LBC Air bearing actuator

Special

Overview

Air static pressure soft actuator based on non-contact air bearing mechanism with zero sliding resistance. The actuator enables sensitive and precise load control when combined with electro pneumatic regulator (EV).



CONTENTS

Product introduction	996
● Single acting/push (LBC)	998
▲Safety precautions	1004

LCM LCR LCG LCW LCX STM STG STR2 UCA2 ULK* JSK/M2 JSG JSC3/JSC4 USSD UFCD USC UB JSB3 LMB LML HCM HCA LBC CAC4 UCAC2 CAC-N UCAC-N RCS2 RCC2 PCC SHC MCP GLC MFC BBS RRC GRC RV3 NHS HRL LN Hand Chuk MecHnd/Chuk

ShkAbs FJ FK SpdContr

Actuators breaking free of sliding resistance 0



LCM LCR LCG LCW LCX STM STG

STM STG STS/STL STR2 UCA2 ULK* JSK/M2 JSG

JSC3/JSC4 USSD UFCD USC UB JSB3

LMB
LML
HCM
HCA
LBC
CAC4
UCAC2

CAC-N UCAC-N RCS2 RCC2 PCC SHC MCP GLC

MFC BBS RRC GRC RV3* NHS HRL

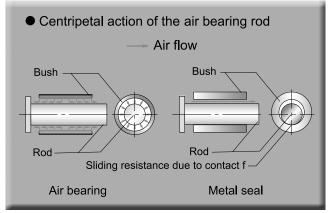
LN
Hand
Chuk
MecHnd/Chuk
ShkAbs
FJ
FK

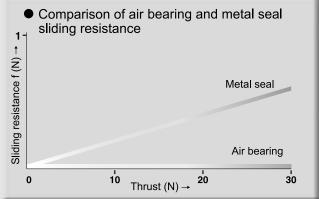
Ending

Minimum control load 0.01 N

Air static pressure type soft actuator LBC Series based on non-contact air bearing mechanism with zero sliding resistance.

The actuator enables sensitive and precise load control when combined with an electro-pneumatic regulator (EV).





LCM LCR LCG LCW

I CX STM

STR2

UCA2

JSK/M2

JSC3/JS UFCD UB

JSB3

LMB

LBC

CAC4 UCAC2 CAC-N UCAC-N RCS2

RCC2

SHC

MCP **GLC MFC** BBS

RRC

NHS

HRL LN

Hand

Chuk

I MI **HCM**

Appropriate for clean environments

Non-contact, non-lubricated air driving method without generating dust. The product is appropriate for clean environments.

Soft touch

Due to allowable minimum load control of 0.01 N, a soft touch on the workpiece is possible. The workpiece is not exposed to impact or damaged.

Optimum load for workpiece

The best load according to the purpose and application will be applied to the workpiece.

Excellent response

The rod (moving part) made of light aluminum alloy enables excellent response.

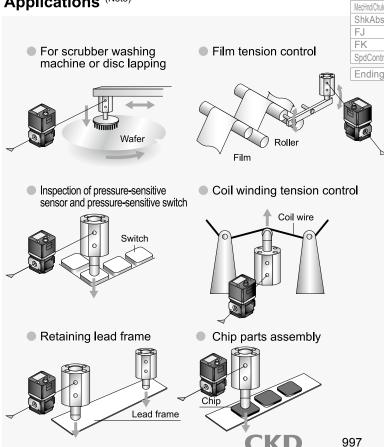
Space-saving & compact

(Note) Rod return mechanism is not provided. If returning the rod is necessary in horizontal or vertical downward applications, combine any other cylinder to return the LBC itself.

High precision linear control

As there is no sliding resistance, high precision linear load control is possible with the electro-pneumatic regulator (EV-FL).

Applications (Note)





Air bearing actuator Single acting/push

LBC Series





Specifications

LCM LCR LCG LCW LCX STM STG

STR2 UCA2

ULK* JSK/M2 JSG JSC3/JSC4 USSD UFCD USC UB JSB3 LMB LML HCM LBC CAC4 UCAC2 CAC-N UCAC-N RCS2 RCC2 PCC

SHC

MCP

GLC MFC BBS RRC GRC RV3

NHS HRL

LN Hand

Chuk

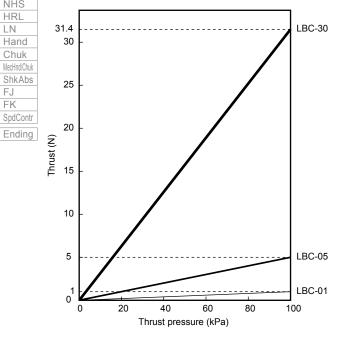
FJ

FK

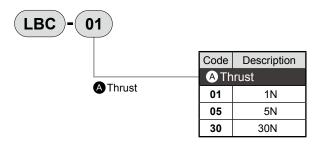
Item			LBC-01	LBC-05	LBC-30				
Actuation Single acting/push (*1)									
Working f	luid		Clean compresse	Clean compressed air (JIS B 8392-1: 2003 Grade 1.4.2 or equivalent)					
Working	Air bearing port		0.3	0.3 (≈44 psi, 3 bar) to 0.5 (≈73 psi, 5 bar)					
pressure MPa Thrust port			0.002	0.002 (≈0.29 psi, 0.02 bar) to 0.1 (≈15 psi, 1 bar)					
Ambient temperature °C				5 (41°F) to 35 (95°F)					
Proof pressure MPa			0.75 (≈110 psi, 7.5 bar)						
Pressuriz	ed area	mm²	10	50	314				
Thrust rar	nge	Ν	0.02 to 1.0	0.1 to 5.0	0.6 to 31.4				
Stroke length mm		Ę	5 ⁺¹ ₀						
Allowable	lateral load	Ν	1.2	0.8	4.0				
Weight g		g	50	45	345				
Movable part weight (*2) g		g	5	4.5	65				
Bearing part air consumption (*3)		2.5 or less	2.5 or less	7.5 or less					

- *1 : Rod return mechanism is not available.
- *2 : Movable part weight indicates the total weight of rod, stopper and cross headed flat head screw.
- $^{\star}3\,$: Value when bearing pressure is 0.5 MPa

Thrust characteristics



How to order





Dimensions

LCM LCR

LCG LCW LCX

STM

STG

STS/STI

STR2

UCA2

ULK* JSK/M2

JSG JSC3/JSC4

USSD UFCD

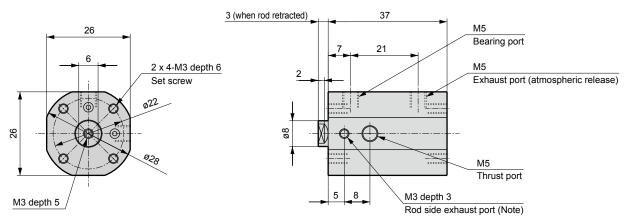
USC

JSB3

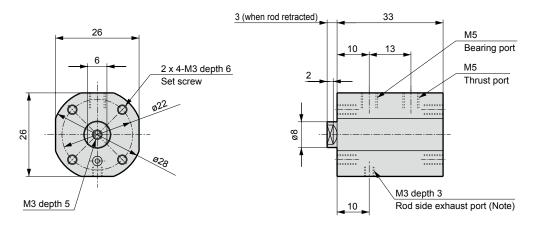
UB

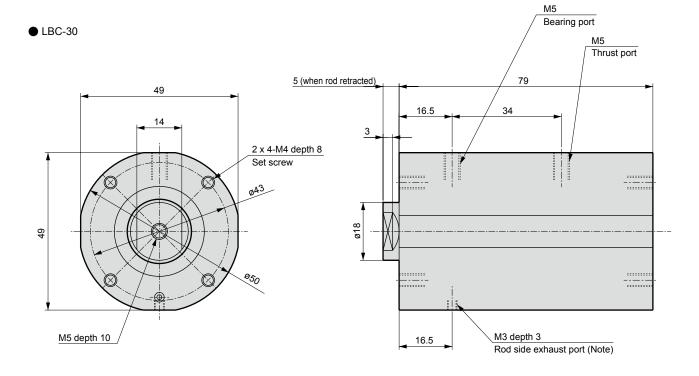
Dimensions

● LBC-01



● LBC-05





LMB LML HCM HCA LBC CAC4 UCAC2 CAC-N UCAC-N RCS2 RCC2 PCC SHC MCP GLC MFC BBS RRC GRC RV3 NHS HRL LN Hand Chuk MecHnd/Chuk ShkAbs

FJ

FΚ

SpdContr

Ending

LBC Series

LCM

LCR LCG

LCW LCX

UB

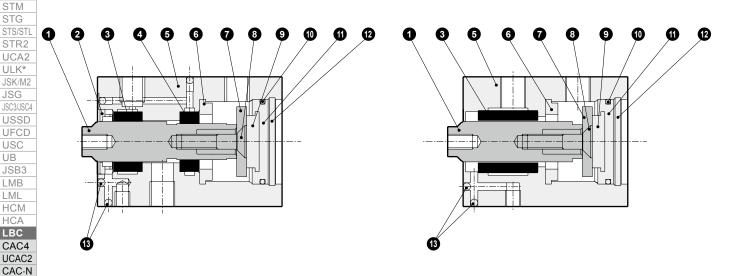
UCAC-N

RCS2 RCC2 PCC SHC MCP GLC **MFC** BBS RRC GRC RV3 NHS HRL LN Hand Chuk MecHnd/Chuk ShkAbs FJ

FΚ SpdContr Ending

Internal structure and parts list

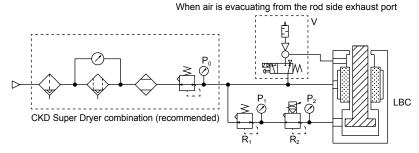
● LBC-01 ● LBC-05, 30



Cannot be disassembled

No.	Part name	Material	Remarks	No.	Part name	Material	Remarks
1	Rod	Aluminum alloy		8	Cross headed flat head screw	Stainless steel	
2	Сар	Aluminum alloy	Alumite	9	Cushion rubber R	Urethane rubber	
3	Bush 1	Carbon graphite porous material		10	Gasket	Nitrile rubber	
4	Bush 2	Carbon graphite porous material		11	Base plate	Special aluminum	Chromate
5	Body	Aluminum alloy	Alumite	12	Snap ring for hole	Stainless steel	
6	Cushion rubber L	Urethane rubber		13	Steel ball	Stainless steel	
7	Stopper	Aluminum alloy	Alumite				

Circuits used



P₀:Air bearing port supply pressure (0.3 to 0.5 MPa)

P₁: Electro pneumatic regulator supply pressure (0.2 MPa)

P₂:Thrust port supply pressure (0.002 to 0.1 MPa)

R₁: Regulator

R₂: Electro pneumatic regulator for LBC

EV25**-FL (Refer to pages 1001 to 1003 for details.) Details of customization

Control pressure 0 to 0.1 MPa (Control pressure accuracy is improved)

Fixed orifice (Pressure relief performance for low pressure range is improved)

Normally open (NO)

(Prevents the rod from popping out when the power supply is turned OFF)

V:SELVACS (VSK)

(Only when necessary to prevent air leak from the rod section)



Electro pneumatic regulator for LBC (made to order)

EV2500 Series

Electro pneumatic regulator for air bearing actuator LBC

Pressure control range: 0 to 0.1 MPa

Actuation: NO

JIS symbol



LCM

LCR

LCG

STR2

ULK* JSK/M2 **JSG** JSC3/JSC4 USSD **UFCD** UB JSB3 LMB LML HCM HCA LBC CAC4 UCAC2 CAC-N UCAC-N RCS2 RCC2 PCC SHC MCP **GLC** MFC BBS RRC GRC RV3 NHS HRL LN Hand Chuk

MecHnd/Chu

ShkAbs

SpdContr Ending

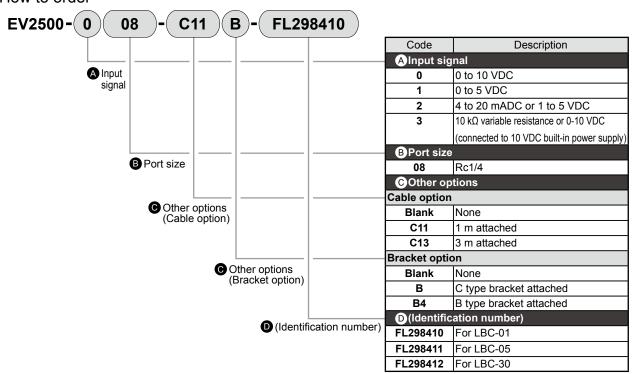
FJ FK

Specifications

Item			EV2500	n ⊡ne El			
		EV2500-□08-FL					
	Working fluid Clean compressed air (JIS B 8392-1: 2012 Grade 1.3.2)				2)		
Working p	ressure range		0.2 (≈29 psi, 2 bar) to	0.3 MPa (≈44 psi, 3 bar)			
Proof pres	ssure		0.7 MPa (≈	100 psi, 7 bar)			
Pressure	control range		0 (≈0 psi, 0 bar) to 0.1 MPa (≈15 psi, 1 bar)				
Power sup	oply voltage	24 VD	C ± 10% (stabilized power	supply with ripple rate 1%	or less)		
Current co	onsumption		0.1 A or less (0.6 A rush current when power is ON)				
Input signal (input impedance)		0 to 10 VDC	0 to 5 VDC	4 to 20 mADC or 1 to 5 VDC	10 kΩ variable resistance		
input sign	ai (input impedance)	(20 kΩ)	(10 kΩ)	(250 Ω) *1	or 0-10 VDC (20 kΩ)		
Monitor or	utput		1 to 1.8 VDC (none for 10	kΩ variable resistance input	t)		
Insulation	resistance		100 MΩ (500	VDC) or more			
Withstand voltage		1500 VAC 1 min.					
	Hysteresis	1% F.S. or less					
A	Linearity	±0.5% F.S. or less					
Accuracy	Resolution	0.5% F.S. or less					
*2	Repeatability	0.5% F.S. or less					
Temperature	Zero point fluctuation	0.75% F.S./°C or less					
characteristics	Span fluctuation	0.35% F.S./°C or less					
Step response *3		0.6 s or less					
Vibration resistance		98 m/s² or less (JISC60068-2-6)					
Operating ambient temperature range		5 to 50°C					
Mounting orientation		Free					
Port size		Rc1/ ₄					
Weight		330 g					

- *1 : When used with a signal voltage of 1 to 5 VDC, 4 to 20 mA of current flows into the EV interior from the signal source. Confirm specifications of the signal source before use.
- *2 : The above characteristics are for FS 10 to 100% control pressure with a power supply voltage 24.0 VDC and a working pressure 0.3 MPa.
- *3 : Working pressure: Max. working pressure and step feed: 50% F.S. → 100% F.S. 50% F.S. → 60% F.S. 50% F.S. → 40% F.S.

How to order



EV2500-FL Series

Dimensions

LCM

LCR LCG

LCW

LCX STM STS/STL STR2 UCA2 ULK*

JSK/M2 JSG JSC3/JSC4

USSD

UFCD USC

UB

JSB3 LMB LML HCM LBC CAC4

UCAC2

CAC-N UCAC-N

RCS2

RCC2 PCC

SHC MCP GLC

MFC

BBS RRC GRC RV3

NHS

HRL

LN

Hand

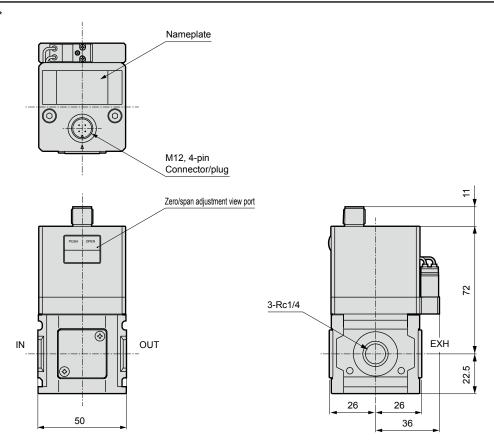
Chuk MecHnd/Chuk ShkAbs FJ

FK

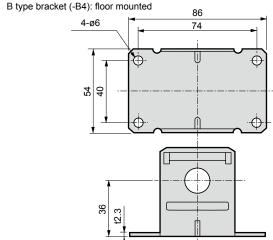
SpdContr

Ending

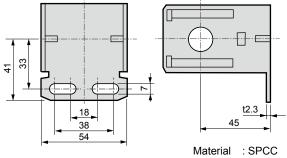
● EV2500-FL*****



Bracket option



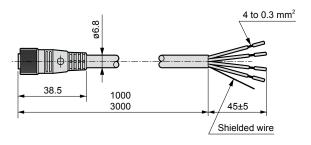
C type bracket (-B): wall mounted



Material : SPCC Treatment: Zinc plated Weight: 165g

Treatment: Zinc plated Weight: 148 g

Cable option



-C1* Shield/cable/connector

	Insulator color	Applications	Type of input signal				
Pin No.			0 to 10 V	0 to 5 V	4 to 20 mA 1 to 5 V	10 kΩVR (0 to 10 V)	
1	Red	Power supply	24 V				
2	Green		Monito	VR input terminal			
3	Black	Common		0 V		VR input terminal 0 V	
4	White	Input signal	0 to 10 V	0 to 5 V	4 to 20 mA 1 to 5 V	VR output terminal (0 to 10 V)	

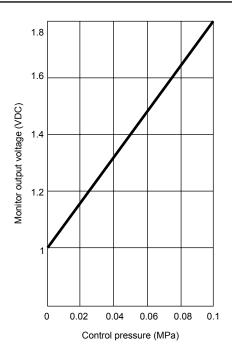
If a cable connector is not used, the following recommended cable sockets (L type) can be used. Use a shielded wire cable. Screw fixing ELWIKA4012

Screw fixing Soldered

XS2C-D422

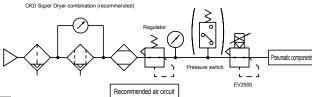
Correns (Hirschmann) OMRON Corporation

Monitor output



Also refer to the precautions of the standard EV2000 Series.

Use clean compressed air that is free of any solids, moisture or oil for working fluid. (JIS B 8392-1: 2012 Grade 1.3.2)



The working pressure is applied to supply the specified pressure for the control pressure. Ensure that the working pressure stays within the specified range. In particular, a prolonged unstable control pressure or a continued state where the control pressure exceeds 0 MPa and is set to 60% FS maximum when there is no working pressure can adversely affect product life. Avoid such conditions.

- 3 Unlike the standard EV2000 Series, the pilot operating pressure of this product is released (NO) when the power is OFF, which causes the secondary pressure to drop to atmospheric pressure.
- This product constantly bleeds the secondary side for the purpose of controlling the flow rate from the bearing port of the air bearing actuator. Significant air flow occurs at the EXH port. For this reason, a loud exhaust noise can be heard from the EXH port, and pressure loss may occur depending on the diameter of the piping. To prevent such occurrences, consider taking the following countermeasures:
 - For exhaust noise : Install a pipe on the EXH port to muffle the sound
 - For pressure loss: Use a pipe with a larger port size or use a higher working pressure, etc.

Custom order

Available as a custom order. Contact CKD for details.

Air bearing cylinder Square shaft

- Non-rotating rod type optimal for precision part installation.
- Jig and rod self-weight cancellation mechanism can also be built in.
- Air flow path for suction and blowing can be built into the rod.
- Square shaft bearing requires no external rotation-stop mechanism.



LCM LCR

SpdConti

Ending



LCM

LCR

LCG LCW LCX STM

STG STS/STI STR2

UCA2 ULK* JSK/M2

JSC3/JSC4

UFCD USC

UB

LMB I MI

HCM

LBC

CAC4

UCAC2

CAC-N UCAC-N

RCS2

RCC2

PCC

SHC

MCP

GLC

MFC

BBS

RRC

RV3

NHS

HRL

LN

Hand

Chuk MecHnd/Chuk

ShkAbs

SpdContr

Ending

FJ FK Safety precautions

Pneumatic components Warnings/cautions

Be sure to read this section before use.

* Refer to Intro Page 73 for cylinders in general.

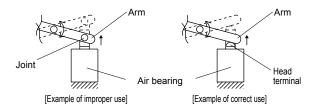
Product-specific cautions: Air bearing actuator LBC Series

Design/selection

ACAUTION

- Use clean, dry compressed air (JIS B 8392-1: 2003 Grade 1.4.2 or equivalent).
 - To supply clean compressed air, install an air filter and oil mist filter. Use of the CKD Super Dryer combination SU Series is recommended. (Refer to page 1003 for compatible circuits)
 - The drainage that occurs due to a drop in temperature within the pneumatic piping or pneumatic components can momentarily block the air flow path and cause operational failure. This can also further cause rust, resulting in pneumatic components failure.
 - Any solid foreign matter in the compressed air can enter the pneumatic components and cause clogging, wear or locking in the bearing.
- Always supply air with the specified pressure (0.3 to 0.5 MPa) to the bearing port when the actuator is in operation.
 - If air is not supplied with the specified pressure, the resulting low load capacity of the bearing can cause the shaft to make contact, resulting in operational failure.
 - Use a pressure switch and install a protection circuit that stops operation when pressure drops.
- Connect a regulator with pressure relief mechanism to the thrust port. When using an electro pneumatic regulator, ensure that it is LBC compatible. (Refer to page 1003 for compatible circuits.)

- The air bearing mounting surface should have a flatness of 0.01 mm or below.
 - Mounting on a low precision surface can cause the bearing to warp, resulting in operational failure.
- Do not connect the end of the rod to an arm, etc.
 - To prevent excessive lateral load from being applied to the bearing, make sure that the rod end is making straight contact with the loading object and that the contact point is a smoothly operating point-contact with low friction.



- Do not use in applications where the rod is rotated using a motor, etc.
 - The rod and bearing will make contact, leading to operational failure.

Mounting, installation and adjustment

ACAUTION

- Regarding installing, setting up, and/or adjusting the actuator, read through the instruction manual and operate correctly.
- Wipe the mounting surface with ethanol and remove any foreign matter by flushing with air blow.
- Supply compressed air to the bearing when installing a jig on the end of the rod.
 If compressed air cannot be supplied, keep the rod

free from lateral load or vibration. This also applies when building the product into the equipment. When attaching a tool to the rod, hold the rod so that no torsional torque or lateral load is applied to the rod or bearing and tighten the screws.

■ The rod is made of an aluminum alloy, which can be easily scratched. Do not touch the outside surface of the rod.

Install the product while the width across flats of the rod end is fixed.

Use/maintenance

ACAUTION

If the product is not going to be in use over a long period of time, store it in a dry, clean environment.

