Sales of ECS-05 to ECS-12 will be terminated.

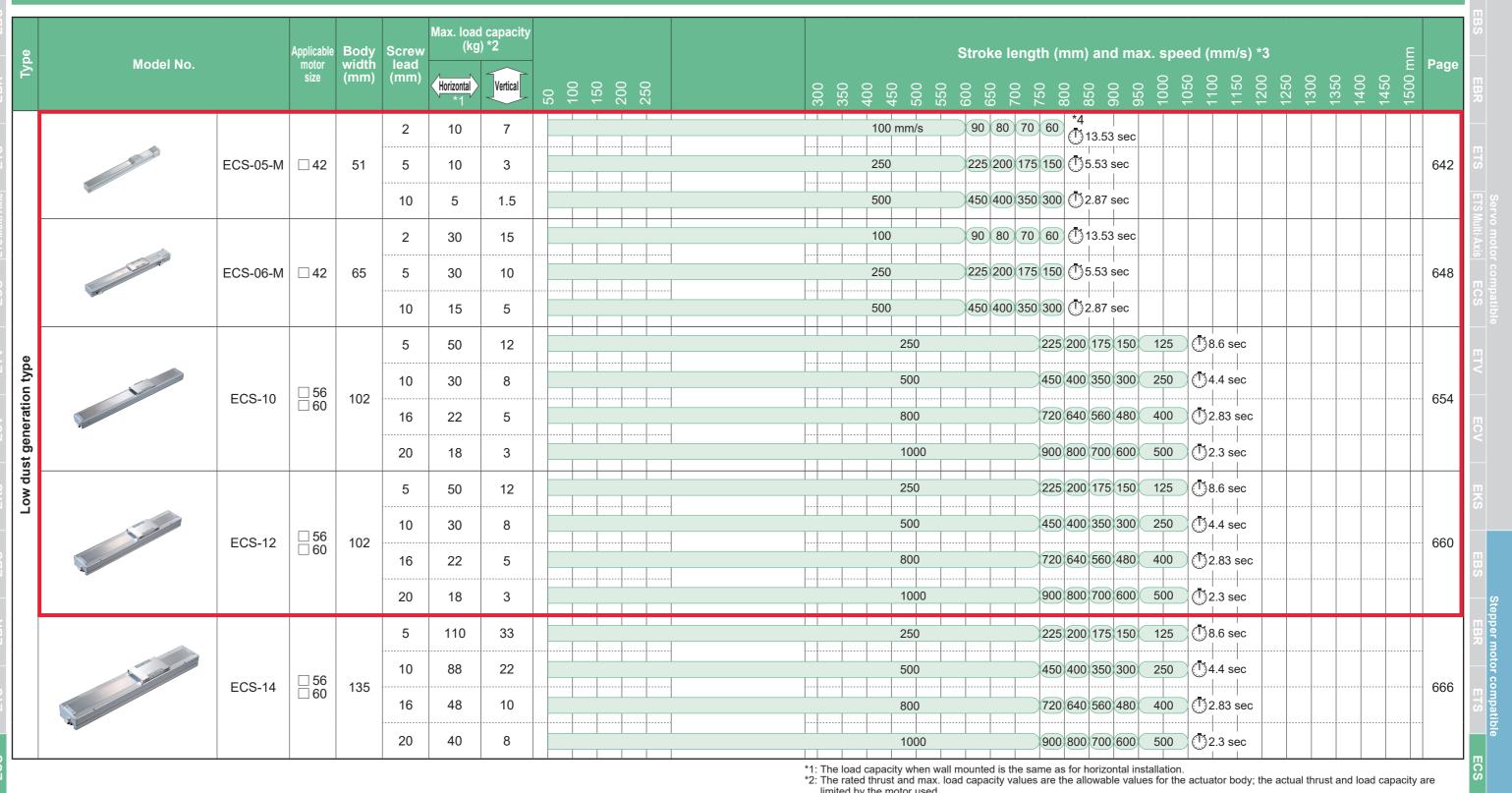
ECS

Stepper motor electric actuator Motorless specifications

Slider (ball screw drive low dust specifications)



	CONTENTS					
Produ	ct introduction	Intro				
Series	variation	638				
● Spe	ecifications/How to order/Dimensions					
· E	CS-05	642				
. E	CS-06	648				
. E	CS-10	654				
· Е(CS-12	660				
· E	CS-14	666				
Mo	del selection	672				
● Tec	Technical data					
♠ Saf	ety precautions	686				
Mode	Selection Check Sheet	708				



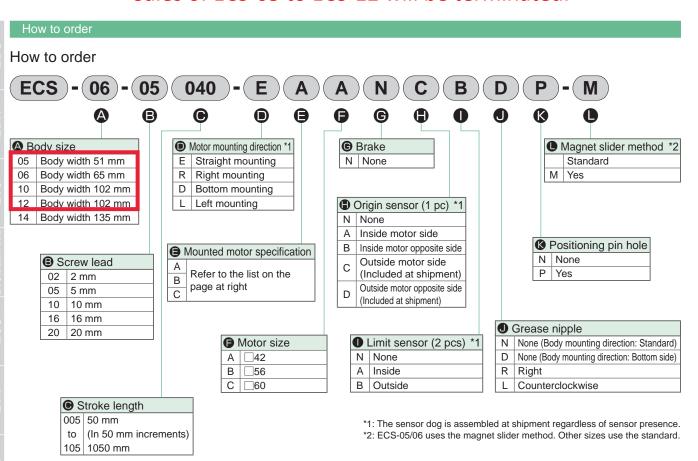
limited by the motor used.

^{*3:} The max. speed is the speed when the motor mounted by the customer can output a rotation speed of 3000 rpm.

The max. speed is restricted by the stroke. Do not move at speeds beyond the limit.

^{*4: (*)} shows the positioning time. Maximum stroke when installed horizontally and operated at max. speed and max. acceleration/deceleration. Note that this is not the value at maximum load capacity.

ECS series Sales of ECS-05 to ECS-12 will be terminated.



Example of model No.

ECS-06-05040-EAANCBDP-M

A Body size : 06 Series Screw lead : 5 mm Stroke length : 400 mm Motor mounting direction : Straight

Mounted motor specification : A (refer to the table on the page at right)

Motor size : 42 Brake : None

: External motor side Origin sensor

Limit sensor : Outside

Grease nipple : None (Body mounting method: Bottom side)

Positioning pin hole : Yes Magnet slider method : Yes

^{*}This product is composed of an actuator (and motor mounting parts) only; there is no motor attached. The user must prepare, mount, and adjust the motor and driver.

ECS Series

List of stepper motors recommended for mounting

List of stepper motors recommended for mounting

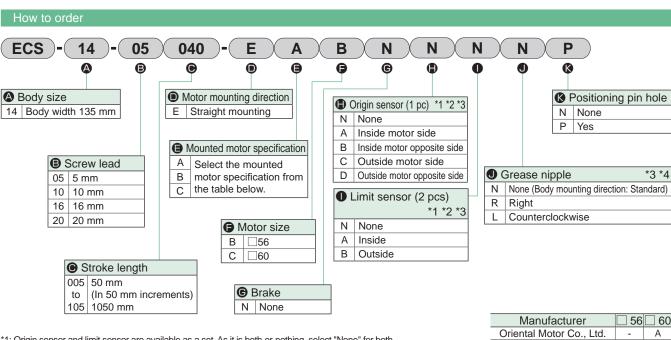
Code	Manufacturer	Series	□42	□56	□60	
Α	Oriental	AZ	AZM46⊡0⊡	-	AZM66_0_ AZM69_0_	
	Motor Co., Ltd.	AR	ARM46⊡0⊡	-	ARM66 <u></u> 0 ARM69 <u></u> 0	
В	MinebeaMitsumi Inc.	A17PM/A23KM	A17PM□□□□CSTBCN	A23KM□□□□CSTBCN	-	
В	Dyadic Systems	Dvadic Systems RMJ		-	-	
С	Co., Ltd.	RMJ	-	RMJ0611/RMJ1211	-	

Discontinued some variations Electric actuator Ball screw drive Slider Low dust specification

ECS-14 Series

Straight motor mounting

Stepper motor size: □56, □60



^{*1:} Origin sensor and limit sensor are available as a set. As it is both-or-nothing, select "None" for both.

^{*4: &}quot;Body mounting direction: Standard" here refers to mounting from the bottom side.

Stroke and max. spee	ed .	
		(mm/s)
Stroke length 100 to		

MinebeaMitsumi Inc.

Dyadic Systems Co., Ltd.

*Refer to page 641 for the motor model No.

В

С

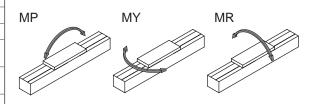
						(
Stroke length Screw lead	100 to 750	800	850	900	950	1050				
5	250	225	200	175	150	125				
10	500	450	400	350	300	250				
16	800	720	640	560	480	400				
20	1000	900	800	700	600	500				
*TI										

^{*}The max. speed is the speed when the motor mounted by the customer can output a rotation speed of 3000 rpm.

Allowable overhang length

*Refer to page 674 for details.

Moment direction



Applicable motor sizes □56, □60 stepper motor Drive method Ball screw ø16 Ball screw accuracy grade C7 Stroke length 50 to 1050 Screw lead mm 5 10 16 20 Max. load capacity Horizontal kg 110 88 48 40 Vertical kg 33 22 10 8 Max. speed 250 500 800 1000 mm/s Rated thrust *1 Ν 1388 694 433 Repeatability mm ±0.01 Lost motion 0.1 or less mm Drive system weight kg 1.6 Other inertia 0.074 ka-cm Coefficient of friction 0.05 Mechanical efficiency 0.8 Ball screw length Stroke + 200 Dynamic allowable load N 6567 Static allowable moment N·m MP: 552, MY: 551, MR: 485 Dynamic allowable moment N·m MP: 262.7, MY: 262.7, MR: 261.0 Operating ambient 0 to 40°C (no freezing) temperature, humidity 35 to 80% RH (no condensation) Storage ambient -10 to 50°C (no freezing) temperature, humidity 35 to 80% RH (no condensation) Atmosphere No corrosive gas, explosive gas, or dust

^{*2:} For sensor inside mounting, the user cannot adjust the position. (Assembled at shipment) For sensor outside mounting, the user can adjust the position. (Included at shipment)

^{*3:} Contact CKD to use the origin sensor, limit sensor and grease nipple in the same direction.

The max. speed is restricted by the stroke. Do not move at speeds beyond the

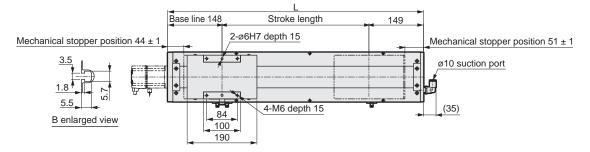
^{*1} The rated thrust and max. load capacity values are the allowable values for the actuator body; the actual thrust and load capacity are limited by the motor used.

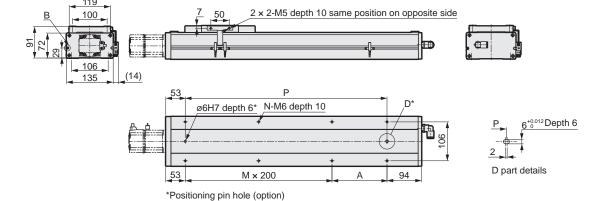
Dimensions/List of attachments

Dimensions Straight motor mounting

● ECS-14-****-E

· Refer to page 680 for grease nipple dimensions.

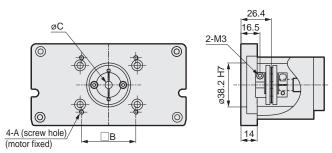


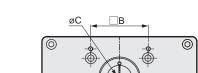


Stroke length (mm)	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000	1050
L	347	397	447	497	547	597	647	697	747	797	847	897	947	997	1047	1097	1147	1197	1247	1297	1347
Α	200	50	100	150	200	50	100	150	200	50	100	150	200	50	100	150	200	50	100	150	200
M	0	1	1	1	1	2	2	2	2	3	3	3	3	4	4	4	4	5	5	5	5
N	4	6	6	6	6	8	8	8	8	10	10	10	10	12	12	12	12	14	14	14	14
Р	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000	1050	1100	1150	1200
Weight (kg)	10.5	11.1	11.7	12.3	12.9	13.5	14.1	14.7	15.3	15.9	16.5	17.1	17.7	18.3	18.9	19.5	20.1	20.7	21.3	21.9	22.5

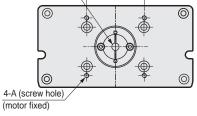
Motor mounting part

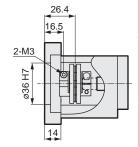
● ECS-14-E (☐ 56)





● ECS-14-E (☐ 60)





Mounted motor	or specification	Α	В	С	Motor mounting bolt
А	□60	M4 depth 14	50	10	4-M4 × L16
В	□56	M4 depth 14	47.14	6.35	4-M4 × L16
С	□56	M4 depth 14	47.14	8	4-M4 × L16

[Motor mounting parts]

[311				
Mounted motor	Coupling	Fitting	Motor	Motor mou	unting bolt
specification		Fitting	size	Size	Quantity
А				M4	4
В	Assembled at shipment	Included at shipment	□56 □60	M4	4
С	at omprion	at ompriorit		M4	4

^{*}Refer to page 682 for fitting details.

Manufacturer	Model	Quantity
OMRON Corporation	EE-SX672	3

^{*}Refer to page 678 for sensor specifications.

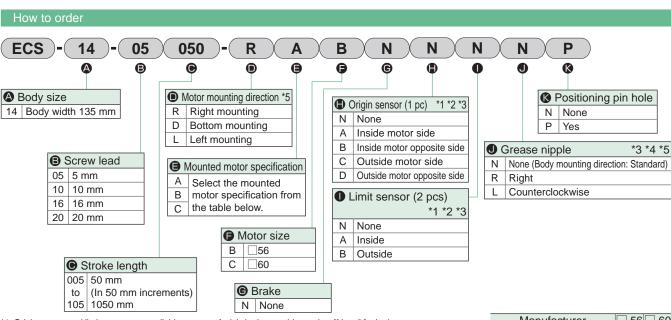
Discontinued some variations

Electric actuator Ball screw drive Slider Low dust specification

ECS-14 Series

Motor side mounting (left, right, bottom)

Stepper motor size: □56, □60



- *1: Origin sensor and limit sensor are available as a set. As it is both-or-nothing, select "None" for both.
- *2: For sensor inside mounting, the user cannot adjust the position. (Assembled at shipment)
- For sensor outside mounting, the user can adjust the position. (Included at shipment)
 *3: Contact CKD to use the origin sensor, limit sensor and grease nipple in the same direction.
- *4: "Body mounting direction: Standard" here refers to mounting from the bottom side.
- *5: When selecting motor mounting direction R, grease nipple R cannot be selected. When selecting L, grease nipple L cannot be selected.

Manufacturer	□ 56	□ 60
Oriental Motor Co., Ltd.	-	Α
MinebeaMitsumi Inc.	В	-
Dyadic Systems Co., Ltd.	С	-

^{*}Refer to page 641 for the motor model No.

Spe	ecification	าร								
Applic	able moto	r sizes	□56, □60 stepper motor							
Drive	method		Ball screw ø16							
Ball so	crew accu	racy grade	C7							
Stroke	length	mm		50 to	1050					
Screw	lead	mm	5	10	20					
Max. lo	ad capacity	Horizontal kg	110	88	48	40				
	*1	Vertical kg	33	22	10	8				
Max. s	speed	mm/s	250	500	800	1000				
Rated	thrust *1	N	1388	694	433	347				
Repea	atability	mm	±0.01							
Lost m	notion	mm	0.1 or less							
Drive :	system we	eight kg	1.6							
Other	inertia	kg-cm ²	0.870							
Coeffic	cient of fri	ction	0.05							
Mecha	anical effic	eiency	0.8							
Ball so	crew lengt	h		Stroke	+ 200					
Dynan	nic allowa	ble load N		65	67					
Static a	allowable m	oment N⋅m	М	P: 552, MY:	551, MR: 4	85				
Dynami	c allowable r	moment N⋅m	MP:	262.7, MY: 2	262.7, MR: 2	261.0				
	ting ambio rature, hu		35 to	0 to 40°C (r 80% RH (r		ation)				
	ge ambien rature, hu			10 to 50°C 80% RH (r						
Atmos	phere		No corro	sive gas, ex	cplosive gas	, or dust				

^{*1} The rated thrust and max. load capacity values are the allowable values for the actuator body; the actual thrust and load capacity are limited by the motor used.

Stroke and max. speed

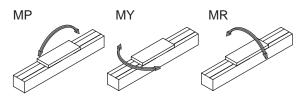
(mm/s)

						, ,
Stroke length Screw lead	100 to 750	800	850	900	950	1050
5	250	225	200	175	150	125
10	500	450	400	350	300	250
16	800	720	640	560	480	400
20	1000	900	800	700	600	500

^{*}The max. speed is the speed when the motor mounted by the customer can output a rotation speed of 3000 rpm.

Allowable overhang length

*Refer to page 674 for details.

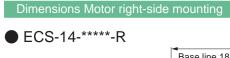


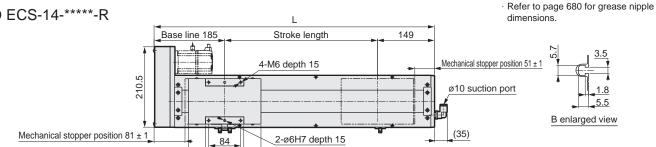


The max. speed is restricted by the stroke. Do not move at speeds beyond the

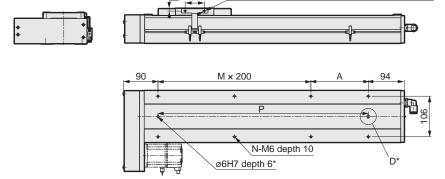
Discontinued some variations ECS-14 Series

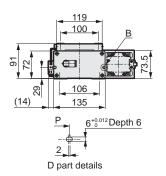
Dimensions/List of attachments





2 x 2-M5 depth 10 same position on opposite side



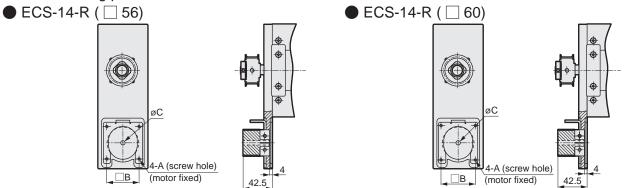


*Positioning pin hole (option)

100

Stroke length (mm)	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000	1050	r
L	384	434	484	534	584	634	684	734	784	834	884	934	984	1034	1084	1134	1184	1234	1284	1334	1384	Ġ
Α	200	50	100	150	200	50	100	150	200	50	100	150	200	50	100	150	200	50	100	150	200	
М	0	1	1	1	1	2	2	2	2	3	3	3	3	4	4	4	4	5	5	5	5	
N	4	6	6	6	6	8	8	8	8	10	10	10	10	12	12	12	12	14	14	14	14	
Р	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000	1050	1100	1150	1200	G
Weight (kg)	11.0	11.6	12.2	12.8	13.4	14.0	14.7	15.3	15.9	16.5	17.1	17.8	18.4	19.0	19.6	20.2	20.9	21.5	22.1	22.7	23.3	1

Motor mounting part



Mounted motor	or specification	А	В	С	Motor mounting bolt
А	□60	M4	50	10	4-M4 × L20
В	□56	M4	47.14	6.35	4-M4 × L20
С	□56	M4	47.14	8	4-M4 × L20

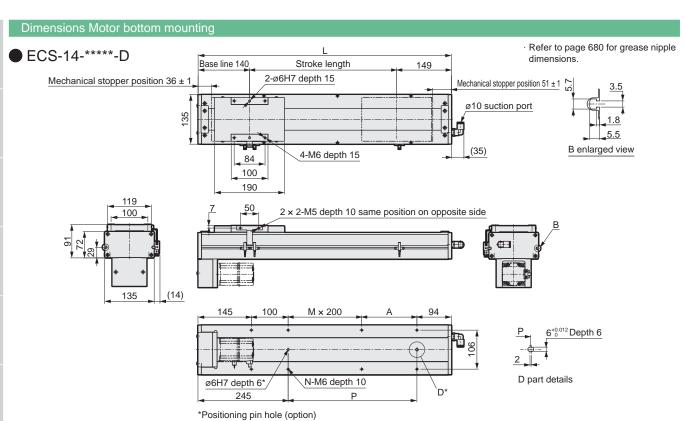
[Motor mounting parts]

•	01 1						
Mounted motor	Timing	Fitting	Motor	Motor mounting bolt			
specification	belt, pulley	Fitting	size	Size	Quantity		
Α		Included		M4	4		
В	Included at shipment	at	□56 □60	M4	4		
С	opo	shipment		M4	4		

^{*}Refer to page 682 for fitting details.

Manufacturer	Model	Quantity
OMRON Corporation	EE-SX672	3

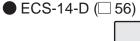
^{*}Refer to page 678 for sensor specifications.

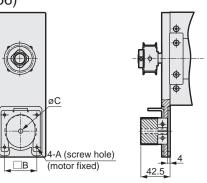


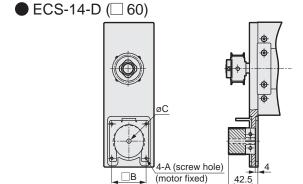
Stroke length (mm) 50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000	1050
L	339	389	439	489	539	589	639	689	739	789	839	889	939	989	1039	1089	1139	1189	1239	1289	1339
А	0	50	100	150	200	50	100	150	200	50	100	150	200	50	100	150	200	50	100	150	200
М	0	0	0	0	0	1	1	1	1	2	2	2	2	3	3	3	3	4	4	4	4
N	4	6	6	6	6	8	8	8	8	10	10	10	10	12	12	12	12	14	14	14	14
Р	0	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000
Weight (F	(g) 11.0	11.6	12.2	12.8	13.4	14.0	14.7	15.3	15.9	16.5	17.1	17.8	18.4	19.0	19.6	20.2	20.9	21.5	22.1	22.7	23.3

Round positioning pin holes are available only for stroke 50.

Motor mounting part







Mounted motor	or specification	А	В	С	Motor mounting bolt
А	□ 60	M4	50	10	4-M4 × L20
В	□ 56	M4	47.14	6.35	4-M4 × L20
С	□ 56	M4	47.14	8	4-M4 × L20

List of attachments

[Motor mounting parts]

[IVIOLOI IIIOUIILII	ig partsj				
Mounted motor	Timing	Fitting	Motor	Motor mou	unting bolt
specification	belt, pulley	Fitting	size	Size	Quantity
А				M4	4
В	Included at shipment	Included at shipment	□ 56 □ 60	M4	4
С	2		_ 00	M4	4

Manufacturer	Model	Quantity
OMRON Corporation	EE-SX672	3

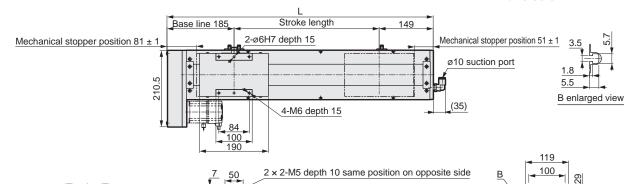
^{*}Refer to page 678 for sensor specifications.

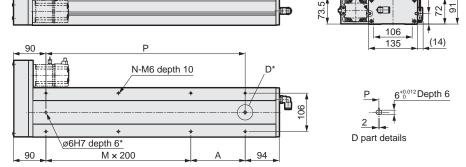
^{*}Refer to page 682 for fitting details.

Dimensions Motor left-side mounting

ECS-14-****-L

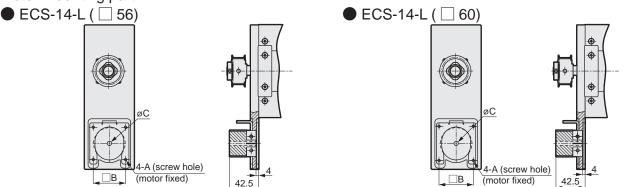
· Refer to page 680 for grease nipple dimensions.





S	troke length (mm)	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000	1050	ŀ
	L	384	434	484	534	584	634	684	734	784	834	884	934	984	1034	1084	1134	1184	1234	1284	1334	1384	G
	Α	200	50	100	150	200	50	100	150	200	50	100	150	200	50	100	150	200	50	100	150	200	h
	М	0	1	1	1	1	2	2	2	2	3	3	3	3	4	4	4	4	5	5	5	5	
	N	4	6	6	6	6	8	8	8	8	10	10	10	10	12	12	12	12	14	14	14	14	
	Р	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000	1050	1100	1150	1200	G
\	Veight (kg)	11.0	11.6	12.2	12.8	13.4	14.0	14.7	15.3	15.9	16.5	17.1	17.8	18.4	19.0	19.6	20.2	20.9	21.5	22.1	22.7	23.3	

Motor mounting part



Mounted motor specification		А	В	С	Motor mounting bolt
А	□60	M4	50	10	4-M4 × L20
В	□56	M4	47.14	6.35	4-M4 × L20
С	□56	M4	47.14	8	4-M4 × L20

[Motor mounting parts]

Mounted motor	Timing	Fitting	Motor	Motor mo	unting bolt
specification	belt, pulley	1 Ittilig	size	Size	Quantity
А				M4	4
В	Included at shipment	Included at shipment	□56 □60	M4	4
С	op	at ompriorit		M4	4

^{*}Refer to page 682 for fitting details.

Manufacturer	Model	Quantity
OMRON Corporation	EE-SX672	3

^{*}Refer to page 678 for sensor specifications.

EBS

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ervo motor compat

Model selection

STEP 1 Confirming load capacity

Load capacity varies with mounting orientation, screw lead and motor performance.

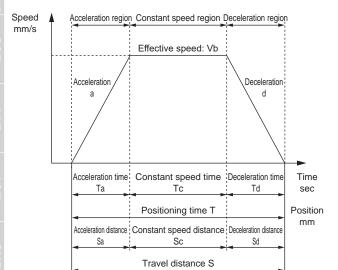
Refer to the selection table (page 638) and the specification table for each model to select the size and screw lead.

For motor performance, contact the motor manufacturer. For motor selection, use the actuator information (mechanical efficiency, etc.) in the specifications.

STEP 2 Confirming positioning time

Calculate the positioning time of the selected product according to the following example and confirm that the required tact is achievable.

Select the speed and acceleration/deceleration from the specification table for each model and the motor selected by the customer.



	Description	Codo	Unit	Bomorko
	Description	Code	Unit	Remarks
	Set speed	V	mm/s	
Set	Set acceleration	а	mm/s ²	
value	Set deceleration	d	mm/s ²	
	Travel distance	S	mm	
	Achieved speed	Vmax	mm/s	= $\{2 \times a \times d \times S/(a + d)\}^{1/2}$
	Effective speed	Vb	mm/s	Smaller of V and Vmax
	Acceleration time	Ta	S	= Vb/a [0.2 sec or more]
	Deceleration time	Td	S	= Vb/d [0.2 sec or more]
Calculated value	Constant speed time	Tc	S	= Sc/Vb
Value	Acceleration distance	Sa	mm	$= (a \times Ta^2)/2$
	Deceleration distance	Sd	mm	$= (d \times Td^2)/2$
	Constant speed distance	Sc	mm	= S - (Sa + Sd)
	Positioning time	Т	S	= Ta + Tc + Td

^{*}Do not use at speeds that exceed the specifications.

STEP 3 Confirming allowable overhang length

Make sure that the load overhang length during operation is within the allowable range (pages 674 to 676).

Contact CKD for selection details.

^{*}The acceleration and deceleration settings related to the acceleration time and deceleration time change depending on the set speed and stroke. *Depending on acceleration/deceleration and stroke length, the trapezoid speed waveform may not be formed (the set speed may not be achieved). In this case, select the effective speed (Vb) from the set speed (V) and the achieved speed (Vmax), whichever is smaller.

^{*}Use with acceleration time/deceleration time of 0.2 sec or longer.

^{*1} G ≈ 9.8 m/s

^{*}Set the speed and acceleration/deceleration by the motor selected by the customer. For motor selection and calculation of speed and acceleration/ deceleration, use the actuator information (mechanical efficiency, etc.) in the specifications.

ECS Series

Model selection

MEMO

BS

70

<u>п</u>

ETS Multi-Ax

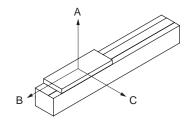
s ECS

ETV

ECS series Sales of ECS-05 to ECS-12 will be terminated.

Allowable overhang length (ECS Series)

[When installed horizontally]



[Allowable overhang length]

● ECS-05

Motor	Acceleration/deceleration time	Screw lead		Overhang mm		
mounted	sec			Α	В	С
	0.2	2	5	750	45	105
			10	350	20	47
Straight		5	4	480	45	105
side/bottom		5	7	300	25	55
		10	3	300	55	110
		10	5	180	30	65

● ECS-06

Motor mounted	Acceleration/deceleration time	Screw	Weight kg	Ove	Overhang mm			
	sec	lead		Α	В	С		
	0.2	2	10	400	65	150		
		2	30	150	15	40		
Straight		5	10	520	50	110		
/			30	130	10	25		
side/bottom			3	800	145	330		
		10	8	280	50	120		
			15	140	23	55		

ECS-10

Motor	Motor Acceleration/deceleration time Screw		Weight	Ove	rhang mm	
mounted	sec lead	kg	Α	В	С	
		5	30	560	50	50
		5	50	310	27	27
	0.2		15	440	90	90
		10	25 30	250	50	50
Straight				200	40	40
/		16	5	950	270	230
side/bottom			10	480	130	110
			22	200	55	45
			5	750	250	200
		20	10	370	120	95
			15	240	80	60

● ECS-12

Motor			Weight	Overhang mm			
mounted	ounted sec lead	kg	Α	В	С		
		5	30	900	70	80	
		э	50	420	30	40	
	Straight , 0.2	10	15	900	150	160	
			25	490	80	85	
Straight			30	400	60	70	
/			5	1700	430	450	
side/bottom		16	10	800	200	220	
			22	330	80	85	
			5	1200	420	400	
		20	10	580	200	190	
			15	370	120	120	

● ECS-14

Motor	Acceleration/deceleration time	Screw	Weight	Ove	rhang	mm	
mounted	sec	lead		kg	Α	В	С
			60	2300	250	240	
		5	80	1600	180	170	
			95	1150	145	140	
	0.2		30	2000	500	450	
		10	50 75	1400	280	250	
Straight				1000	170	160	
side/bottom			10	2200	1200	1000	
		16	20	1600	600	500	
			44	800	260	220	
			10	2300	1200	1000	
		20	20	1400	600	500	
			35	1000	330	290	

^{*}The above values are the allowable values for the actuator body; the actual load capacity is limited by the motor used.

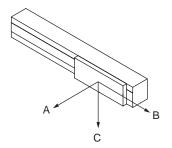
Use overhang length up to the center of gravity of the load within A, B and C directions.

load capacity is limited by the motor used. *When suspending from above, use 1/3 of the dynamic allowable load, dynamic allowable moment, and overhang length.

Sales of ECS-05 to ECS-12 will be terminated. ECS series

Allowable overhang length (ECS Series)

[When wall-mounted]



[Allowable overhang length]

● ECS-05

Motor	Acceleration/deceleration time sec	Screw lead	rew Weight	Overhang mm		
mounted			kg	Α	В	С
	0.2	2	5	105	45	750
			10	47	20	350
Straight		_	4	100	45	450
side/bottom		5	7	55	23	240
		10	3	110	55	400
		10	5	60	30	230

ECS-06

Motor Acceleration/deceleration ti			Weight kg	Overhang mm		
mounted	mounted sec lead	Α		В	С	
	Straight / 0.2 ide/bottom	2	15	110	42	400
		2	30	45	15	180
		5 1	5	240	95	1150
Straight			10	115	50	540
side/bottom			30	25	10	140
0.00/2010111			3	320	150	700
		10	8	110	50	250
			15	50	25	120

● ECS-10

Motor	Acceleration/deceleration time	Screw	Weight	Ove	rhang	mm
mounted	sec	lead	kg	Α	В	С
	0.2		10	160	160	1400
		5	20	75	75	650
			30	45	45	400
			10	130	140	690
		10	20	60	65	330
Straight			30	40	40	210
side/bottom			5	230	250	750
		16	10	110	120	370
			22	45	50	160
			5	220	250	650
		20	10	105	120	320
			15	65	75	210

● ECS-12

Motor	Acceleration/deceleration time	celeration/deceleration time Screw		Ove	rhang	mm
mounted	sec	lead	Weight kg	Α	В	С
			10	330	270	2200
		5	20	145	120	1000
			30	90	70	600
		10	260	240	850	
		10	20	115	110	520
Straight	0.2		30	70	60	300
side/bottom	0.2		5	450	450	1300
		16	10	210	210	600
			22	80	80	240
			5	410	410	1200
		20	10	190	195	600
			15	120	120	390

● ECS-14

Motor	Acceleration/deceleration time	Screw	Weight	Ove	rhang	mm		
mounted	sec	lead	lead	lead	kg	Α	В	С
			60	240	250	1600		
		5	80	170	180	1200		
			95	140	145	1050		
		10	30	420	460	1500		
			50	240	250	1000		
Straight	0.2		75	150	160	700		
side/bottom	0.2		10	1050	1200	2650		
		16	20	500	620	1450		
					270	800		
			10	1000	1200	1900		
		20	20	500	600	1000		
			35	270	300	600		

^{*}The above values are the allowable values for the actuator body; the actual load capacity is limited by the motor used.

Stepper motor compatible

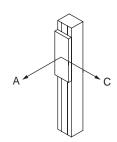
^{*}When suspending from above, use 1/3 of the dynamic allowable load, dynamic allowable moment, and overhang length.

Use overhang length up to the center of gravity of the load within A, B and C directions.

ECS series Sales of ECS-05 to ECS-12 will be terminated.

Allowable overhang length (ECS Series)

[When installed vertically]



[Allowable overhang length]

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Motor mounted	Acceleration/deceleration time	Screw	Weight kg	Overhang mm	
	sec	lead		Α	С
Straight / side/bottom		2	3	80	80
	0.2	2	7	35	35
		5	3	65	65
		10	1.5	120	120

ECS-06

Motor	Acceleration/deceleration time			ng mm		
mounted	sec	lead	kg	Α	С	
Straight / side/bottom		2 5	160	160		
			15	53	53	
			2 300	300		
	0.2	5	4	150	150	
	0.2		10	60	60	
			1	410	410	
		10	2	205	205	
			5	82	82	

● ECS-10

Motor	Acceleration/deceleration time	Screw			ing mm
mounted	sec	lead	kg	Α	С
			5 310 310		
		5	10	155	155
			12	130	130
			4	360	360
		10	6	240	240
Straight	0.2		8	180	180
side/bottom	0.2		1	1050	1050
		16	2	155 130 360 240 180 1050 525 210 850	525
			5	210	210
			1	850	850
		20	2	425	425
			3	283	283

● ECS-12

Motor	Acceleration/deceleration time	Screw Weight Overham Read kg A 5 600		ing mm	
mounted	sec			Α	С
			5	600	600
		5	10	300	300
Straight / side/bottom			12	250	250
			4	650	650
	0.2	10	6	430	430
	0.2		8	320	320
			1	1050	1050
		16	2	525	525
			5	210	210
		20	3	650	700

● ECS-14

Motor	Acceleration/deceleration time	Odiow Wolgin		ing mm	
mounted	nounted sec		kg	Α	С
			20	755	755
		5	25	605	605
			27	560	560
			10	1350	1350
Straight	0.2	10	15	900	900
side/bottom	0.2		18	750	750
			2	2400	2400
		16	4	1700	5 755 6 605 0 560 0 1350 0 900 0 750 0 2400 0 1700 0 1300
			7	1300	1300
		20	6	1200	1200

^{*}The above values are the allowable values for the actuator body; the actual

Stepper motor compatible

load capacity is limited by the motor used.

*When suspending from above, use 1/3 of the dynamic allowable load, dynamic allowable moment, and overhang length.

Use overhang length up to the center of gravity of the load within A, B and C directions.

ECS Series

Technical data

MEMO

BS

EBR

70

E C

ETS Multi-Ax

ECS

ETV

ПВ

FRR.

ETS

ECS

Safety

ECS Series

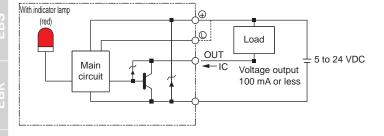
Origin sensor, limit sensor

	Manufacturer	Model
External mounted sensor	OMRON Corporation	EE-SX672
Internal mounted sensor	OMRON Corporation	EE-SX674

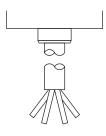
Performance

Item	Specifications
Hysteresis	0.025 mm or less
Light source (peak emission wavelength)	GaAs infrared LED (940 nm)
Indicator lamp	ON when receiving light (red)
Power supply voltage	5 to 24 VDC ±10% ripple (P-P) 10% or less
Current consumption	35 mA or less (NPN)
Control output	NPN: NPN open collector output 5 to 24 VDC 100 mA or less OFF state current 0.5 mA or less Residual voltage 0.8 V or less (at load current 100 mA) Residual voltage 0.4 V or less (at load current 40 mA)
Operating ambient illumination	Light-receiving surface luminance Fluorescent light: 1,000 lx or less
Ambient temperature range	When operating: -25 to +55°C When stored: -30 to +80°C (no condensation or freezing)
Ambient humidity range	When operating: 5 to 85% RH When stored: 5 to 95% RH (no condensation or freezing)
Degree of protection	IP50 IEC 60529 Standards
Cord length	2 m (Connector with cord [EE-1006 2M])

Output circuit



Wiring diagram



Terminal layout

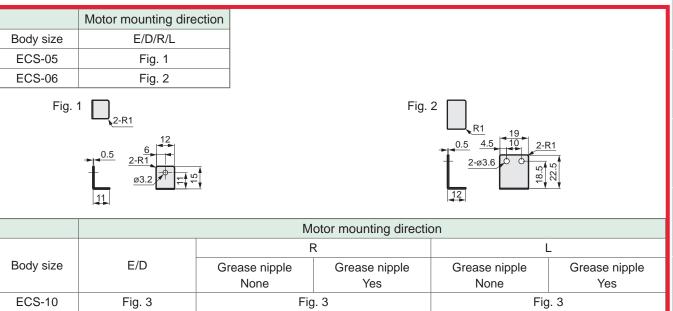
Brown	5 to 24 VDC
Pink	L
Blue	0 V
Black	OUTPUT

Fig. 5

2-ø5.6

52

ECS-12



	Motor mounting direction				
		F	3	ı	L
Body size	E/D	Grease nipple	Grease nipple	Grease nipple	Grease nipple
		None	Yes	None	Yes
ECS-14	Fig. 6	Fig. 6	Fig. 7	Fig. 6	Fig. 7

Fig. 4

Fig. 3

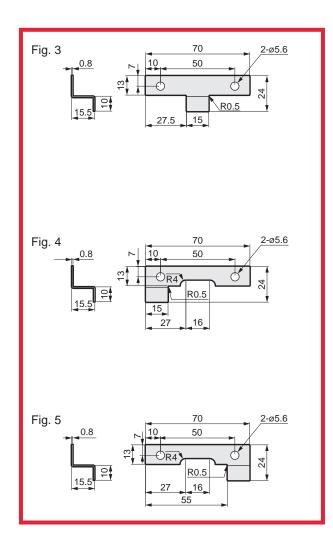


Fig. 3

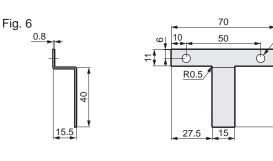
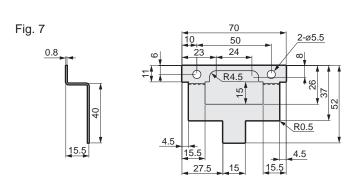


Fig. 3

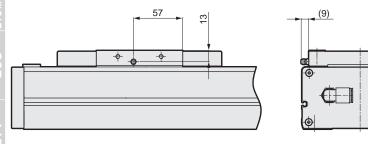


Stepper motor compatible EBR ETS

ECS series Sales of ECS-05 to ECS-12 will be terminated.

Grease nipple dimensions *Horizontally symmetrical against the actuator. ● ECS-10 ● ECS-12

● ECS-14



ECS Series

Grease nipple dimensions

MEMO

BS

EBR

ETS

ETS Multi-Axis

ECS

ETV

ППО

FRR.

ETS

ECS series Sales of ECS-05 to ECS-12 will be terminated.

Basic

Motor mounting bolt (common motor mounting direction)

Model No.	Mounted motor specification	Motor size	Size	Quantity
ECS-05	A	□42	M3	4
ECS-06	В	<u></u> 42	M3	4
ECS-10 ECS-12 ECS-14	A	□56 □60	M4	4
	В		M4	4
	С	□00	M4	4

By motor mounting direction

Model No.	Attachment name	Included quantity
E (external direct mounting)	Coupling (Assembled at shipment)	1
R (right-side mounting)	Timing belt	1
L (left-side mounting) D (bottom mounting)	Pulley	1

When origin/limit sensor is selected *1

Sensor mounting direction	Shipping format	Quantity
Inner sensor	Fixed position assembled at shipment	3 *2
Outer sensor	Included at shipment *3	3 2

- *1 Shipping format varies according to whether origin sensor and limit sensor are assembled inside or outside.
- *2 When "None" is selected for origin sensor or limit sensor, the other sensor is also "None".
- *3 Sensor mounting screws are also included.

Suction port fitting

Model No.	Fitting model No.	Shipping format	Quantity
ECS-05/ECS-06	GWL6-M5	Assembled at shipment	2
ECS-10 to ECS-14	GWL10-8	Included at shipment	1

CKD

Maintenance parts

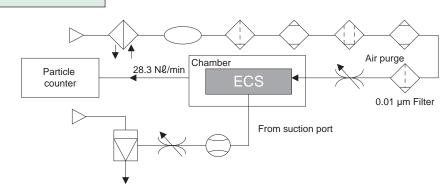
Maintenance parts

Maintenance parts (external mounted sensor)

Basic price mode	Compatibility	Part
ETS-22008-000		Body
ETS-22008-000	All models 006	Cable

Dust generation characteristics Reference data

Test circuit



Measuring method

- (1) Set a test sample in the acrylic resin chamber.
- (2) Supply clean air at the same flow rate as the particle counter intake rate (28.3 N \(\mathbb{Q} \) /min).
- (3) Place the chamber in an ISO class 4 (class 10) clean bench.
- (4) Activate the test sample, and measure changes in particle concentration over time during the specified measurement time.
- (5) Test sample operating speed

Measuring conditions

Item		Description
Test sample	Model No.	Operating speed 400 mm/sec for ECS-06-10040
	iviodei No.	Operating speed 800 mm/sec for ECS-14-20040
	Acceleration/deceleration time	0.3 sec
	Air intake	40.0 N ℓ /min for ECS-06-10040
		60.0 N ℓ /min for ECS-14-20040
Chamber	Internal capacity	28.3 N ℓ
Particle counter	Name	Laser dust monitor
	Min. measurable particle diameter	0.1 μm
	Intake	28.3 N & /min
Setting conditions	Sampling	10 min
	Interval	40 min
	Measurement time	50 h

Dust generation data

The values in the data are measured values under the above conditions, and are not guaranteed.

