2	S02	80
	32	M1	Blank	70
		M2	S02	80

## How to order discrete rubber cushion stopper

- Hexagon socket set screw with urethane
- Use this when changing the adjustable stroke range or when using custom stroke length



**LCX - 25 - S02**

Bore size  
(Item ① on page 177)

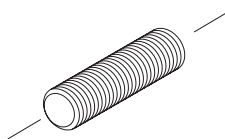
A Adjustable stroke range	
<b>S01</b>	Single side 10 mm (standard)
<b>S02</b>	Single side 20 mm

(Unit: g)

Model No.			Weight
<b>LCX</b>	25	S01	30
	32	S02	40

## How to order discrete metal stopper

- Use when changing the adjustable stroke range or when using a custom stroke length



**LCX - 25 - M02**

Bore size  
(Item ① on page 177)

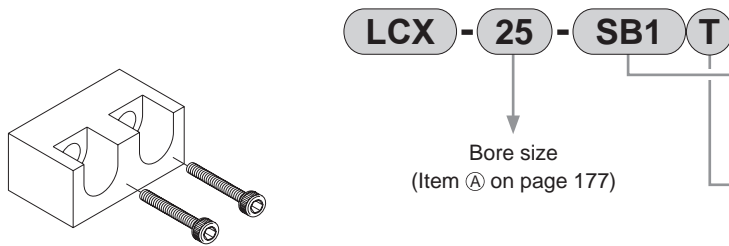
A Adjustable stroke range	
<b>M01</b>	Single side 10 mm (standard)
<b>M02</b>	Single side 20 mm

(Unit: g)

Model No.			Weight
<b>LCX</b>	25	M01	30
	32	M02	40

## How to order discrete stopper block

- Use this when changing from the standard to the with rubber cushion stopper or metal stopper



Bore size  
(Item ① on page 177)

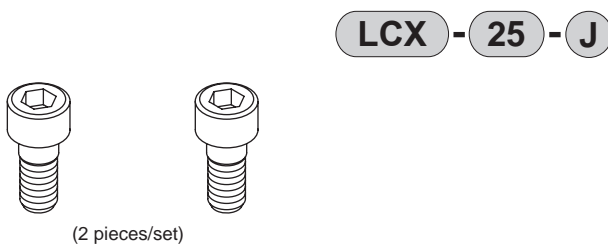
A Stopper block	
SB1	For 30, 50 mm stroke length
SB2	For 10, 20, 40 mm stroke length
B Material	
Blank	Stopper block material: Rolled steel
T	Stopper block material: steel (nitriding)

(Unit: g)

	Model No.		Weight
LCX	25	SB1 (T)	80
	32	SB2 (T)	100

## How to order positioning bolt

- A hexagon socket head cap screw for positioning
- Enables assembling of the crossed unit and two-stage unit without adjusting the position

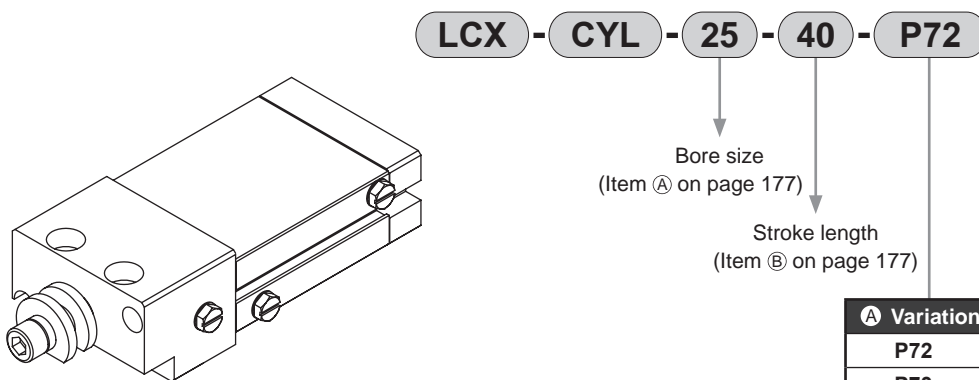


(Unit: g)

	Model No.		Weight
LCX	25	J	10

\* Weight per set (2 pieces)

## How to order discrete cylinder



Bore size  
(Item ① on page 177)

Stroke length  
(Item ② on page 177)

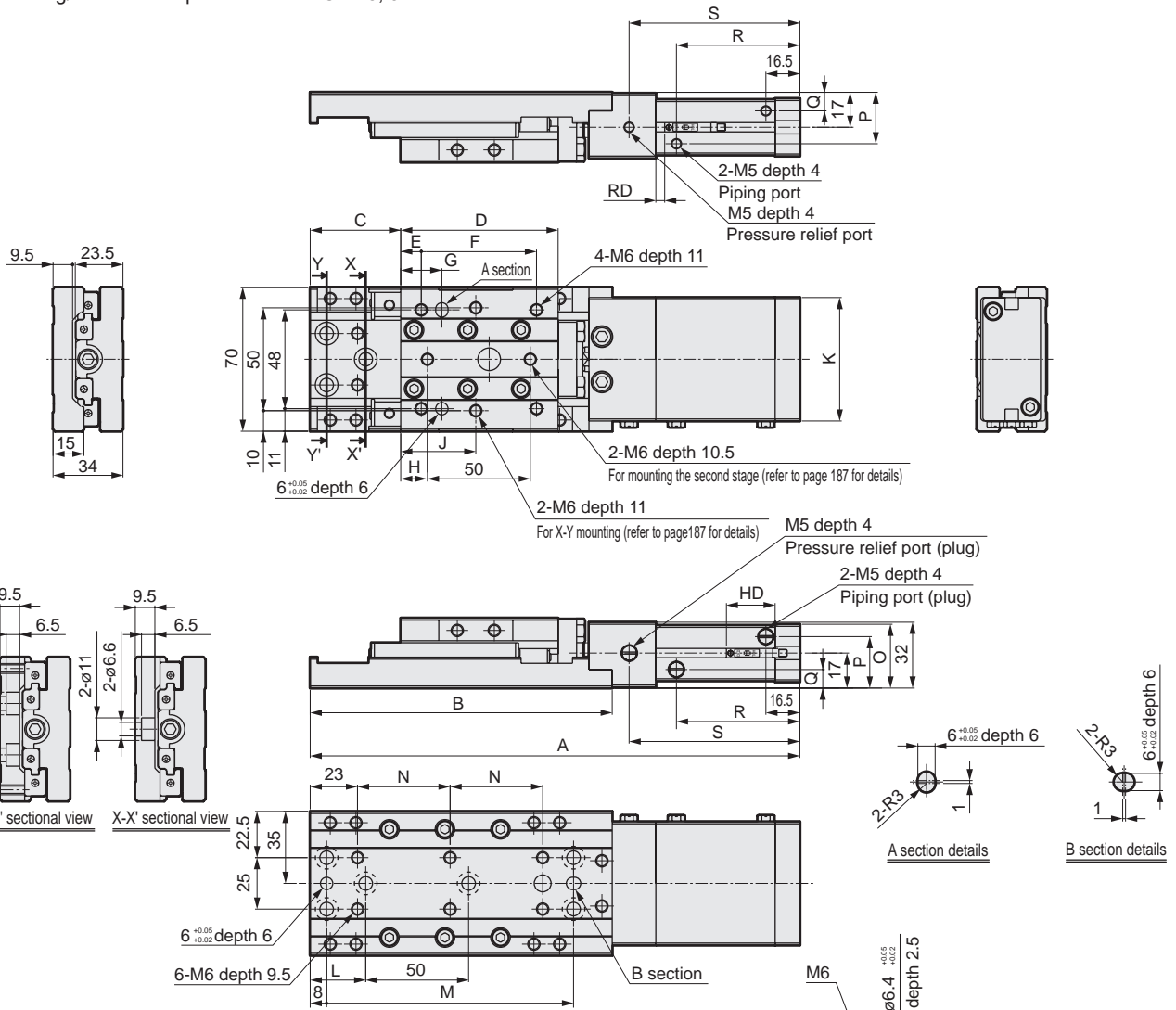
A Variation	
P72	Clean room specifications (exhaust treatment)
P73	Clean room specifications (vacuum treatment)

- SCPD3
- SCM
- SSD2
- MDC2
- SMG
- LCM
- LCR
- LCG
- LCX**
- STM
- STG
- STR2
- MRL2
- GRC
- Cylinder Switch
- MN3E  
MN4E
- 4GA/B
- M4GA/B
- MN4GA/B
- F.R. (module unit)
- Clean F.R
- Precision R
- Press gauge  
Diff. press gauge
- Electro-pneumatic R
- Speed controller
- Auxiliary valve
- Fitting/tube
- Clean air unit
- Pressure sensor
- Flow rate sensor
- Valve for air blow
- Ending

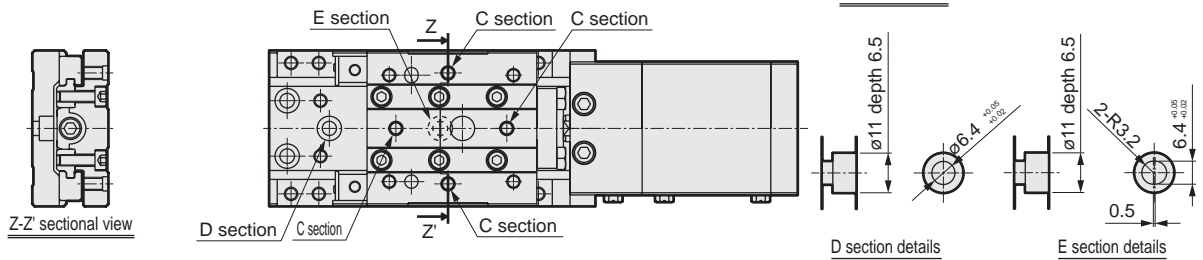
## Dimensions



● Double acting/clean room specifications LCX-25, 32-P7\*



● With positioning hole LCX-25, 32-EP7\*



Bore size	Stroke length	A	B	C	D	E	F	G	H	J	K	L	M	N	O	P	Q	R	S	RD			HD		
																				T0*	T2*	T2W*	T0*	T2*	T2W*
																				T5*	T3*	T3W*	T5*	T3*	T3W*
ø25	10	218		34														40	63						
	20	228	147	39	76.5	10	56	20	13	36.5		27	120	45				50	73						
	30	238		44													29.5	24.5	60	83					
	40	268		49	86.5	15	64	30	23	46.5		41	140	55				70	93						
	50	278	167	54														80	103						
ø32	10	218		34														40	63	5	6.5	23.5	21.5		
	20	228	147	39	76.5	10	56	20	13	36.5		27	120	45				50	73						
	30	238		44														60	83						
	40	268		49	86.5	15	64	30	23	46.5		41	140	55			31	25	70	93					
	50	278	167	54														80	103						

SCPD3

SCM

SSD2

MDC2

SMG

LCM

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**LCX**

STM

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GRC

Cylinder  
Switch

MN3E  
MN4E

4GA/B

M4GA/B

MN4GA/B

F.R. (module  
unit)

Clean  
F.R

Precision  
R

Press gauge  
Diff. press gauge

Electro-  
pneumatic R

Speed  
controller

Auxiliary  
valve

Fitting/  
tube

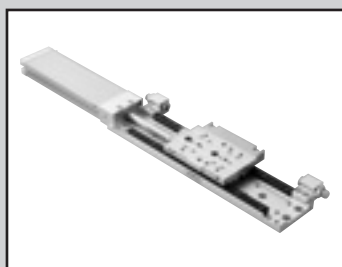
Clean  
air unit

Pressure  
sensor

Flow rate  
sensor

Valve for  
air blow

Ending



Linear slide cylinder double acting/single rod clean room specifications/long stroke length

# LCX-\*L Series

● Bore size:  $\phi 25/\phi 32$



## Specifications

Descriptions	LCX-*L-P7*	
Bore size mm	$\phi 25$	$\phi 32$
Actuation	Double acting	
Working fluid	Compressed air	
Max. working pressure MPa	0.7	
Min. working pressure MPa	0.15	
Proof pressure MPa	1.05	
Ambient temperature °C	-10 to 60 (no freezing) (*1)	
Port size	M5	
Port size (relief port)	M5	
Stroke tolerance mm	+2.0 0 (*2)	
Working piston speed mm/s	20 to 500	
Cushion	With rubber cushion	
Lubrication	Not available	
Allowable energy absorption J	Refer to table 3 on page 189.	

## Structure and material restriction

	Structure	Model No.
P7 Series	Exhaust treatment	<b>P72</b>
	Vacuum treatment	<b>P73</b>

## Stroke length

Bore size (mm)	Standard stroke length (mm)
$\phi 25$	75, 100, 125, 150
$\phi 32$	75, 100, 125, 150

Note: The stroke length other than above is not available.

\*1: Contact CKD if the use environment is always cold (5°C or less) or hot (40°C and over).

\*2: Note that there will be a slight gap between the end plate and floating bush if no stopper is attached.

\*3: Keep within 20 to 200 mm/s when using a metal stopper.

## Theoretical thrust table

Refer to page 188.

## Switch specifications

● 1-color/2-color display

Descriptions	Reed 2-wire				Proximity 2-wire		Proximity 3-wire		
	T0H/T0V		T5H/T5V		T2H/T2V	T2WH/T2WV	T3H/T3V	T3PH/T3PV	T3WH/T3WV
Applications	Programmable controller, relay		Programmable controller, relay IC circuit (without indicator lamp), serial connection		Programmable controller		Programmable controller, relay		
Output method	-		-		-		NPN output	PNP output	NPN output
Power supply voltage	-		-		-		10 to 28 VDC		
Load voltage	12/24 VDC	110 VAC	5/12/24 VDC	110 VAC	10 to 30 VDC	24 VDC $\pm 10\%$	30 VDC or less		
Load current	5 to 50 mA	7 to 20 mA	50 mA or less	20 mA or less	5 to 20 mA (*2)		100 mA or less		50 mA or less
Indicator lamp	LED (Lit when ON)		Without indicator lamp		LED (Lit when ON)	Red/green LED (Lit when ON)	LED (Lit when ON)	Yellow LED (Lit when ON)	Red/green LED (Lit when ON)
Leakage current	0 mA				1 mA or less		10 $\mu$ A or less		
Weight g	1 m: 18 3 m: 49 5 m: 80				1 m: 18 3 m: 49 5 m: 80		1 m: 18 3 m: 49 5 m: 80		

\*1: Refer to page 309 for detailed switch specifications and dimensions.

\*2: The maximum load current of 20 mA is for 25°C. The current will be lower than 20 mA when operating ambient temperature around the switch is higher than 25°C. (5 to 10 mA at 60°C)

## Cylinder weight

● Clean room specifications

(Unit: g)

Bore size (mm)	Basic Stroke length (mm)			
	75	100	125	150
$\phi 25$	1,530	1,670	1,820	1,960
$\phi 32$	1,660	1,810	1,960	2,110

● Weight of variation/option (stopper)

(Unit: g)

Bore size (mm)	Option/stopper code			
	S1 to S4	M1 to M4	S5/S6	M5/M6
$\phi 25$	320		400	
$\phi 32$	320		400	

### How to order

Without switch (Magnet for switch incorporated)



With switch (Magnet for switch incorporated)



Model No.

A Bore size

B Stroke length

C Switch model No.  
\*8

D Switch quantity

E Stopper

F Clean room specifications

### ⚠ Precautions for model No. selection

- \*1: To change the adjustable stroke length, use a discrete rubber cushion stopper or metal stopper on page 184.
- \*2: Can be selected for the type with stopper only.
- \*3: The alloy steel stopper block (code: T) is recommended for a metal stopper.
- \*4: Combination of the rubber cushion stopper and metal stopper is custom order.
- \*5: Keep within 20 to 200 mm/s when using a metal stopper.
- \*6: Refer to page 185 for a discrete cylinder model No.
- \*7: The long stroke length has a positioning hole as standard.
- \*8: Be careful of the lead wire direction when designing the 30 mm or less stroke length of axial lead wire and the 20 mm stroke length of radial lead wire since a switch is installed in each groove of the body.

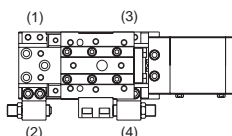
[Example of model No.]

### LCX-25L-100-T2H-R-S1TP72

Model No.: Linear slide cylinder Double acting/ single rod (clean room specifications) LCX-P7\*

- A Bore size :  $\phi 25$
- B Stroke length : 100 mm
- C Switch model No. : Proximity/2 wires/  
Lead wire 1 m  
Lead wire straight
- D Switch quantity : 1 (on rod end)
- E Other options : Rubber cushion stopper  
Stopper position (1)  
Material, alloy steel (nitriding)
- F Clean room specifications : Exhaust treatment

● Stopper position



Code	Content						
<b>A Bore size</b>							
25	$\phi 25$						
32	$\phi 32$						
<b>B Stroke length (mm)</b>							
75	75						
100	100						
125	125						
150	150						
<b>C Switch model No.</b>							
Lead wire straight	Lead wire L-shaped	Contact	Voltage		Display	Lead wire	
			AC	DC			
T0H*	T0V*	Reed	●	●	1-color display Without indicator lamp	2 wires	
T5H*	T5V*		●	●			
T2H*	T2V*		Proximity		●	1-color display	2 wires
T3H*	T3V*				●		
T3PH*	T3PV*					1-color display (PNP output)	3 wires
T2WH*	T2WV*			●	2-color display	2 wires	
T3WH*	T3WV*			●		3 wires	
<b>* Lead wire length</b>							
Blank	1 m (standard)						
3	3 m (option)						
5	5 m (option)						
<b>D Switch quantity</b>							
R	1 (on rod end)						
H	1 (on head end)						
D	2						
<b>E Stopper</b>							
Blank	Without stopper						
<b>S Cushion cushion stopper</b> *1, *4							
S1*	Stopper position (1) (can be changed to (4))					Stopper mounting position	
S2*	Stopper position (2) (can be changed to (3))						
S3*	Stopper position (3) (can be changed to (2))						
S4*	Stopper position (4) (can be changed to (1))						
S5*	Stopper position (1), (3)						
S6*	Stopper position (2), (4)						
<b>M Metal stopper</b> *1, *3, *4, *5							
M1*	Stopper position (1) (can be changed to (4))					Stopper mounting position	
M2*	Stopper position (2) (can be changed to (3))						
M3*	Stopper position (3) (can be changed to (2))						
M4*	Stopper position (4) (can be changed to (1))						
M5*	Stopper position (1), (3)						
M6*	Stopper position (2), (4)						
<b>* Part</b>							
Blank	Stopper block material: Rolled steel						
T	Stopper block material: Alloy steel (nitriding) *2						
<b>F Clean room specifications</b>							
Structure							
P72	Exhaust treatment						
P73	Vacuum treatment						

SCPD3
SCM
SSD2
MDC2
SMG
LCM
LCR
LCG
<b>LCX</b>
STM
STG
STR2
MRL2
GRC
Cylinder Switch
MN3E
MN4E
4GA/B
M4GA/B
MN4GA/B
F.R. (module unit)
Clean F.R
Precision R
Press gauge
Diff. press gauge
Electro-pneumatic R
Speed controller
Auxiliary valve
Fitting/ tube
Clean air unit
Pressure sensor
Flow rate sensor
Valve for air blow
Ending

## How to order switch

- SCPD3
- SCM
- SSD2
- MDC2
- SMG
- LCM
- LCR
- LCG
- LCX**
- STM
- STG
- STR2
- MRL2
- GRC
- Cylinder switch
- MN3E  
MN4E
- 4GA/B
- M4GA/B
- MN4GA/B
- F.R (module unit)
- Clean F.R
- Precision R
- Press gauge  
Diff. press gauge
- Electro-pneumatic R
- Speed controller
- Auxiliary valve
- Fitting/tube
- Clean air unit
- Pressure sensor
- Flow rate sensor
- Valve for air blow
- Ending

**SW - T2H3**

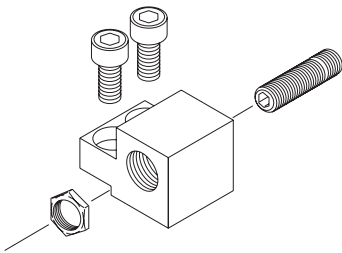
Switch model No.  
(Item © on page 183)

## How to order a stopper set

- A set of a stopper and rubber cushion stopper or metal stopper
- Use this when changing from the standard to the with rubber cushion stopper or metal stopper

**LCX - 25 - S 2 - S02**

Bore size  
(Item ① on page 183)



A Stopper	
<b>S</b>	Cushion stopper
<b>M</b>	Metal stopper
B Stopper mounting position	
<b>1</b>	Stopper position (1) or for (4)
<b>2</b>	Stopper position (2) or for (3)
C Stroke adjusting amount (*1)	
<b>Blank</b>	Adjustable stroke range 10 mm
<b>S02</b>	Adjustable stroke range 20 mm

(Unit: g)

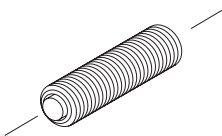
Model No.			Weight	
<b>LCX</b>	25	S1	Blank	70
		S2	S02	80
	32	M1	Blank	70
		M2	S02	80

## How to order discrete rubber cushion stopper

- Hexagon socket set screw with urethane
- Use it when changing the adjustable stroke range or when using custom stroke length

**LCX - 25 - S02**

Bore size  
(Item ① on page 183)



A Adjustable stroke range	
<b>S01</b>	Single side 10 mm (standard)
<b>S02</b>	Single side 20 mm

(Unit: g)

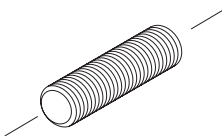
Model No.			Weight
<b>LCX</b>	25	S01	30
	32	S02	40

## How to order discrete metal stopper

- Use this when changing the adjustable stroke range or when using custom stroke length

**LCX - 25 - M02**

Bore size  
(Item ① on page 183)



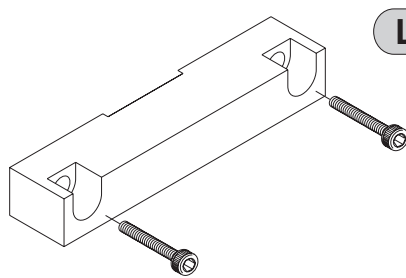
A Adjustable stroke range	
<b>M01</b>	Single side 10 mm (standard)
<b>M02</b>	Single side 20 mm

(Unit: g)

Model No.			Weight
<b>LCX</b>	25	M01	30
	32	M02	40

### How to order discrete stopper block

- Use it when changing from the standard to the with rubber cushion stopper or metal stopper



**LCX - 25 L - SB3 T**

Bore size  
(Item ① on page 183)

① Material	
Blank	Stopper block material: Rolled steel
T	Stopper block material: Alloy steel (nitriding)

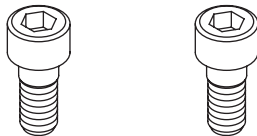
(Unit: g)

LCX	Model No.		Weight
	25L 32L	SB3 (T)	
			250

### How to order positioning bolt

- A hexagon socket head cap screw for positioning
- Enables assembling of the crossed unit and two-stage unit without adjusting the position

**LCX - 25 - J**



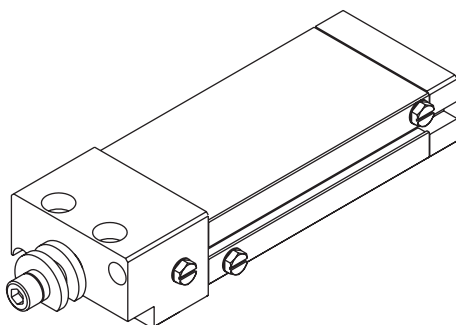
(2 pieces/set)

(Unit: g)

LCX	Model No.		Weight
	25	J	
			10

\* Weight per set (2 pieces)

### How to order discrete cylinder



**LCX - CYL - 25 L - 100 - P72**

Bore size  
(Item ① on page 183)

Stroke length  
(Item ② on page 183)

① Variation	
P72	Clean room specifications (exhaust treatment)
P73	Clean room specifications (vacuum treatment)

SCPD3

SCM

SSD2

MDC2

SMG

LCM

LCR

LCG

**LCX**

STM

STG

STR2

MRL2

GRC

Cylinder  
Switch

MN3E  
MN4E

4GA/B

M4GA/B

MN4GA/B

F.R. (module  
unit)

Clean  
F.R

Precision  
R

Press gauge  
Diff. press gauge

Electro-  
pneumatic R

Speed  
controller

Auxiliary  
valve

Fitting/  
tube

Clean  
air unit

Pressure  
sensor

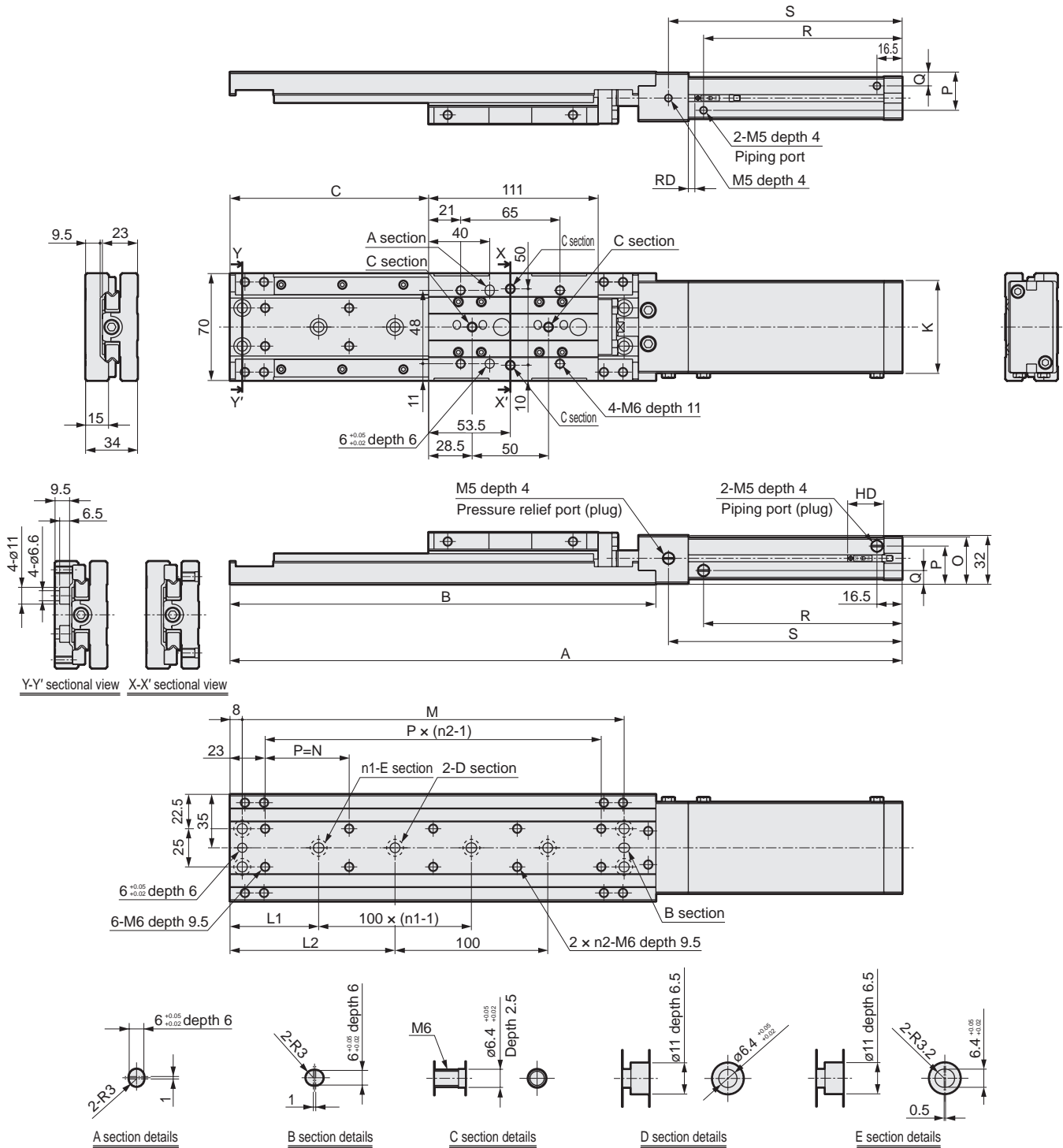
Flow rate  
sensor

Valve for  
air blow

Ending

## Dimensions

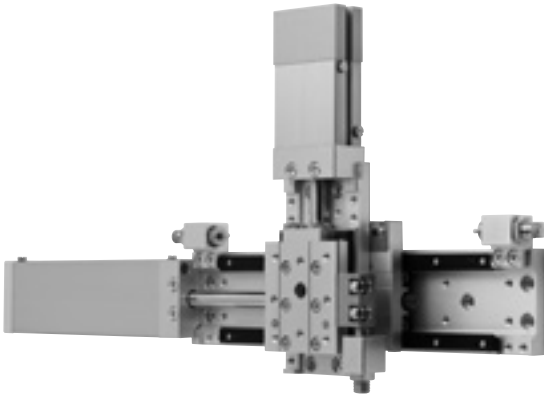
● Double acting/single rod clean room specifications/long stroke length LCX-\*L-P7\*



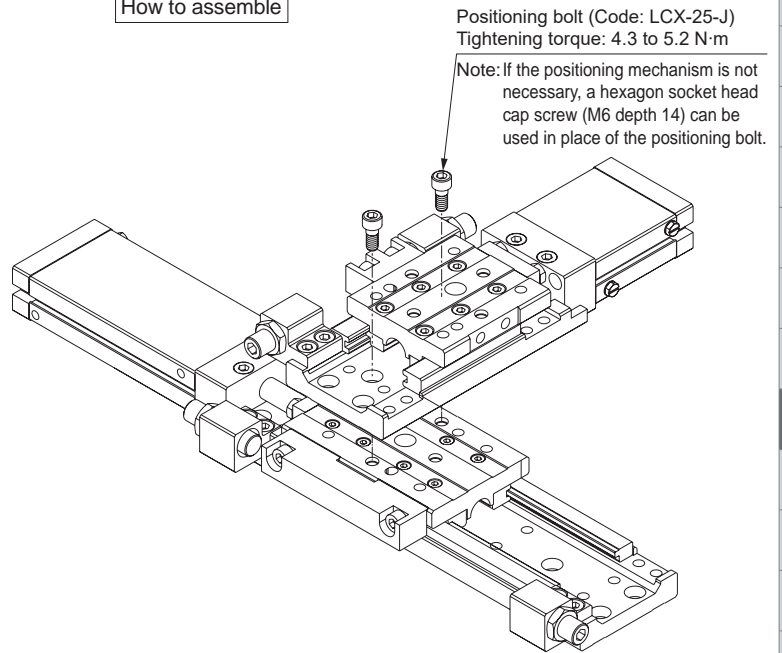
Bore size	Stroke length	A	B	C	K	L1	L2	n1	n2	M	N	O	P	Q	R	S	RD			HD				
																	T0*	T2*	T2W*	T0*	T2*	T2W*		
																	T5*	T3*	T3W*	T5*	T3*	T3W*		
ø25	75	390	254	105	50	45.5	95.5	2	5	225	49	29.5	24.5	9.5	105	128	5	6.5	23.5	21.5				
	100	440	279	130		58	108	2	5	250	55												130	153
	125	490	304	155		45.5	95.5	3	6	275	49												155	178
	150	540	329	180		58	108	3	6	300	54												180	203
ø32	75	390	254	105	60	45.5	95.5	2	5	225	49	31	25	9	105	128	5	6.5	23.5	21.5				
	100	440	279	130		58	108	2	5	250	55												130	153
	125	490	304	155		45.5	95.5	3	6	275	49												155	178
	150	540	329	180		58	108	3	6	300	54												180	203

## Unit example

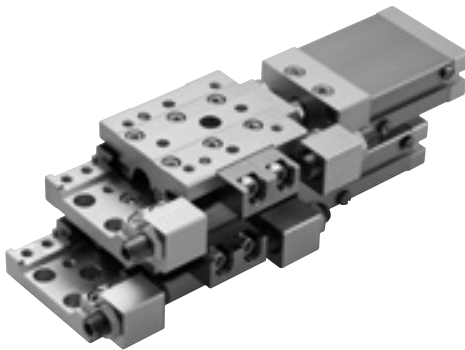
### ● Crossed unit



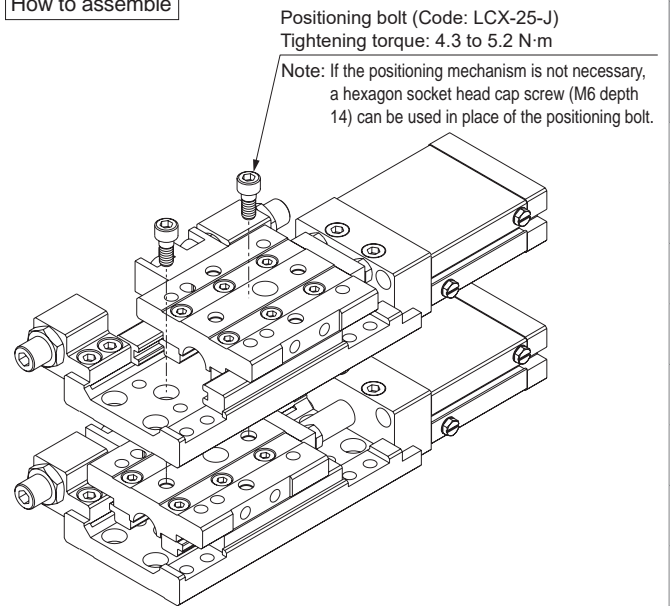
#### How to assemble



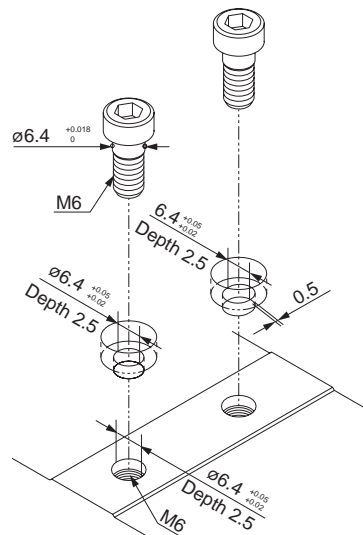
### ● 2-stage unit



#### How to assemble



[Fastening with positioning bolt]



\* The picture shows the standard product.

SCPD3

SCM

SSD2

MDC2

SMG

LCM

LCR

LCG

**LCX**

STM

STG

STR2

MRL2

GRC

Cylinder  
Switch

MN3E  
MN4E

4GA/B

M4GA/B

MN4GA/B

F.R. (module  
unit)

Clean  
F.R

Precision  
R

Press gauge  
Diff. press gauge

Electro-  
pneumatic R

Speed  
controller

Auxiliary  
valve

Fitting/  
tube

Clean  
air unit

Pressure  
sensor

Flow rate  
sensor

Valve for  
air blow

Ending

### STEP-1

Calculate the load factor and decide the bore size.

$$\alpha = \frac{F_0}{F} \times 100 (\%)$$

$\alpha$  : Load factor

$F_0$  : Force (N) required to move the workpiece

$F$  : Cylinder theoretical thrust (N)  
(Table 1)

For horizontal operation	For vertical operation
$F_0 = Fw$	$F_0 = W + Fw$
$FW: W \times 0.2$ Note (N)	
$W$ : Load (N)	

Note : coefficient of friction

(Table 1) Theoretical thrust table

(Unit: N)

Bore size	Operating direction	Working pressure MPa						
		0.15	0.2	0.3	0.4	0.5	0.6	0.7
ø25 equiv.	PUSH	74	99	148	197	246	296	345
	PULL	57	76	114	152	190	228	266
ø32 equiv.	PUSH	116	155	233	310	388	466	543
	PULL	99	133	199	265	332	398	464

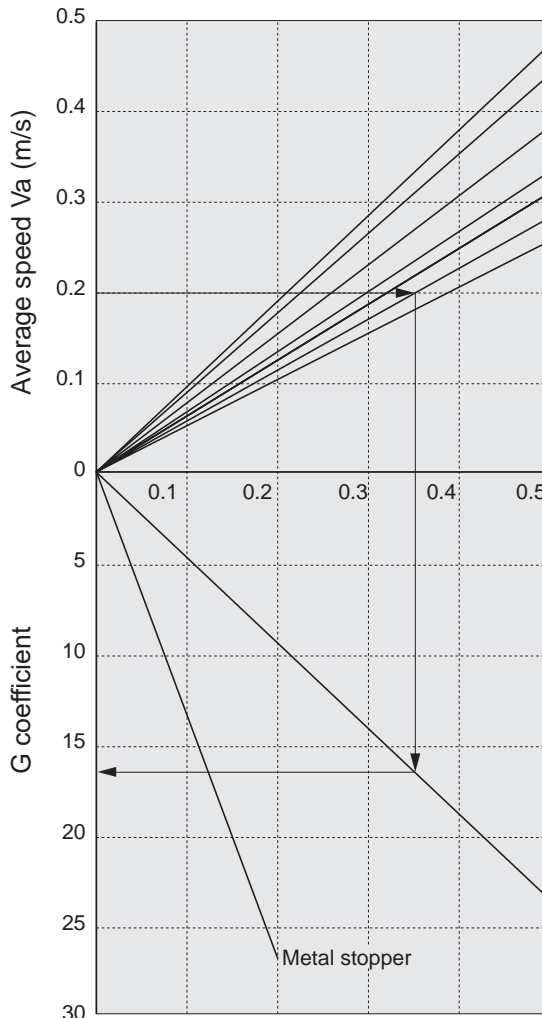
(Table 2) Rough indication of load factor

Working pressure MPa	Load factor (%)
0.2 to 0.3	$\alpha \leq 40$
0.3 to 0.6	$\alpha \leq 50$
0.6 to 0.7	$\alpha \leq 60$

### STEP-2

Obtain the stroke end speed ( $V_m$ ) and G coefficient.

Obtain the stroke end speed ( $V_m$ ) and G coefficient from the average speed ( $V_a$ ) and load factor obtained in STEP-1.



Load factor 5%  
Load factor 10%  
Load factor 20%  
Load factor 30%  
Load factor 40%  
Load factor 50%  
Load factor 60%

Stroke end speed  $V_m$

The arrows (→) in the figure shows an example that the stroke end speed of 0.35 m/s and G coefficient of 16.8 are obtained at the 0.20 m/s average speed and 50% load factor.

Standard rubber cushion stopper

Graph of speed and G coefficient

G coefficient =

## STEP-3

Check the allowable absorbed energy.

$$E = \frac{1}{2} \times (m + m_a) \times Vm^2$$

$E$  : Kinetic energy at workpiece end (J)  
 $m$  : Load weight (kg) ( $m \doteq \frac{W(N)}{9.8}$ )  
 $m_a$  : Table weight (from Table 4)  
 $Vm$  : Stroke end speed (m/s)  
 $E_{max}$  : Max. allowable value of  $E_0$  (from Table 3)

Confirm  $E \leq E_{max}$ .

(Table 3) LCX allowable absorbed energy value ( $E_0$ )

Bore size	Standard (J)	Cushion stopper (J)	Metal stopper (J)
ø25	0.34	0.14	0.07
ø32			

(Table 4) Table weight (Unit: kg)

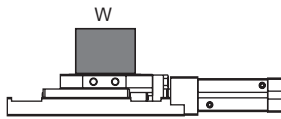
Bore size	Stroke length (mm)								
	10	20	30	40	50	75	100	125	150
ø25	0.030				0.035				
ø32									

## STEP-4

Obtain M'T (resultant moment at rest).

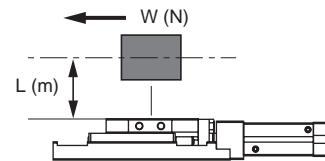
Calculate the load (moment) and the moment of impact occurring at the stroke end and obtain M'T (resultant moment at rest).

● Vertical load:  $W'$  (N)



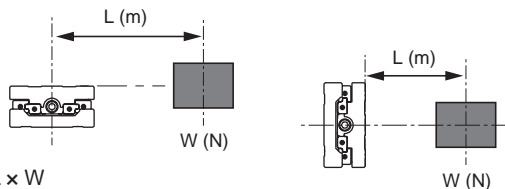
$$W' = W$$

● Bending moment:  $M1'$  (N·m)



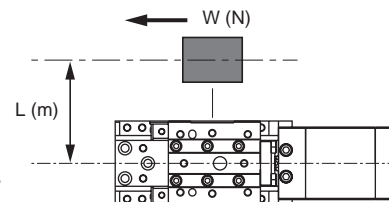
$$M1' = L \times W$$

● Radial moment:  $M2'$  (N·m)



$$M2' = L \times W$$

● Torsion moment:  $M3'$  (N·m)



$$M3' = L \times W$$

$$M'T = \frac{W'}{W'_{max}} + \frac{M1' \times G}{M1'_{max}} + \frac{M2'}{M2'_{max}} + \frac{M3' \times G}{M3'_{max}} = \boxed{\phantom{0.0}}$$

$M'T$  : Synthesis of moment  
 $G$  : G coefficient  
 $W'_{max}$  : Maximum allowable value of  $W'$  (from Table 5)  
 $M1'_{max}$  : Max. allowable value of  $M1'$  (from Table 5)  
 $M2'_{max}$  : Max. allowable value of  $M2'$  (from Table 5)  
 $M3'_{max}$  : Max. allowable value of  $M3'$  (from Table 5)

(Table 5) Allowable static load

Bore size	Stroke length	Vertical load $W'_{max}$ (N)	Bending moment $M1'_{max}$ (N·m)	Radial moment $M2'_{max}$ (N·m)	Torsion moment $M3'_{max}$ (N·m)
ø25	10, 20, 30, 40, 50	670	52	110	52
ø32					
ø25	75, 100, 125, 150	970	128	116	128
ø32					

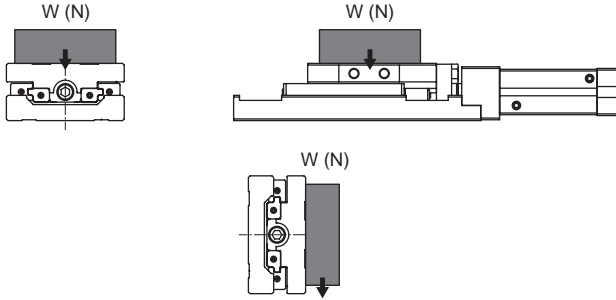
Confirm  $M'T \leq 1$ .

SCPD3  
SCM  
SSD2  
MDC2  
SMG  
LCM  
LCR  
LCG  
LCX  
STM  
STG  
STR2  
MRL2  
GRC  
Cylinder Switch  
MN3E  
MN4E  
4GA/B  
M4GA/B  
MN4GA/B  
F.R. (module unit)  
Clean F.R  
Precision R  
Press gauge  
Diff. press gauge  
Electro-pneumatic R  
Speed controller  
Auxiliary valve  
Fitting/tube  
Clean air unit  
Pressure sensor  
Flow rate sensor  
Valve for air blow  
Ending

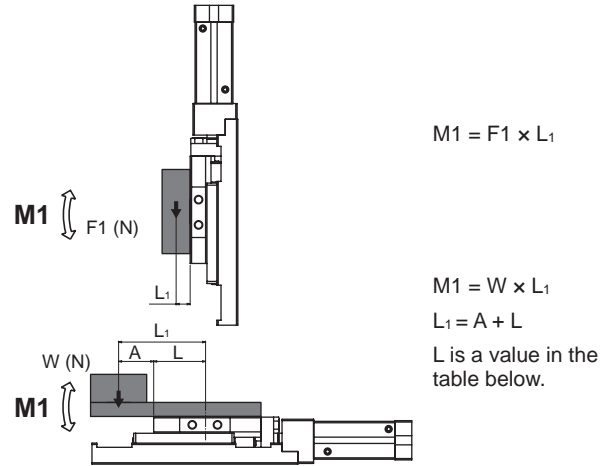
### STEP-5

Obtain  $M_T$  (resultant moment during movement) (Note that it differs from that obtained in STEP-4.)

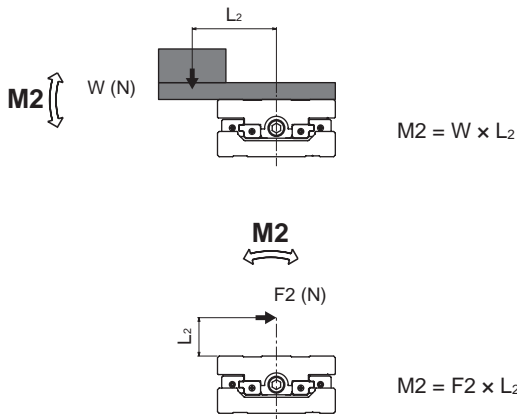
● Vertical load:  $W$  (N)



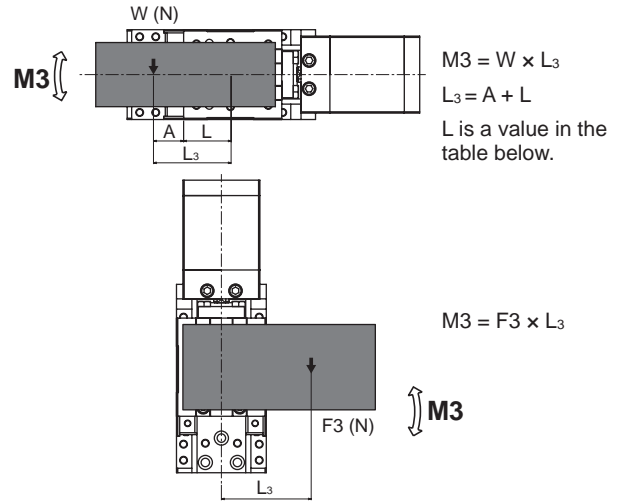
● Bending moment:  $M_1$  (N·m)



● Radial moment:  $M_2$  (N·m)



● Torsion moment:  $M_3$  (N·m)



L (length from the table end to the center of the bearing)

Unit (m)

Bore size	Stroke length									
	10	20	30	40	50	75	100	125	150	
ø25	0.037			0.042		0.0535				
ø32										

$W = W$  =  (N)

$M_1 = M_1$  =  (N·m)

$M_2 = M_2$  =  (N·m)

$M_3 = M_3$  =  (N·m)

$M_T = \frac{W}{W_{max}} + \frac{M_1}{M_{1max}} + \frac{M_2}{M_{2max}} + \frac{M_3}{M_{3max}} =$

$M_T$  : Synthesis of moment

$W_{max}$  : Maximum allowable value of  $W$  (from Table 7)

$M_{1max}$  : Maximum allowable value of  $M_1$  (from Table 7)

$M_{2max}$  : Maximum allowable value of  $M_2$  (from Table 7)

$M_{3max}$  : Maximum allowable value of  $M_3$  (from Table 7)

(Table 7) Allowable moving load

Bore size	Stroke length	Vertical load $W_{max}$ (N)	Bending moment $M_{1max}$ (N·m)	Radial moment $M_{2max}$ (N·m)	Twist moment $M_{3max}$ (N·m)
ø25	10, 20, 30,	97	7	15	7
	40, 50				
ø32	75, 100,	130	17	16.5	17
	125, 150				

Can be used when  $M_T \leq 1$  is satisfied.

### Displacement at point A

#### [Displacement of table due to M1, M2 and M3 moments]

M1 moment: Displacement at the table end when the load (F1) is applied to the table end

M2 moment: Displacement at the table end (point A) when the load (F2) is applied to the point 100 mm away from the center of the cylinder

M3 moment: Displacement angle of the table when the rotation moment (M3) is applied to the cylinder

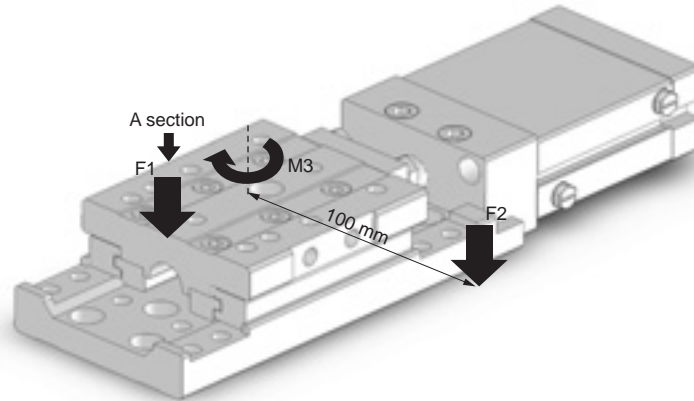


Table deflection of M1 moment

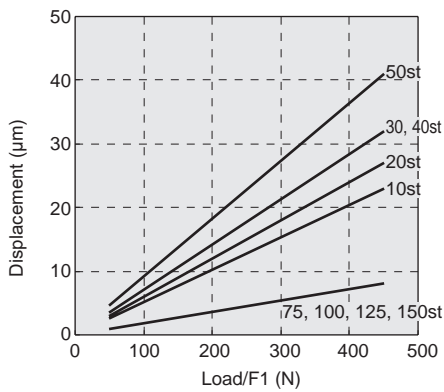


Table deflection of M2 moment

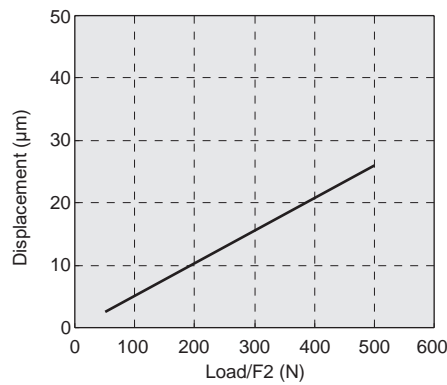
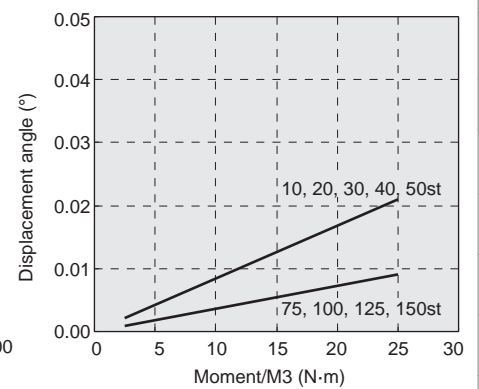
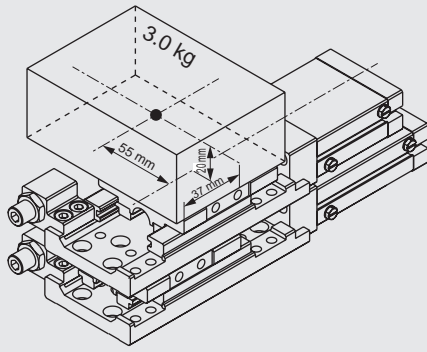


Table deflection of M3 moment



SCPD3
SCM
SSD2
MDC2
SMG
LCM
LCR
LCG
<b>LCX</b>
STM
STG
STR2
MRL2
GRC
Cylinder Switch
MN3E MN4E
4GA/B
M4GA/B
MN4GA/B
F.R. (module unit)
Clean F.R
Precision R
Press gauge Diff. press gauge
Electro-pneumatic R
Speed controller
Auxiliary valve
Fitting/tube
Clean air unit
Pressure sensor
Flow rate sensor
Valve for air blow
Ending

## Selection guide: selection example (1)



### [Operation condition]

Model used (upper): LCX-25-30-M6 (product weight: 1,270 (g))  
(lower): LCX-32-30-S6 (product weight: 1,440 (g))

Pressure: 0.5 (MPa)

Weight of workpiece: 3.0 (kg)

Operating direction: Horizontal

Average speed (upper): 100 (mm/s)

(lower): 230 (mm/s)

Shape of workpiece: As shown on the left

## STEP-1 Check of the load factor and decision of the bore size (For details on how to calculate, refer to page 188.)

### Formula

$$\alpha = \frac{F_0}{F} \times 100 (\%)$$

$\alpha$  : Load factor

$F_0$  : Force (N) required to move the workpiece

$F$  : Cylinder theoretical thrust (N)

### Selection example

[Cylinder on upside]

$$\alpha_1 = \frac{(3.0 \times 9.8) \times 0.2}{190} \times 100 = 3.1\%$$

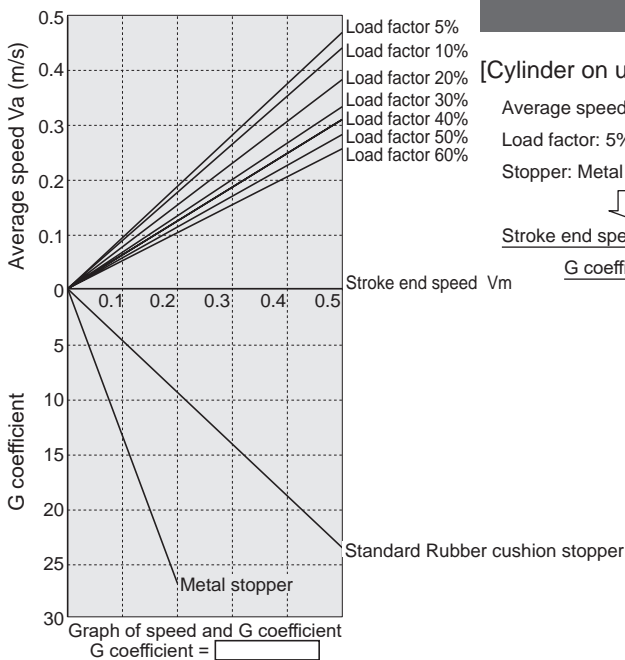
[Cylinder on downside]

$$\alpha_2 = \frac{((3.0 + 1.27 + 0.01) \times 9.8) \times 0.2}{332} \times 100 = 2.5\%$$

Can be used since the estimated load factor at 0.5 MPa is

Can be used as " $\alpha \leq 50$ "

## STEP-2 Check of the stroke end speed and G factor (For details on how to calculate, refer to page 188.)



### Selection example

[Cylinder on upside]

Average speed: 100 mm/s  
Load factor: 5% or less (3.1%)  
Stopper: Metal stopper

Stroke end speed: 110 mm/s

G coefficient: 14

[Cylinder on downside]

Average speed: 230 mm/s  
Load factor: 5% or less (2.5%)  
Stopper: Rubber cushion stopper

Stroke end speed: 240 mm/s

G coefficient: 12

## STEP-3 Check of the allowable absorbed energy (For details on how to calculate, refer to page 189.)

### Formula

$$E = \frac{1}{2} \times (m + m_a) \times V_m^2$$

$E$  : Kinetic energy at workpiece end (J)

$m$  : Load weight (kg)

$m_a$  : Table weight (kg)

$V_m$  : Stroke end speed (m/s)

### Selection example

[Cylinder on upside]

$$E = \frac{1}{2} \times (3.0 + 0.03) \times 0.11^2 = 0.02 \text{ (J)}$$

Can be used since the allowable absorbed energy of the metal stopper is "0.07J"

[Cylinder on downside]

$$E = \frac{1}{2} \times (3.0 + 1.27 + 0.01 + 0.035) \times 0.24^2 = 0.124 \text{ (J)}$$

Can be used since the allowable absorbed energy of the rubber cushion stopper is "0.14J"

### STEP-4 Check of the allowable static load (For details on how to calculate, refer to page 189.)

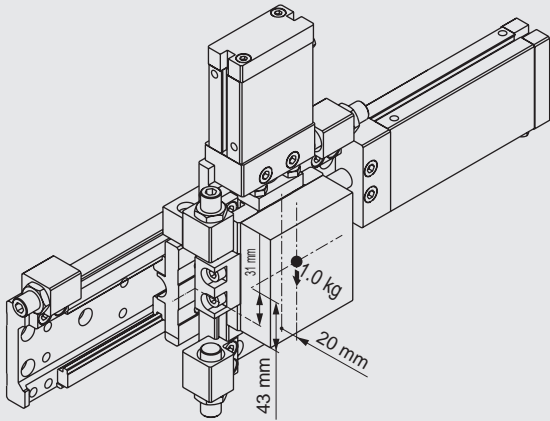
Formula	Selection example	
<ul style="list-style-type: none"> <li>● Vertical load <math>W' = W</math></li> <li>● Bending moment: <math>M1'</math> (N·m) <math>M1' = L_1 \times W</math></li> <li>● Radial moment: <math>M2'</math> (N·m) <math>M2' = L_2 \times W</math></li> <li>● Torsion moment: <math>M3'</math> (N·m) <math>M3' = L_3 \times W</math></li> <li>◎ Synthesis of moment</li> </ul> $M_T = \frac{W'}{W_{max}} + \frac{M1' \times G}{M1'_{max}} + \frac{M2'}{M2'_{max}} + \frac{M3' \times G}{M3'_{max}}$	<p>[Calculating load and moment]</p> <p>[Cylinder on upside]</p> $W' = 3.0 \times 9.8 = 29.4 \text{ (N)}$ $M1' = 0.02 \times 29.4 = 0.6 \text{ (N·m)}$ $M2' = 0.055 \times 29.4 = 1.6 \text{ (N·m)}$ $M3' = 0.055 \times 29.4 = 1.6 \text{ (N·m)}$	
	<p>[Cylinder on downside]</p> $W' = 3.0 \times 9.8 + 1.27 \times 9.8 = 41.8 \text{ (N)}$ $M1' = 0.054 \times 29.4 + 0.017 \times 1.27 \times 9.8 = 1.8 \text{ (N·m)}$ <small>(Omit the underlined part if the cylinder on upside does not work as a moment of impact.)</small> $M2' = 0.055 \times 29.4 = 1.6 \text{ (N·m)}$ $M3' = 0.055 \times 29.4 = 1.6 \text{ (N·m)}$	
	<p>[Resultant moment when the cylinder on upside operates]</p> <p>Stroke end speed: 110 mm/s, G factor: 14</p> <p>[Cylinder on upside]</p> $M_T = \frac{29.4}{670} + \frac{0.6 \times 14}{52} + \frac{1.6}{110} + \frac{1.6 \times 14}{52} = 0.7$ <u>Can be used since the resultant moment (<math>M_T</math>) is "1 or less"</u> <p>[Cylinder on downside]</p> $M_T = \frac{41.8}{670} + \frac{1.6 \times 14}{52} + \frac{1.6}{110} + \frac{1.6 \times 14}{52} = 1.0$ <u>Can be used since the resultant moment (<math>M_T</math>) is "1 or less"</u>	
	<p>[Resultant moment when the cylinder on downside operates]</p> <p>Stroke end speed: 240 mm/s, G factor: 12</p> <p>[Cylinder on upside]</p> $M_T = \frac{29.4}{670} + \frac{0.6 \times 12}{52} + \frac{1.6}{110} + \frac{1.6 \times 12}{52} = 0.6$ <u>Can be used since the resultant moment (<math>M_T</math>) is "1 or less"</u> <p>[Cylinder on downside]</p> $M_T = \frac{41.8}{670} + \frac{1.8 \times 12}{52} + \frac{1.6}{110} + \frac{1.6 \times 12}{52} = 0.9$ <u>Can be used since the resultant moment (<math>M_T</math>) is "1 or less"</u>	

### STEP-5 Check of the allowable dynamic load (For details on how to calculate, refer to page 190.)

Formula	Selection example	
<ul style="list-style-type: none"> <li>● Vertical load <math>W = W</math></li> <li>● Bending moment: <math>M1</math> (N·m) <math>M1 = L_1 \times W</math></li> <li>● Radial moment: <math>M2</math> (N·m) <math>M2 = L_2 \times W</math></li> <li>● Torsion moment: <math>M3</math> (N·m) <math>M3 = L_3 \times W</math></li> <li>◎ Synthesis of moment</li> </ul> $M_T = \frac{W}{W_{max}} + \frac{M1}{M1_{max}} + \frac{M2}{M2_{max}} + \frac{M3}{M3_{max}}$	<p>[Cylinder on upside]</p> $W = 3.0 \times 9.8 = 29.4 \text{ (N)}$ $M1 = 0 \text{ (N·m)}$ $M2 = 0.055 \times 29.4 = 1.6 \text{ (N·m)}$ $M3 = 0 \text{ (N·m)}$ $M_T = \frac{29.4}{97} + \frac{0}{7} + \frac{1.6}{15} + \frac{0}{7} = 0.4$ <u>Can be used since the resultant moment (<math>M_T</math>) is "1 or less"</u>	
	<p>[Cylinder on downside]</p> $W = 3.0 \times 9.8 + 1.27 \times 9.8 = 41.8 \text{ (N)}$ $M1 = 0.035 \times 29.4 + 0.068 \times 1.27 \times 9.8 = 1.9 \text{ (N·m)}$ <small>(Add the value of the cylinder on upside since it works as a moment. Substitute the center of the external dimensions for the center of gravity of the cylinder.)</small> $M2 = 0.055 \times 29.4 = 1.6 \text{ (N·m)}$ $M3 = 0 \text{ (N·m)}$ $M_T = \frac{41.8}{97} + \frac{1.9}{7} + \frac{1.6}{15} + \frac{0}{7} = 0.8$ <u>Can be used since the resultant moment (<math>M_T</math>) is "1 or less"</u>	
<p>(L on page190)</p>		

SCPD3
SCM
SSD2
MDC2
SMG
LCM
LCR
LCG
<b>LCX</b>
STM
STG
STR2
MRL2
GRC
Cylinder Switch
MN3E
MN4E
4GA/B
M4GA/B
MN4GA/B
F.R. (module unit)
Clean F.R
Precision R
Press gauge
Diff. press gauge
Electro-pneumatic R
Speed controller
Auxiliary valve
Fitting/tube
Clean air unit
Pressure sensor
Flow rate sensor
Valve for air blow
Ending

## Selection guide: selection example (2)



### [Operation condition]

Model used (X-axis): LCX-32-150-A6 (product weight: 2,450 (g))  
 (Z-axis): LCX-32-30-S6 (product weight: 1,440 (g))  
 Pressure: 0.5 (MPa)  
 Weight of workpiece: 1.0 (kg)  
 Operating direction: Horizontal + vertical  
 Average speed (X-axis) : 300 (mm/s)  
 (Z-axis): 50 (mm/s)  
 Shape of workpiece: As shown on the left

## STEP-1 Check of the load factor and decision of the bore size (For details on how to calculate, refer to page 188.)

### Formula

$$\alpha = \frac{F_0}{F} \times 100 (\%)$$

$\alpha$  : Load factor

$F_0$  : Force (N) required to move the workpiece

$F$  : Cylinder theoretical thrust (N)

### Selection example

[X-axis cylinder]

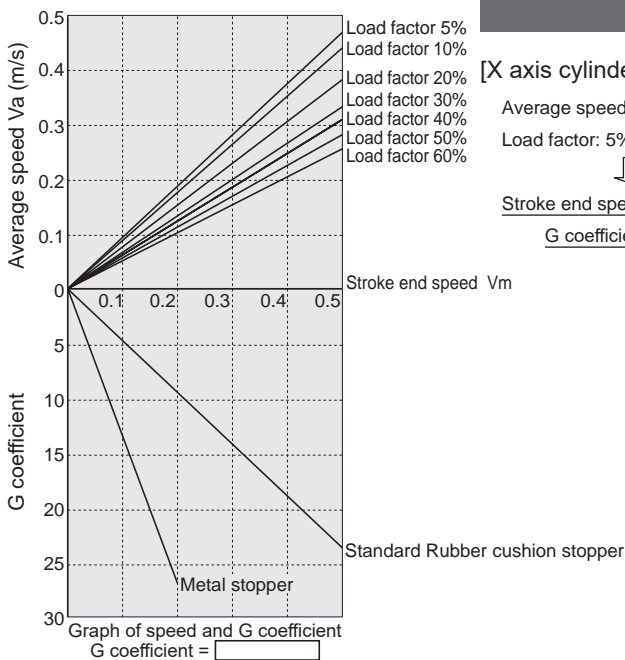
$$\alpha_1 = \frac{((1.0 + 1.29 + 0.01) \times 9.8) \times 0.2}{332} \times 100 = 1.4\%$$

[Z axis cylinder]

$$\alpha_2 = \frac{(1.0 \times 9.8) + 0.2 \times (1.0 \times 9.8)}{332} \times 100 = 3.5\%$$

Can be used since the estimated load factor at 0.5 MPa is  
 Can be used as " $\alpha \leq 50$ "

## STEP-2 Check of the stroke end speed and G factor (For details on how to calculate, refer to page 188.)



### Selection example

[X axis cylinder]

Average speed: 300 mm/s  
 Load factor: 5% or less (1.4%)  
 ↓  
 Stroke end speed: 310 mm/s  
 G coefficient: 4

[Z axis cylinder]

Average speed: 50 mm/s  
 Load factor: 5% or less (3.5%)  
 Stopper: Rubber cushion stopper  
 ↓  
 Stroke end speed: 55 mm/s  
 G coefficient: 3

## STEP-3 Check of the allowable absorbed energy (For details on how to calculate, refer to page 189.)

### Formula

$$E = \frac{1}{2} \times (m + m_a) \times Vm^2$$

$E$  : Kinetic energy at workpiece end (J)

$m$  : Load weight (kg)

$m_a$  : Table weight (kg)

$Vm$  : Stroke end speed (m/s)

### Selection example

[X axis cylinder]

$$E = \frac{1}{2} \times (1.0 + 1.29 + 0.01 + 0.035) \times 0.31^2 = 0.11 (J)$$

Can be used since the allowable absorbed energy of the shock absorber stopper is "1.3J"

[Z axis cylinder]

$$E = \frac{1}{2} \times (1.0 + 0.035) \times 0.055^2 = 0.002 (J)$$

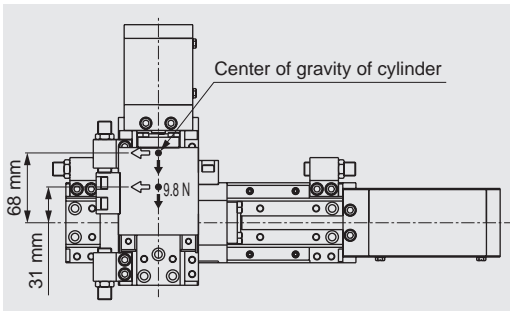
Can be used since the allowable absorbed energy of the rubber cushion stopper is "0.14J"

### STEP-4 Check of the allowable static load (For details on how to calculate, refer to page 189.)

#### Formula

- Vertical load  
 $W' = W$
- Bending moment:  $M1'$  (N·m)  
 $M1' = L1 \times W$
- Radial moment:  $M2'$  (N·m)  
 $M2' = L2 \times W$
- Torsion moment:  $M3'$  (N·m)  
 $M3' = L3 \times W$
- ◎ Synthesis of moment  
$$M'T = \frac{W'}{W_{max}} + \frac{M1' \times G}{M1'_{max}} + \frac{M2'}{M2'_{max}} + \frac{M3' \times G}{M3'_{max}}$$

Note) In the crossed unit, a moment of impact may occur in the M2 direction. Multiply the G coefficient with the M2' value as necessary.



#### Selection example

##### [Calculating load and moment]

##### [X axis cylinder]

$$W' = 1.0 \times 9.8 + 1.44 \times 9.8 = 23.9 \text{ (N)}$$

$$M1' = 0.054 \times 9.8 + 0.017 \times 1.44 \times 9.8 = 0.8 \text{ (N·m)}$$

(Add the value of the Z-axis cylinder since it works as a moment.)

$$M2' = 0.054 \times 9.8 + 0.017 \times 1.44 \times 9.8 = 0.8 \text{ (N·m)}$$

$$M3' = 0.031 \times 9.8 + 0.068 \times 1.44 \times 9.8 = 1.3 \text{ (N·m)}$$

##### [Z axis cylinder]

$$W' = 0 \text{ (N)}$$

$$M1' = 0.02 \times 9.8 = 0.2 \text{ (N·m)}$$

$$M2' = 0.02 \times 9.8 = 0.2 \text{ (N·m)}$$

$$M3' = 0.001 \times 9.8 = 0.01 \text{ (N·m)}$$

##### [Resultant moment when the X-axis cylinder operates]

Stroke end speed: 310 mm/s, G factor: 4

##### [X axis cylinder]

$$M'T = \frac{23.9}{970} + \frac{0.8 \times 4}{128} + \frac{0.8}{116} + \frac{1.3 \times 4}{128} = 0.1$$

Can be used since the resultant moment (M'T) is "1 or less"

##### [Z axis cylinder]

$$M'T = \frac{0}{670} + \frac{0.2}{52} + \frac{0.2 \times 4}{110} + \frac{0.01 \times 4}{52} = 0.01$$

(Multiply the G factor if a moment of impact in M2 direction is caused in the Z-axis cylinder by operation of the X-axis cylinder.)  
Can be used since the resultant moment (M'T) is "1 or less"

##### [Resultant moment when the Z-axis cylinder operates]

Stroke end speed: 55 mm/s, G factor: 3

##### [X axis cylinder]

$$M'T = \frac{23.9}{970} + \frac{0}{128} + \frac{0.5 \times 3 + 0.2}{116} + \frac{0}{128} = 0.04$$

(Multiply the G factor if a moment of impact in M2 direction is caused in the X-axis cylinder by operation of the Z-axis cylinder.)  
Can be used since the resultant moment (M'T) is "1 or less"

##### [Z axis cylinder]

$$M'T = \frac{0}{670} + \frac{0.2 \times 3}{52} + \frac{0}{110} + \frac{0}{52} = 0.01$$

Can be used since the resultant moment (M'T) is "1 or less"

### STEP-5 Check of the allowable dynamic load (For details on how to calculate, refer to page 190.)

#### Formula

- Vertical load  
 $W = W$
- Bending moment:  $M1$  (N·m)  
 $M1 = L1 \times W$
- Radial moment:  $M2$  (N·m)  
 $M2 = L2 \times W$
- Torsion moment:  $M3$  (N·m)  
 $M3 = L3 \times W$
- ◎ Synthesis of moment  
$$M_T = \frac{W}{W_{max}} + \frac{M1}{M1_{max}} + \frac{M2}{M2_{max}} + \frac{M3}{M3_{max}}$$

#### Selection example

##### [X axis cylinder]

$$W = 1.0 \times 9.8 + 1.44 \times 9.8 = 23.9 \text{ (N)}$$

$$M1 = 0 \text{ (N·m)}$$

$$M2 = 0.054 \times 9.8 + 0.017 \times 1.44 \times 9.8 = 0.8 \text{ (N·m)}$$

$$M3 = 0 \text{ (N·m)}$$

$$M_T = \frac{23.9}{130} + \frac{0}{17} + \frac{0.8}{16.5} + \frac{0}{17} = 0.2$$

Can be used since the resultant moment (M'T) is "1 or less"

##### [Z axis cylinder]

$$W = 0 \text{ (N)}$$

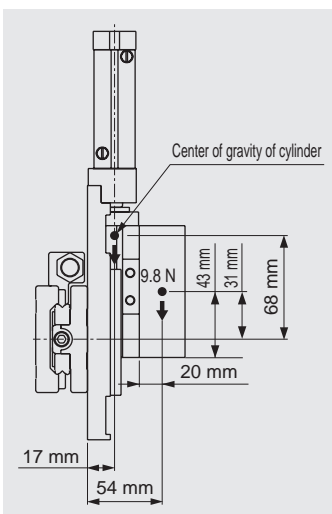
$$M1 = 0.02 \times 9.8 = 0.2 \text{ (N·m)}$$

$$M2 = 0 \text{ (N·m)}$$

$$M3 = 0 \text{ (N·m)}$$

$$M_T = \frac{0}{97} + \frac{0.2}{7} + \frac{0}{15} + \frac{0}{7} = 0.03$$

Can be used since the resultant moment (M'T) is "1 or less"





Pneumatic components

# Safety Precautions

Always read this section before use.

Refer to page 2 for general information of the cylinder, and to page 320 for general information of the cylinder switch.

Thin linear slide cylinder LCX Series

## Design & selection

### 1. Common

#### CAUTION

- When selecting the cylinder, follow the "LCX selection guide" on pages 188 to 190.
- Protect the cylinder with a cover to prevent damage and malfunction in a place where it is exposed to water or oil drops, or corrosive conditions.
- Caution for mounting the switch
  - Be careful of the lead wire direction when designing the 30 mm or less stroke length of axial lead wire and the 20 mm stroke length of radial lead wire since a switch is installed in each groove of the body.
- Keep the supply pressure 0.5 MPa and over when the ambient temperature of the cylinder is 5°C or less.
- Contact CKD if the use environment is always cold (5°C or less) or hot (40°C and over).

- The following two types of stopper with stroke adjusting function are available.

- Rubber cushion stopper
 

The stopper has an integrated urethane rubber cushion. A stopper allowing for contact to the metal part at 0.4 MPa and over for a stable stop position is also available. Contact CKD for details.
- Metal stopper
 

The stopper has no cushion mechanism and should be used for a low-load and low-speed application. The stop position is stable since it does not suffer from deformation of a rubber cushion.

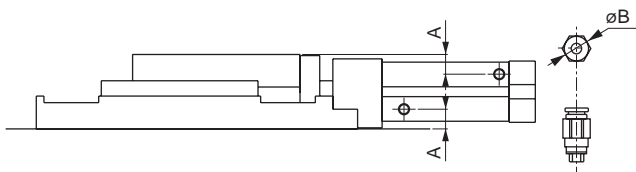
## Mounting, installation & adjustment

### 1. Common; when piping

#### CAUTION

- Precautions for piping
 

Be sure to attach a speed controller during piping before use. The available fittings are as below.



Descriptions	Port diameter	Port location dimensions A	Applicable fitting	Fitting O.D. B
Bore size (mm) ø25	M5	9.5	SC3W-M5-4-P7* SC3W-M5-6-P7* GWS4-M5-S-P7* GWS4-M5-P7*	ø17 or less
Bore size (mm) ø32			9 GWL4-M5-P7* GWS6-M5-S-P7* GWS6-M5-P7* GWL6-M5-P7*	

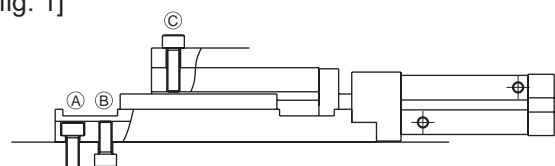
### 2. Common; when installing

#### CAUTION

- The installation surfaces of the base and table have been finished with precision machining to obtain high-precision linear movement. Therefore, grinding the installation surface of the device to improve flatness will enable more stable high-precision performance. (Recommended flatness: 0.01 mm or less) Do not damage surface flatness by denting or scratching the mounting surface.

- Observe the following bolt insertion lengths and tightening torque when installing the jig on the table or base.

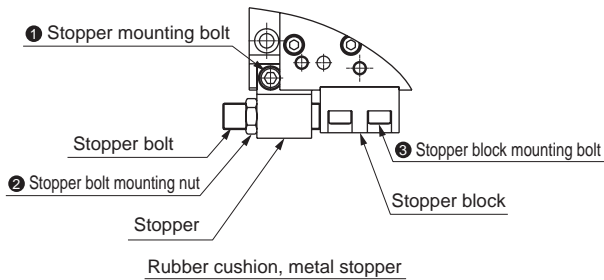
[fig. 1]



Descriptions	A		B		Max. insertion length	C		Max. insertion length
	Applicable bolts	Tightening torque (N·m)	Applicable bolts	Tightening torque (N·m)		Applicable bolts	Tightening torque (N·m)	
LCX-25	M6	4.3 to 5.2	M6 x 1.0	4.3 to 5.2	9.5 mm	M6 x 1.0	4.3 to 5.2	11 mm
LCX-32								

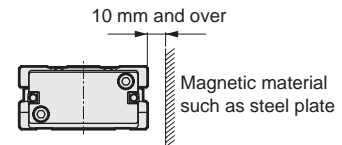
## Mounting, installation & adjustment

- Observe the following tightening torque of bolts and nuts of the stopper.  
[Fig. A]

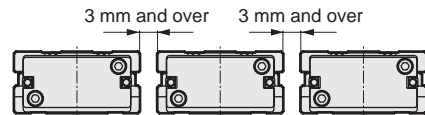


Descriptions	1 Stopper mounting bolt (N·m)	2 Stopper bolt mounting nut (N·m)	3 Stopper block mounting bolt (N·m)
LCX-25	4.3 to 5.2	4.5 to 6.0	4.3 to 5.2
LCX-32			

- The cylinder switch could malfunction if there is a magnetic substance such as a metal plate installed adjacently. To ensure safe operation, keep it 10 mm and over away from the cylinder surface or change the installation surface of the cylinder switch.  
(Common for all port sizes)



- The cylinder switches may accidentally function if the cylinders are close to each other. Keep the distance between the surfaces of the cylinders.  
(Common for all port sizes)



- When using a positioning hole, use a pin of the dimensions that do not require press fitting. If a pin is press fitted, the load of press fitting may damage or distort the linear guide, lowering the accuracy. The recommended tolerance of a pin is JIS tolerance m6 or less.

## During use & maintenance

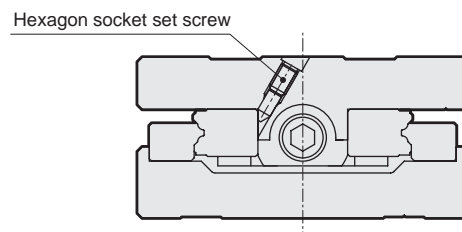
### 1. Common

#### CAUTION

- Apply AFF grease (THK) to the guide rail in six months or when the number of operation times reaches one million, whichever comes first.

### 2. Long stroke length LCX-\*L

- The preload of the linear guide has been adjusted to an optimum value. Do not loosen or tighten the hexagon socket set screw. Doing so may degrade the product performance.



SCPD3
SCM
SSD2
MDC2
SMG
LCM
LCR
LCG
<b>LCX</b>
STM
STG
STR2
MRL2
GRC
Cylinder Switch
MN3E
MN4E
4GA/B
M4GA/B
MN4GA/B
F.R.(module unit)
Clean F.R
Precision R
Press gauge
Diff. press gauge
Electro-pneumatic R
Speed controller
Auxiliary valve
Fitting/tube
Clean air unit
Pressure sensor
Flow rate sensor
Valve for air blow
Ending