# SCK

## **Related products**

## Shock absorber/adjustable

## Overview

Impact force absorption with original mechanism. This adjustable shock absorber increases service life and production efficiency of facilities and equipment.

Compared to the NCK, the SCK shock absorber is the ideal buffering device for stopping a workpiece that moves or freefalls at high speeds.

## Features

Safely stops the movable object. Production cycle is increased. Life of machinery is extended. Noise levels are reduced, improving the environment of mechanical facilities. Mechanical failure can be prevented.



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SCP\*3

CMK2

CMA2

SCM

SCG

SCA2

SCS2

CKV2

COVP/N2

SSD2

SSG

SSD

CAT

MDC2

MVC

SMG

MSD/

MSDG

FC\*

STK

SRL3

SRG3

SRM3

SRT3

MRL2

MRG2

SM-25

ShkAbs

FJ

FK

Spd Contr



Shock absorber **SCK** Series

Max. energy absorption: 0.049 to 588J



(B

Series



## Specifications

SCM

SCG

SCA<sub>2</sub>

SCS<sub>2</sub>

CKV2

COVP/N2 SSD2

SSG

SSD

CAT

MDC2

MVC

SMG

MSD/

MSDG

FC\*

STK

SRL3

SRG3

SRM3

SRT3

MRL2

MRG2

SM-25

ShkAbs

FJ

FK

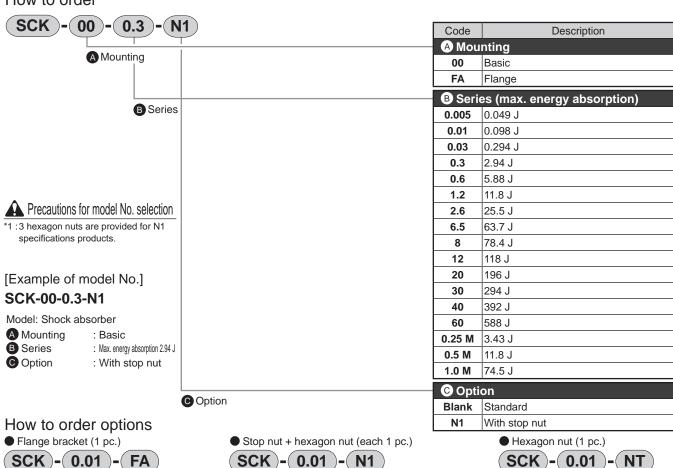
Spd Contr

Ending

	SCK																
0.005	0.01	0.03	0.3	0.6	1.2	2.6	6.5	8	12	20	30	40	60	0.25 M	0.5 M	1.0 M	
	•			Spring return with adjuster											Spring retur with adjuste (thread pitch: la		
0.049	0.098	0.294	2.94	5.88	11.8	25.5	63.7	78.4	118	196	294	392	588	3.43	11.8	74.5	
M10x1.0	M10x1.0 M12x1.0 M16x1.0 M20x1		x1.0	M25	5x1.5	M30x1.5			M40x1.5				M14x1.5	M20x1.5	M27x3.0		
oke mm 7 10					1	5	25			40	60	70		10	15	30	
J/hr 0.135 0.27 0.98 8.1 10		10.8	21.6	39	78	86.4		108 126		120	144	9.2	21.2	80.5			
3	1	.0		1.5	2	.0	2.	.5		3.0			4.0	1.0	2.0	2.5	
	4	5		3	0	25	20 18 12 9 7 5						4	45	30	18	
)						-10 (14°F) to 80 (176°F)											
39	59	147	540	1000	1400	3100	4600	5700	8600	90	00	10000	15000	630	1440	4560	
0	.3 or le	ss		0.4 o	r less		0.	5 or les	ss		0.6 o	r less		0.4 o	r less	0.5 or less	
0.02	0.04	0.07	0.	.2	0.	32	0.0	63	1.17	1.25	1.39	1.45	2.05	0.05	0.13	0.39	
1.2	2.0	5.9	5.	.9	6	.9	12.0		20.0			29.0	3.9	5.5	7.6		
2.6	5.0	10.5	11	.3	17	17.2		30.0		51.0	68.0	75.0	84.0	8.4	11.5	21.0	
S									Stan	dard							
	Sp with J 0.049 h M10x1.0 h 7 c 0.135 s	Spring ret without adjudy of the without adj	Spring return without adjuster  J 0.049 0.098 0.294  M10x1.0 M12x1.0 M16x1.0  n 7 1  r 0.135 0.27 0.98  s 1.0  45  N 39 59 147  S 0.3 or less g 0.02 0.04 0.07  N 1.2 2.0 5.9  N 2.6 5.0 10.5	Spring return without adjuster  J 0.049   0.098   0.294   2.94   M10x1.0   M12x1.0   M16x1.0   M20   T 0.135   0.27   0.98   8.1   S 1.0   45   N 39   59   147   540   C 0.3 or less   C 0.02   0.04   0.07   0.0   N 1.2   2.0   5.9   5.0   N 2.6   5.0   10.5   11	Spring return without adjuster  J 0.049 0.098 0.294 2.94 5.88  M 10x1.0 M12x1.0 M16x1.0 M20x1.0  T 0.135 0.27 0.98 8.1 10.8  S 1.0 1.5  45 3  W 39 59 147 540 1000  G 0.3 or less 0.4 o  J 0.02 0.04 0.07 0.2  M 1.2 2.0 5.9 5.9  M 2.6 5.0 10.5 11.3	Spring return without adjuster  J 0.049 0.098 0.294 2.94 5.88 11.8  M10x1.0 M12x1.0 M16x1.0 M20x1.0 M20x1.0  T 0.135 0.27 0.98 8.1 10.8 21.6  S 1.0 1.5 2  45 30  N 39 59 147 540 1000 1400  O.3 or less 0.4 or less  J 0.02 0.04 0.07 0.2 0.  N 1.2 2.0 5.9 5.9 6  N 2.6 5.0 10.5 11.3 17	Spring return without adjuster         Spring return without adjuster           J 0.049   0.098   0.294   2.94   5.88   11.8   25.5           M10x1.0   M12x1.0   M16x1.0   M20x1.0   M25x1.5           T 0.135   0.27   0.98   8.1   10.8   21.6   39           S 1.0   1.5   2.0   30   25           A 39   59   147   540   1000   1400   3100   3	Spring return without adjuster         Spring ret without adjuster           J 0.049   0.098   0.294   2.94   5.88   11.8   25.5   63.7           M10x1.0   M12x1.0   M16x1.0   M20x1.0   M25x1.5   M30           T 0.135   0.27   0.98   8.1   10.8   21.6   39   78           S 1.0   1.5   2.0	0.005   0.01   0.03   0.3   0.6   1.2   2.6   6.5   8	0.005   0.01   0.03   0.3   0.6   1.2   2.6   6.5   8   12	0.005   0.01   0.03   0.3   0.6   1.2   2.6   6.5   8   12   20	0.005   0.01   0.03   0.3   0.6   1.2   2.6   6.5   8   12   20   30	0.005   0.01   0.03   0.3   0.6   1.2   2.6   6.5   8   12   20   30   40	0.005   0.01   0.03   0.3   0.6   1.2   2.6   6.5   8   12   20   30   40   60	Note   Note	No.005   0.01   0.03   0.3   0.6   1.2   2.6   6.5   8   12   20   30   40   60   0.25 M   0.5 M	

Note: Min. absorbed energy should be 1/5 of max. absorbed energy.

#### How to order



(B)

Series

1832





(B)



#### Shock absorber and other buffers

SCP\*3

CMK2

CMA2

SCM

SCG

SCA2

SCS2 CKV2

CAV2/ COVP/N2

SSD2

SSG

SSD

CAT

MDC2

MVC

\_\_\_\_

SMG

MSD/ MSDG

FC\*

STK

SRL3

SRG3

SRM3

SRT3

MRL2

MRG2

SM-25

ShkAbs

FJ

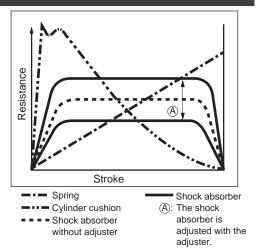
FK Spd

Contr Ending

## Shock absorber and other buffers

As shown at right:

- The spring accumulates energy and functions as spring return force at the stroke end.
- Cylinder cushion (single orifice connected to hydraulic cylinder) increases resistance sharply at collision and does not decelerate smoothly.
- Shock absorbers without adjuster have a preset level of energy that is absorbed and so working conditions are limited (SCK-00-0.03 or below).
- Shock absorbers with adjuster have roughly constant resistance throughout the stroke, uniformly decelerating the object's speed. The curve moves in parallel vertically when adjusted, and collision energy is absorbed appropriately.



Collision

SCP\*3

CMK2

CMA2

SCM

SCG

SCA<sub>2</sub>

SCS<sub>2</sub>

CKV2

CAV2/

COVP/N2

SSD2

SSG

SSD

CAT

MDC2

MVC

SMG MSD/

MSDG

FC\*

STK

SRL3

SRG3

SRM3

SRT3

MRL2

MRG2

SM-25

ShkAbs

FJ

FK

Spd

Contr

## Internal structure and operational explanation

#### ● SCK-00-0.005 Cannot be disassembled 00-0.01

## 00-0.03

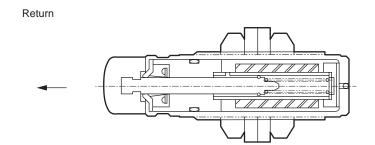
## Damper case Orifice Air chamber Damper Piston rod 1 Slit valve Cylinder Spring

#### Collision

Collision force applied to the damper pushes the piston rod and pressurizes oil in the cylinder. When the generated hydraulic pressure passes through the orifice and flows into the damper case, shock is absorbed.

Oil flowing into the damper case pressurizes the air chamber and decreases air chamber volume.

Note) With this product structure, internal pressure increases with workpiece speed during collision, generating resistance and absorbing energy. Resistance may thus appear low when pushed by hand, but the product is not defective.



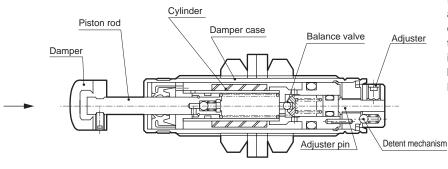
#### Return

When the colliding workpiece is removed, the piston rod is pushed out by the internal spring. At the same time, the slit valve (check valve) is opened by pressure in the air chamber. Oil flows to the inner pipe and at completion, the slit valve closes.

## SCK-00-0.3 to 60

## Cannot be disassembled

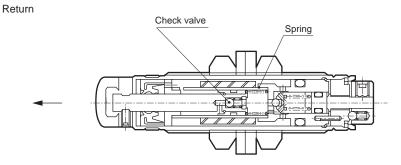
#### Collision



## Collision

Collision force applied to the damper pushes the piston via the piston rod and pressurizes oil in the cylinder. When the generated hydraulic pressure passes through the orifice and balance valve and flows into the damper case, shock is absorbed. When the adjuster is turned clockwise, the adjustable pin moves and the force of the balance valve spring increases. Oil flow is decreased and a larger colliding force can be withstood. Note) With this product structure, internal

pressure increases with workpiece speed during collision, generating resistance and absorbing energy. Resistance may thus appear low when pushed by hand, but the product is not defective.



## Return

When the colliding workpiece is removed, the piston rod is pushed out by the internal spring. At the same time, the check valve is opened by pressure in the air chamber. Oil flows to the inner pipe and at completion, the check valve closes.



SCP\*3

CMK2

CMA2

SCM

SCG

SCA2

SCS2

CKV2 CAV2/

COVP/N2 SSD2

MDC2

MVC

SMG

MSD/

MSDG FC\*

STK

SRL3

SRG3

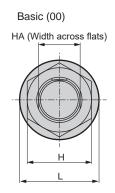
SRM3

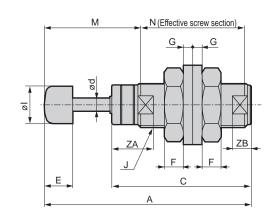
SRT3

## **Dimensions**



● SCK-00-0.005 0.03



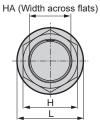


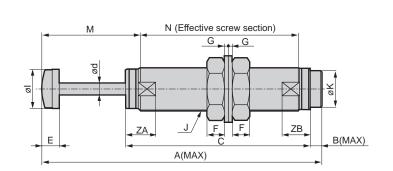
Code	Basic (00)															
Model No.	Α	С	Е	F	G	Н	I	J	L	М	N	d	HA	ZA	ZB	SSG
SCK-00-0.005	41.5	27	7	4	2	14	8	M10x1.0	18	21.3	18.5	3.0	9	9	4	
SCK-00-0.01	55	37	7.5	5	2.5	17	10	M12x1.0	21	25.5	27.5	3.5	11	11	5	SSD
SCK-00-0.03	70	49.5	10	6.5	2.5	22	14	M16x1.0	27	28.3	39.5	4.0	15	12	6	
			^					`		^			^			CAT

● SCK-00-0.3 to 60, 0.25 M to 1.0 M (Screw pitch (large))



Basic (00)





Code	Basic (00)														MDLO			
Model No.	Α	В	С	E	F	G	Н	I	J	K	L	M	N	d	НА	ZA	ZB	MRL2
SCK-00-0.3	94.6	5.8	66.8	11	8	2.9	27	16	M20x1.0	13.5	33	33.5	45.7	5	17	17.5	16	MRG2
SCK-00-0.6	94.6	5.8	66.8	11	8	2.9	27	16	M20x1.0	13.5	33	33.5	45.7	5	17	17.5	16	IVIRGZ
SCK-00-1.2	122.5	7.5	86	13	10	2.9	32	22	M25x1.5	19.5	39	40.5	65.4	6	24	21	18	SM-25
SCK-00-2.6	122.5	7.5	86	13	10	2.9	32	22	M25x1.5	19.5	39	40.5	65.4	6	24	21	18	3171-23
SCK-00-6.5	157.4	7.9	109.5	14	12	3.6	41	27	M30x1.5	23.5	50	51.5	89.4	8	27	21.5	19.5	ShkAbs
SCK-00-8	157.4	7.9	109.5	14	12	3.6	41	27	M30x1.5	23.5	50	51.5	89.4	8	27	21.5	19.5	SIIKAUS
SCK-00-12	175.6	10.5	123.1	16	16	3.6	50	36	M40x1.5	33.5	61	55.5	98.5	11	38	27.5	26	FJ
SCK-00-20	205.6	10.5	138.1	16	16	3.6	50	36	M40x1.5	33.5	61	70.5	113.5	11	38	27.5	26	1 3
SCK-00-30	257.1	10.5	169.6	16	16	3.6	50	36	M40x1.5	33.5	61	90.5	145	11	38	27.5	26	FK
SCK-00-40	277.1	10.5	179.6	16	16	3.6	50	36	M40x1.5	33.5	61	100.5	155	11	38	27.5	26	1 1
SCK-00-60	298.4	10.9	198.6	18	18	4.5	55	42	M45x1.5	37.5	67	102.9	172.5	12.5	43.5	31.5	30	Spd
SCK-00-0.25M	96.6	6.5	69.1	10	5.5	2.5	19	12	M14x1.5	10	24	26.1	53.5	4	12.4	10	15.5	Contr
SCK-00-0.5M	111.4	6.5	77.9	11	8	2.9	27	16	M20x1.5	13.5	33	33	60.8	5	17	12	17.5	Fig. alian at
SCK-00-1.0M	161.6	7.7	109.9	13	10	2.9	32	22	M27x3.0	19.5	39	50.5	90.3	6	24	15	22	Ending

## Dimensions: Option (flange [mounting bracket])

● SCK-0.005-\*\* CMK2 0.01 0.03

SCP\*3

CMA2

SCM

SCG

SCA2

SCS2

CKV2 CAV2/ COVP/N2 SSD2

SSG

SSD

CAT

MDC2

MVC

SMG MSD/ MSDG FC\*

STK

SRL3

SRG3

SRM3

SRT3

MRL2

MRG2

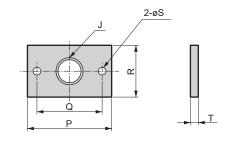
SM-25

ShkAbs

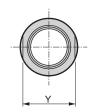
FJ

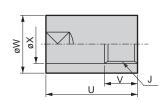
FΚ

Flange (FA)



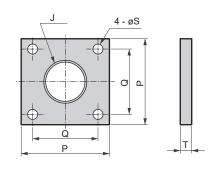
Stop nut (N1)



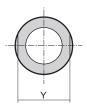


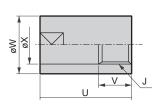
● SCK-0.3 to 60, 0.25M to 1.0M-\*\* (Screw pitch (large))

Flange (FA)



Stop nut (N1)

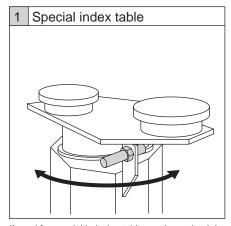




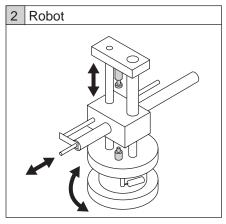
3	Code	Flange (FA)						Weight	Weight Stop nut (N1)									
4	Model No.	J	Р	Q	R	S	Т	(g)	J	U	٧	W	Х	Υ	(g)			
3	SCK-0.005-**	M 10 x 1.0	42	30	20	5.5	2.3	14	M 10 x 1.0	17	10	15	11	13	12			
4	SCK-0.01-**	M 12 x 1.0	46	34	20	5.5	3.6	22	M 12 x 1.0	23	10	19	13	17	19			
3	SCK-0.03-**	M 16 x 1.0	52	40	32	5.5	4.5	51	M 16 x 1.0	23	10	22	17	19	30			
4	SCK-0.3-**	M 20 x 1.0	52	38	-	6.5	6	107	M 20 x 1.0	32.5	15	26	21	24	52			
3	SCK-0.6-**	M 20 x 1.0	52	38	-	6.5	6	107	M 20 x 1.0	32.5	15	26	21	24	52			
4	SCK-1.2-**	M 25 x 1.5	52	38	-	6.5	6	100	M 25 x 1.5	35	15	32	26	30	82			
2	SCK-2.6-**	M 25 x 1.5	52	38	-	6.5	6	100	M 25 x 1.5	35	15	32	26	30	82			
$\dashv$	SCK-6.5-**	M 30 x 1.5	66	48	-	8.5	6	163	M 30 x 1.5	40	15	40	31	36	162			
2	SCK-8-**	M 30 x 1.5	66	48	-	8.5	6	163	M 30 x 1.5	40	15	40	31	36	162			
$\dashv$	SCK-12-**	M 40 x 1.5	84	64	-	10.5	9	390	M 40 x 1.5	69.5	20	50	41	46	362			
5	SCK-20-**	M 40 x 1.5	84	64	-	10.5	9	390	M 40 x 1.5	69.5	20	50	41	46	362			
	SCK-30-**	M 40 x 1.5	84	64	-	10.5	9	390	M 40 x 1.5	69.5	20	50	41	46	362			
3	SCK-40-**	M 40 x 1.5	84	64	-	10.5	9	390	M 40 x 1.5	69.5	20	50	41	46	362			
	SCK-60-**	M 45 x 1.5	84	64	-	10.5	9	390	M 45 x 1.5	70	20	60	46	55	649			
	SCK-0.25M-**	M 14 x 1.5	52	38	-	6.5	6	115	M 14 x 1.5	26.5	10	20	15	17	30			
	SCK-0.5M-**	M 20 x 1.5	52	38	-	6.5	6	108	M 20 x 1.5	36.5	15	26	21	24	59			
	SCK-1.0M-**	M 27 x 3.0	52	38	-	6.5	6	106	M 27 x 3.0	45.5	15	35	28	32	134			

Spd Contr

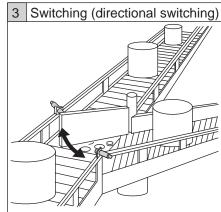
## Example of shock absorber



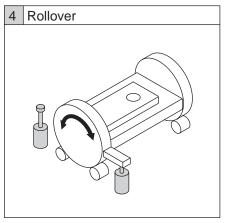
If used for special indexing tables such as wheel rim welding, etc., the index time can be reduced without damaging the machine.



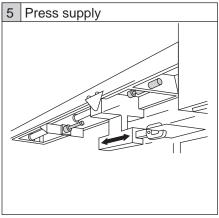
This absorbs the impact caused by the movement of various parts, and prevents damage to parts. Furthermore, production speed can be improved.



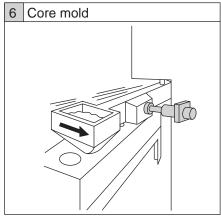
When used for defective parts inspection and sorting for shipping, this mechanism absorbs the gate bound impact and prevents damage to pneumatic cylinders, etc.



Can be used for automatic turn-over mechanism for parts after machining and welding, etc. Reduces wear and extends the service life of driving parts such as the drive, gears, pinion, etc.



Can be used with feeding mechanisms for parts leading to press machine dies (molds, stamps). Without reducing the supply speed of pneumatic cylinders, etc., the deceleration effects suited for the parts can be attained.



Can be used to stop the swing arm in the process that injects sand model material. This also increases cycles per unit time and supports increases in production.

SCP\*3

CMK2

CMA2

SCM

SCG

SCA2

SCS2

CKV2

CAV2/ COVP/N2

SSD2

SSG

SSD

CAT

MDC2

MVC

SMG

MSD/ MSDG

FC\*

STK

SRL3

SRG3

SRM3

SRT3

MRL2

MRG2

SM-25

**ShkAbs** 

FJ

FK Spd

Contr

## Selection guide

SCP\*3

CMK2

CMA2

SCM SCG

SCA<sub>2</sub>

SCS2 CKV2

CAV2/ COVP/N2

SSD2 SSG

SSD

CAT

MDC2 MVC

**SMG** 

MSD/

MSDG

FC\*

STK

SRL3

SRG3

SRM3

SRT3

MRL2

MRG2

SM-25

**ShkAbs** 

F.J

FK Spd Contr

Ending

## Selection guide

## Setting working conditions

Make the following conditions clear for shock absorber selection.

- (1) Load weight (kg)
- (2) Instantaneous colliding speed of impact with shock absorber(m/s)
- (3) Thrust (kgf) if there is external pressure with load

## Code

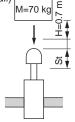
- D = Cylinder diameter (mm)
- E = Kinetic energy (J)
- P = Operation pressure (MPa)
- K = Radius of rotation (m) (distance of load center to center of rotation)
- $\omega$  = Colliding angular speed (rad/s)
- I = Moment of inertia (kg/m²)
- F = Thrust(N)
- $T = Torque (N \cdot m)$
- V = Colliding speed (m/s)
- H = Height (m)
- St = Shock absorber stroke (m)
- M = Weight of workpiece (kg)
- g = Gravity acceleration 9.8 m/s<sup>2</sup>

## **Example of calculation**

(1) Vertical falling motion (free fall)

$$E = \frac{1}{2} \cdot M \cdot V^2 + Mg \cdot St$$

Where weight (M) of workpiece is 70 kg and vertical fall is from 0.7 m (H), check if SCK-00-60 can be used.



Find the max. colliding speed under these conditions.

$$V = \sqrt{2 \cdot g \cdot H} = \sqrt{19.6 \times H}$$

$$V = \sqrt{19.6 \times 0.7} = 3.7 \text{ m/s} < 4 \text{ m/s}$$

(SCK-00-60)

$$E = \frac{1}{2}x70x3.7^2 + 70x9.8x0.07 = 527.2$$

Absorbed energy of SCK-00-60 is larger according to colliding speed characteristics graph of absorbed energy on Graph 1. Therefore, energy can be absorbed by SCK-00-60.

(2) Horizontal motion (inertia motion)

$$E = \frac{1}{2} \cdot M \cdot V^2$$

$$V=1.0 \text{ m/s}$$

$$M=10 \text{ kg}$$

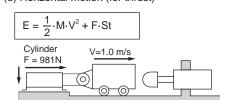
With workpiece weight (M) of 10 kg for colliding speed (V)

At 1.0m/s,

$$E = \frac{1}{2} \times 10 \times (1.0)^2 = 5.0 J$$

SCK-00-1.2 can be used.

(3) Horizontal motion (for thrust)



If the workpiece calculated in (2) is moved by a ø50 mm pneumatic cylinder (D) with pneumatic pressure (P) of 0.5 MPa, pneumatic cylinder thrust is:

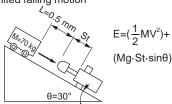
$$F = \frac{\pi}{4} \times D^2 \times P = \frac{\pi}{4} \times 50^2 \times 0.5 = 981N$$

Check if SCK-00-6.5 can be used.E=-

Therefore, energy can be absorbed by SCK-00-6.5.

(Graph 1)

(4) Tilted falling motion



When a 70 kgf workpiece comes down a 30° slope, When a 70 kgf workpiece with a radius of rotation (K) consider if the SCK-00-40 can be used. Find the max. colliding speed under the same conditions.

$$V = \sqrt{19.6xH(H=0.5xsin30^\circ)}$$
  
=  $\sqrt{19.6x0.5xsin30^\circ}$ 

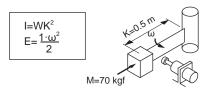
$$= 2.2 \text{ m/s} < 3 \text{ m/s}$$

$$E = (\frac{1}{2}x70x2.2^{2}) + (70x9.8x0.07xsin30^{\circ})$$

$$\approx 193.4 \text{ J}$$

Therefore, energy can be absorbed by SCK-00-20.

(5) Horizontal rotary motion (inertia motion)



0.5 m and colliding angular speed of 1 rad/s is being operated, consider if the SCK-00-1.2 can be used.I =

70 x 
$$(0.5)^2 = 17.5 \text{ kg·m}^2$$
  
 $(1)^2 = 17.5 \text{ x}(1)^2$   
 $E = 2 = 2$ 

=8.8 J

Therefore, energy can be absorbed by SCK-00-1.2.

