

DIGITAL ELECTRO-PNEUMATIC REGULATOR

EVD-1000/3000 Series IO-Link Type

INSTRUCTION MANUAL

SM-A20758-A/4



- Read this Instruction Manual before using the product.
- In particular, read the safety notes carefully.
- Keep this Instruction Manual in a safe and convenient place for future reference.

PREFACE

Thank you for purchasing CKD's **"EVD-1000/3000 Series IO-Link Type" digital electro-pneumatic regulator**.

This Instruction Manual contains basic matters such as installation and usage instructions in order to ensure optimal performance of the product. Please read this Instruction Manual thoroughly and use the product properly.

Keep this Instruction Manual in a safe place and be careful not to lose it.

Product specifications and appearances presented in this Instruction Manual are subject to change without notice.

- The product is intended for users who have basic knowledge about materials, piping, electricity, and mechanisms of pneumatic components. CKD shall not be responsible for accidents caused by persons who selected or used the product without knowledge or sufficient training.
- Since there are a wide variety of customer applications, it is impossible for CKD to be aware of all of them. Depending on the application or usage, the product may not be able to exercise its full performance or an accident may occur due to fluid, piping, or other conditions. It is the responsibility of the customer to check the product specifications and decide how the product shall be used in accordance with the application and usage.

SAFETY INFORMATION

When designing and manufacturing any device incorporating the product, the manufacturer has an obligation to ensure that the device is safe. To that end, make sure that the safety of the machine mechanism of the device, the pneumatic control circuit, and the electric system that controls such mechanism is ensured.

Ensure to observe organization's standards, laws and regulations etc. for safety related to design and management of the equipment.

ISO 4414 and JIS B 8370 (the latest edition of each standard)

In order to use our products safely, it is important to select, use, handle, and maintain the products properly.

Observe the warnings and precautions described in this Instruction Manual to ensure device safety.

Although various safety measures have been adopted in the product, customer's improper handling may lead to an accident. To avoid such a situation,

Thoroughly read and understand this Instruction Manual
before using the product.

To explicitly indicate the severity and likelihood of a potential harm or damage, precautions are classified into three categories: "DANGER", "WARNING", and "CAUTION".

| | |
|--|---|
|  DANGER | Indicates an imminent hazard. Improper handling will cause death or serious injury to people. |
|  WARNING | Indicates a potential hazard. Improper handling may cause death or serious injury to people. |
|  CAUTION | Indicates a potential hazard. Improper handling may cause injury to people or damage to property. |

Precautions classified as "CAUTION" may still lead to serious results depending on the situation. All precautions are equally important and must be observed.

Other general precautions and tips on using the product are indicated by the following icon.



Indicates general precautions and tips on using the product.

Precautions on Product Use

DANGER

Do not use the product outside of the specified voltage range.

Applying voltage beyond the specified range may cause a malfunction, damage to the sensor, electric shock, or fire.

Do not connect a load exceeding the rated output.

The output circuit may become damaged or a fire may occur.

Precautions on Design and Selection

WARNING

Do not supply anything other than compressed air.

Use clean compressed air that does not contain corrosive gases.

Use "ISO Class 1.3.2" equivalent oil-free clean dry air.

Understand the compressed air characteristics before designing a pneumatic pressure circuit.

- Note that if instantaneous stop holding is required for emergency stop, the same functions as those for mechanical, hydraulic, or electrical regulators cannot be expected.
- The air may pop out, flow out, or leak out due to its compression and expansion characteristics.

Make sure that the product can withstand the working environment before use.

- The product cannot be used in an atmosphere where corrosive gas, chemical liquid, solvent vapor, water, and water vapor are present. If water drop, oil, or metal chips (such as spatter or cutting chips) may come into contact with the product, provide an appropriate protection.
- The product cannot be used in an explosive gas atmosphere.

Consider the effects of an emergency stop on the electric circuit and power outages on the cylinder when designing and selecting the product.

Install a pressure switch and a residual pressure exhaust valve on the compressed air supply side of the device.

The pressure switch prevents the product from operating if the set pressure is not reached. The residual pressure exhaust valve discharges compressed air remaining in the pneumatic pressure circuit in order to prevent the residual pressure from causing the pneumatic components to operate and to cause accidents.

Do not leave the pressure applied to the primary side of the product when the power is not turned on.

The secondary side pressure may rise to the same level as the primary side pressure. If there are safety concerns, design a system that ensures safety by providing measures such as installing a valve on the primary side or the secondary side.

⚠ CAUTION

Use the product within the working pressure range.

Specify maintenance conditions in the instruction manual of the customer's device.

Depending on the conditions of use, working environment, and maintenance conditions, the functions of the product may decline significantly and the safety may not be ensured. Proper maintenance will deliver optimum performance.

Use a constant voltage power supply.

Check for leakage currents from the external control devices to prevent a malfunction.

When using a control device such as a programmable controller, leakage currents from the control device may affect the product and cause it to malfunction.

| | | |
|-----------------|------------|----------------|
| Reference value | For 24 VDC | 1.8 mA or less |
|-----------------|------------|----------------|

If a stable reproducibility is necessary for the response time of the system, install a precision regulator before the product.

The response time is affected by the working pressure and the capacity of the load on the secondary side.

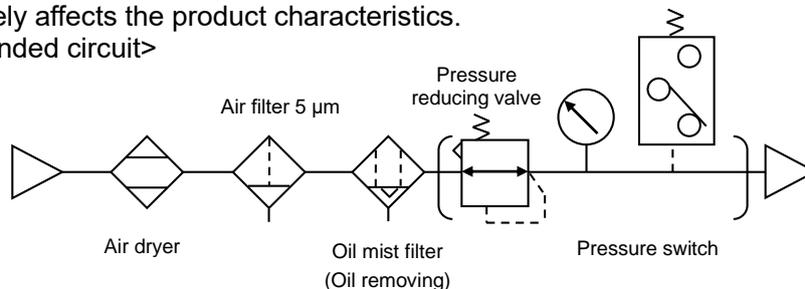
Take the following measures to prevent malfunctions caused by noise.

- Insert a line filter in the AC power supply line.
- Use a surge suppressor such as a CR or diode for the inductive load (such as a solenoid valve or a relay) to remove noise at its source.
- Install the wiring for the product away from strong electric fields.
- Wire the power lines as short as possible.
- Do not share the power supply with noise-generating devices such as inverters or motors.
- Do not wire the power cables and the signal cables in parallel with other power lines.

Do not use air of poor quality.

- For the source of pneumatic air, use clean air from which solids, moisture, and oil have been sufficiently removed with a dryer, an air filter, and an oil mist filter. Do not use air containing oil that adversely affects the product characteristics.

<Recommended circuit>



- When the secondary side pressure is reduced with an input signal, the secondary side air passes through the product and is discharged from the exhaust port. Maintain the inside of the pipes clean since contamination inside the secondary side pipes and the load also has an adverse effect on the product characteristics.

When turning off the power in a pressurized state, ensure that no residual pressure remains.

The pressure on the secondary side will remain if the power is turned off while the pressure is applied but not for a long period. Reduce the set pressure with an input signal and then turn off the power or discharge the pressure using a residual pressure exhaust valve as necessary.

The primary side pressure shall not be less than the minimum working pressure (EVD-1100: set pressure +50 kPa, EVD-1500/1900: set pressure +100 kPa, EVD-3100: set pressure +50 kPa, EVD-3500/3900: set pressure +100 kPa).

Not supplying the primary side pressure for a long period while the power is turned on will shorten the product service life.

When using the product as an air blow with the control pressure of the secondary side released to the atmosphere, test the usage under actual conditions of use or contact CKD.

The pressure may fluctuate depending on the piping and blowing conditions.

CAUTION

Select a dryer, an air filter, an oil mist filter, and a regulator that can accommodate a flow rate higher than the flow rate used for the product.

When using the product out of the specified conditions or for a special application, consult CKD about the specifications.

Do not use the product where it is exposed to direct sunlight or where water, oil, and other liquids may directly splash onto the product.

Do not install the product in places where moisture, saline matters, dusts, or cutting chips are present and pressure is applied or reduced.

The degree of protection of the product is equivalent to IP40. The product cannot be used where the temperature changes sharply or humidity is high as condensation may develop in the product and cause damage.

If 0 MPa is required, bleed the secondary side or install a 3-way valve to release the pressure to the atmosphere.

With this product, even when setting to 0 MPa, secondary pressure will remain within 1% F.S. of the maximum control pressure.

Working conditions for CE compliance

This product conforms to the EMC Directive and CE standard. The standard for the immunity for industrial environments applied to this product is EN61000-6-2; the following requirements must be satisfied in order to conform to this standard:

Condition

- The evaluation of this product is performed by using a cable that has a power supply line and a signal line, paired to assess the product's performance.
- This product is not resistant to surge immunity. Implement surge protection measures on the device side.

Regarding UL standard

If this product is being used as a UL/ULc-compliant product, please take care the below.

- Maximum temperature rating of 50°C
- Please use the "Class 2" power supply.

| UL File No. | UL Standard | Description |
|-------------|-------------|------------------------------|
| E339318 | UL 508 | Industrial Control Equipment |

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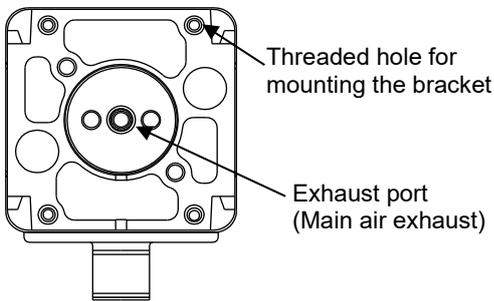
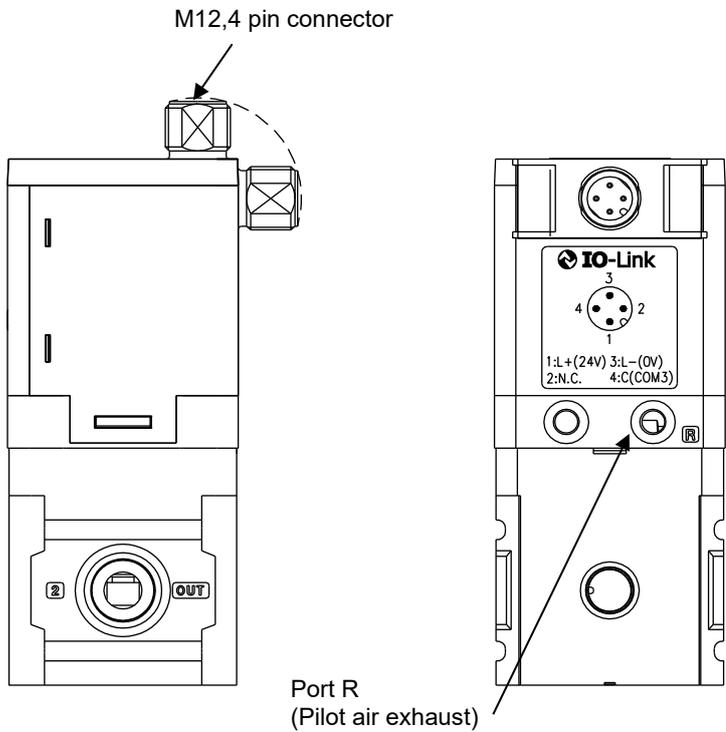
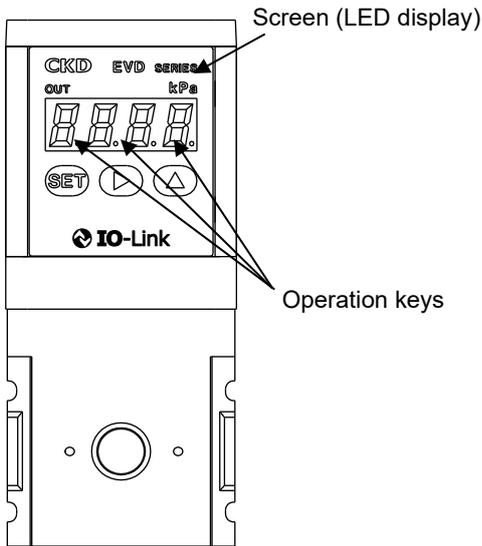
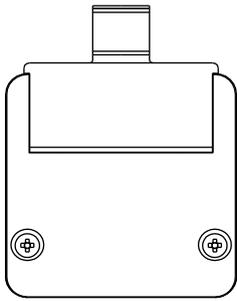
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1. PRODUCT OVERVIEW

1.1 Part Name

1.1.1 Body

■ EVD-1000 Series

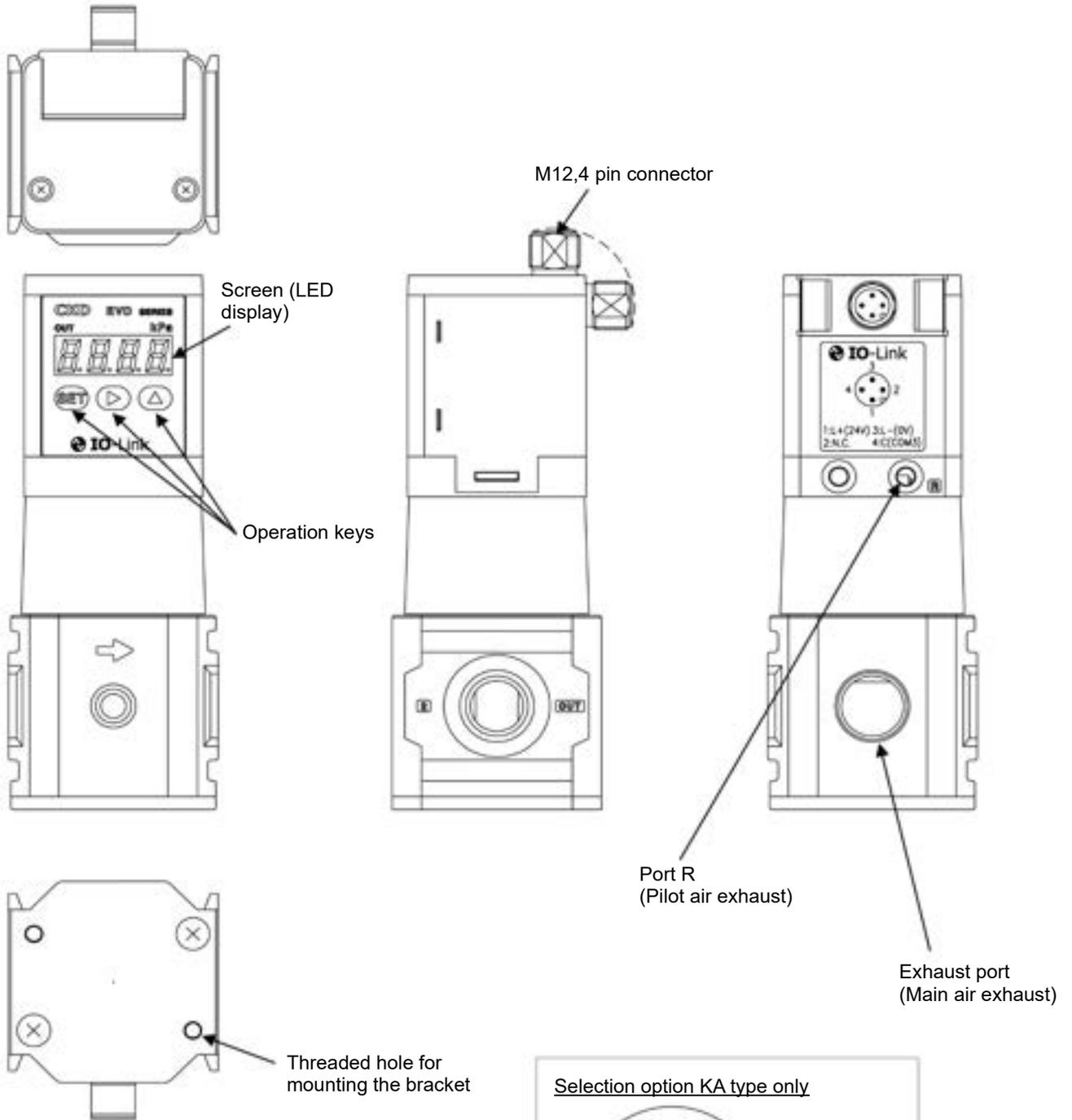


Selection option KA type only

* Please attach the unit label sticker according to the unit to be used.

| | |
|--------------------------------|-----|
| Unit label sticker (accessory) | bar |
| | psi |

■ EVD-3000 Series



Selection option KA type only

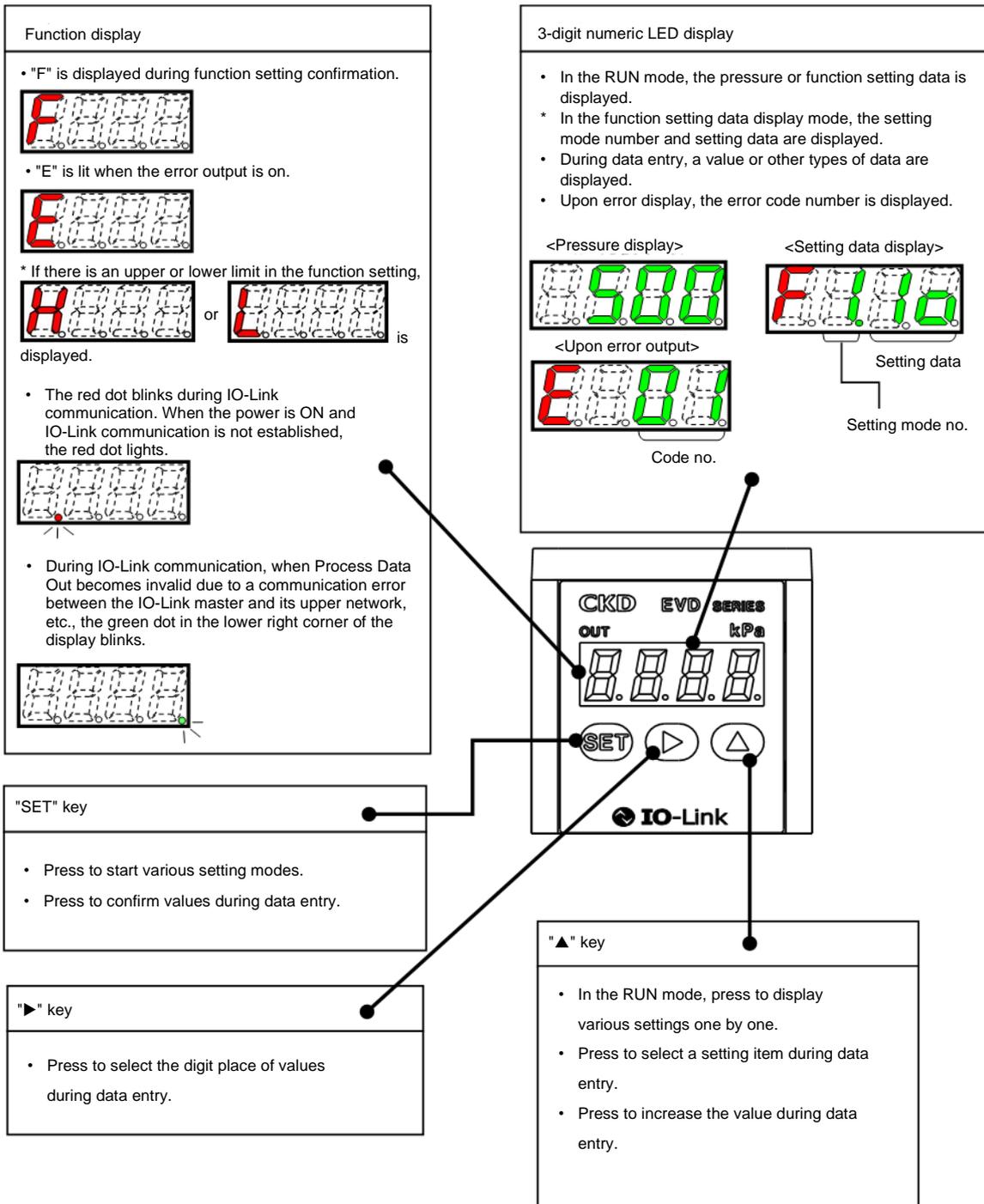


* Please attach the unit label sticker according to the unit to be used.

Unit label sticker (accessory)



1.1.2 Names and functions of display and operation section

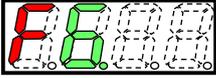
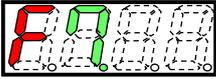
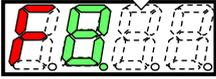


1.2 Functions

| Screen | Part Name | Details (RUN mode) | Setting details (setting mode) | Related page |
|---------------|-----------------------------|---|--|--------------|
| | Pressure display | Indicates the secondary side pressure with 3-digit number. The display value is converted to the set unit. | | |
| Screen F1 | Input specification setting | Indicates the selected input specification, current pressure value, and unit. *The factory setting is the normal mode "F1.lo". | Either normal mode input, preset input or direct memory input can be selected. For preset input/direct input, enter the setting value on this screen. Preset input values can also be set via IO-Link communication. (Direct input values can be set only on this screen.) | P.32 P.37 |
| Screen F2 | Zero/span adjustment | Not available "F2.--" is displayed. | | |
| Screen F3 | Automatic power off | Indicates whether automatic power off is enabled or disabled. * This function is set to disabled "F3.--" at the factory setting. | Select to enable or disable the automatic power off. Note) The automatic power off time is set to approximately one minute. The time cannot be changed. | P.33 P.39 |
| Screen F4 | Switch output | Indicates whether switch outputs 1 and 2 are enabled or disabled and their set values. For "Mode 1 enabled", after F4._1 or F4._2 is displayed, switch output No. 1, "-" tolerance range set value (L), and "+" tolerance range set value (H) are displayed. For "Mode 2 enabled", after F4._1 or F4._2 is displayed, switch output No. 2, lower set value (L) and upper set value (H) are displayed. *This function is set to Disabled "F4._1" ⇔ "1 --" and disabled "F4._2" ⇔ "2 --" at the factory setting. | Select to enable or disable the switch outputs 1 and 2. If enabled, "Mode 1" and "Mode 2" can be selected. +/- tolerance values and upper/lower values can be set randomly. | P.33 P.40 |
| Screen F5 | Proportional value setting | Indicates the validity of proportional value change and its set level. For "Higher proportional value", F5.H is displayed. For "Lower proportional value", F5.L and its set level is displayed alternately. * This function is set to Disabled "F5.--" at the factory setting. | Select either using the standard value or changing the proportional value. The proportional value level can be set in this mode only if "Lower proportional value" is selected (10 levels) | P.34 P.42 |

To screen F6

From screen F5

| Screen | Part Name | Details (RUN mode) | Setting details (setting mode) | Related page |
|--|---|---|---|--------------|
| Screen F6  | Unit switching | Indicates the unit. For Selection option: Unit change none (no symbol), "F6.-" is displayed. For Selection option: Unit change available (symbol KA), F6 and unit are displayed alternately. *This function is set to kPa "F6." ⇔ "kPa" at the factory setting. | Units can be selected from "kPa", "psi", and "bar" only when Selection option: Unit change available. Unit cannot be selected when Unit change none is selected. | P.34 P.44 |
| Screen F7  | Operation setting when the communication error occurs | Indicates the operation of pressure control when the communication error occurs during IO-Link communication. * This function is set to HOLD "F7.Ho" at the factory setting. | The operation of pressure control when the communication error occurs can be set from HOLD/CLEAR. | P.35 P.45 |
| Screen F8  | Operation stop function at zero input | Indicates whether the input zero operation stop function is enabled or disabled. *This function is set to Disabled "F8.--" at the factory setting. When disabled, the control does not stop when the set pressure is 0%F.S. | Whether the input zero operation stop function is enabled or disabled can be selected. When enabled, the control is stopped when the set pressure is 0%F.S. | P.35 P.46 |

1.3 Model Number Indication

■ EVD-1000 Series

EVD-1 (500) - (C) (08) (KA) - (MS) - (3)

a Pressure control range

b Input signal

c Port size

d Unit switching

e Option

f Power supply voltage

| Code | Description |
|---------------------------------|-------------|
| a Pressure control range | |
| 100 | 100kPa |
| 500 | 500kPa |
| 900 | 900kPa |

| | |
|-----------------------|---------|
| b Input signal | |
| C | IO-Link |

| | |
|--------------------|--------|
| c Port size | |
| 08 | Rc1/4 |
| 08G | G1/4 |
| 08N | NPT1/4 |

| | |
|-------------------------|-----------------------|
| d Unit switching | |
| Blank | Unit change None |
| KA | Unit change Available |

| | |
|---------------------|--|
| e Option | |
| Cable option | |
| Blank | None |
| MS | IO-Link Straight (female)/straight (male) 3 m |
| ML | IO-Link L-type (female)/straight (male) 3 m |
| MM | IO-Link One-side straight (female) 3 m |

| | |
|-----------------------|-------------------------------|
| Bracket option | |
| Blank | None |
| B1 | B-type bracket, floor mounted |
| L1 | L-type bracket, wall mounted |

| | |
|-------------------------------|-------|
| f Power supply voltage | |
| 3 | 24VDC |

*Symbol d: KA type with unit change function is only available outside Japan.

■ EVD-3000 Series

EVD-3 (500) - (C) (08) (KA) - (MS) - (3)

a Pressure control range

b Input signal

c Port size

d Unit switching

e Option

f Power supply voltage

| Code | Description |
|---------------------------------|--|
| a Pressure control range | |
| 100 | 100kPa |
| 500 | 500kPa |
| 900 | 900kPa |
| b Input signal | |
| C | IO-Link |
| c Port size | |
| 08 | Rc1/4 |
| 10 | Rc3/8 |
| 08G | G1/4 |
| 10G | G3/8 |
| 08N | NPT1/4 |
| 10N | NPT3/8 |
| d Unit switching | |
| Blank | Unit change None |
| KA | Unit change Available |
| e Option | |
| Cable option | |
| Blank | None |
| MS | IO-Link Straight (female)/straight (male) 3 m |
| ML | IO-Link L-type (female)/straight (male) 3 m |
| MM | IO-Link One-side straight (female) 3 m |
| Bracket option | |
| Blank | None |
| B3 | B-type bracket, floor mounted |
| L3 | L-type bracket, wall mounted |
| f Power supply voltage | |
| 3 | 24VDC |

*Symbol d: KA type with unit change function is only available outside Japan.

1.4 Specification

■ EVD-1100-C (maximum pressure: 100 kPa)

| Item | EVD-1100-C [*2] [*3]-[*4] [*5]-3 | | |
|-----------------------------|---|---|---|
| Working fluid | Clean compressed air (equivalent to ISO Class 1. 3. 2) | | |
| Max. working pressure | 160 kPa | | |
| Min. working pressure | Control pressure +50 kPa | | |
| Proof pressure | Inlet side | 240 kPa | |
| | Output side | 150 kPa | |
| Pressure control range | Note 1 | 0 kPa to 100 kPa | |
| Power supply voltage | 24 VDC \pm 10% (stabilized power supply with ripple rate of 1% or less) | | |
| Current consumption | Note 2 | 0.15 A or less (starting current is 0.6 A or less when the power is turned on) (port type A) | |
| Input signal | IO-Link | | |
| Preset input | 8-point (IO-Link) | | |
| Pressure display | Display method | 3-digit 7-segment LED, display accuracy: \pm 2%F.S. or less | |
| | Display range | 0 kPa to 100 kPa | |
| | Display resolution | 1 kPa | |
| Direct memory setting | 1 kPa to 100 kPa (min. set width 1 kPa/set resolution 1 kPa) | | |
| Hysteresis | Note 3 | 0.5%FS or less | |
| Linearity | Note 3 | \pm 0.3%FS or less | |
| Resolution | Note 3 | 0.2%FS or less | |
| Repeatability | Note 3 | 0.3%FS or less | |
| Temperature characteristics | Zero drift | \pm 0.15%FS/ $^{\circ}$ C or less | |
| | Span drift | \pm 0.07%FS/ $^{\circ}$ C or less | |
| Max. flow rate (ANR) | Note 4 | 60 L/min | |
| Step response | Note 5 | No load | 0.2 sec. or less |
| | | With 1000 cm ³ load | 0.8 sec. or less |
| Vibration resistance | 98 m/s ² or less | | |
| Ambient temperature | 5 $^{\circ}$ C to 50 $^{\circ}$ C | | |
| Fluid temperature | 5 $^{\circ}$ C to 50 $^{\circ}$ C | | |
| Port size [*2] | For [*2] = 08, Rc1/4 For [*2] = 08G, G1/4 For [*2] = 08N, NPT1/4 | | |
| Unit change [*3] | Note 6 | Blank | Without unit change function |
| | | KA | Unit change kPa / psi / bar (accessory: unit label sticker psi / bar) |
| Mounting orientation | No restriction | | |
| Weight (body) | 250 g | | |
| Protection circuit | Power reverse connection protection | | |

Note 1: There is 1%F.S. or less residual pressure when the input signal is 0%. (1 kPa or less)

Note 2: Use the power supply unit that has the power supply capacity sufficiently to each port of IO-Link master.

Note 3: The above characteristics are based on the condition that power supply voltage is 24 VDC \pm 0.1 VDC, working pressure is set to maximum control pressure +50 kPa, and control pressure is 10% to 90%. (No load, ambient temperature of 25 $^{\circ}$ C \pm 3 $^{\circ}$ C)

Also, the specified values are only for when the secondary side is a closed circuit and pressure fluctuations will occur if the product is used for blowing or similar applications.

Note 4: The above characteristics are based on the condition that working pressure and control pressure are set to their maximum.

Note 5: The above characteristics are based on the condition that working pressure is set to maximum and the step amount is changed

(from 50%FS to 100%FS.
from 50%FS to 60%FS.
from 50%FS to 40%FS.

Note 6: KA type with unit change function is only available outside Japan.

■ EVD-1500-C (maximum pressure: 500 kPa)

| Item | EVD-1500-C [*2] [*3]-[*4] [*5]-3 | |
|-----------------------------|---|---|
| Working fluid | Clean compressed air (equivalent to ISO Class 1. 3. 2) | |
| Max. working pressure | 700 kPa | |
| Min. working pressure | Control pressure +100 kPa | |
| Proof pressure | Inlet side | 1050 kPa |
| | Output side | 750 kPa |
| Pressure control range | Note 1 | 0 kPa to 500 kPa |
| Power supply voltage | 24 VDC \pm 10% (stabilized power supply with ripple rate of 1% or less) | |
| Current consumption | Note 2 | 0.15 A or less (starting current is 0.6 A or less when the power is turned on) (port type A) |
| Input signal | IO-Link | |
| Preset input | 8-point (IO-Link) | |
| Pressure display | Display method | 3-digit 7-segment LED, display accuracy: \pm 2%F.S. or less |
| | Display range | 0 kPa to 500 kPa |
| | Display resolution | 1 kPa |
| Direct memory setting | 5 kPa to 500 kPa (min. set width 1 kPa/set resolution 1 kPa) | |
| Hysteresis | Note 3 | 0.5%FS or less |
| Linearity | Note 3 | \pm 0.3%FS or less |
| Resolution | Note 3 | 0.2%FS or less |
| Repeatability | Note 3 | 0.3%FS or less |
| Temperature characteristics | Zero drift | \pm 0.15%FS/ $^{\circ}$ C or less |
| | Span drift | \pm 0.07%FS/ $^{\circ}$ C or less |
| Max. flow rate (ANR) | Note 4 | 400 L/min |
| Step response | No load | 0.2 sec. or less |
| | With 1000 cm ³ load | 0.8 sec. or less |
| Vibration resistance | 98 m/s ² or less | |
| Ambient temperature | 5 $^{\circ}$ C to 50 $^{\circ}$ C | |
| Fluid temperature | 5 $^{\circ}$ C to 50 $^{\circ}$ C | |
| Port size [*2] | For [*2] = 08, Rc1/4 For [*2] = 08G, G1/4 For [*2] = 08N, NPT1/4 | |
| Unit change [*3] | Blank | Without unit change function |
| | KA | Unit change kPa / psi / bar (accessory: unit label sticker psi / bar) |
| Mounting orientation | No restriction | |
| Weight (body) | 250 g | |
| Protection circuit | Power reverse connection protection | |

Note 1: There is 1%F.S. or less residual pressure when the input signal is 0%. (5 kPa or less)

Note 2: Use the power supply unit that has the power supply capacity sufficiently to each port of IO-Link master.

Note 3: The above characteristics are based on the condition that power supply voltage is 24 VDC \pm 0.1 VDC, working pressure is set to maximum control pressure +100 kPa, and control pressure is 10% to 90% (No load, ambient temperature of 25 $^{\circ}$ C \pm 3 $^{\circ}$ C)

Also, the specified values are only for when the secondary side is a closed circuit and pressure fluctuations will occur if the product is used for blowing or similar applications.

Note 4: The above characteristics are based on the condition that working pressure and control pressure are set to their maximum.

Note 5: The above characteristics are based on the condition that working pressure is set to maximum and the step amount is changed

| | |
|---|-----------------------|
| { | from 50%FS to 100%FS. |
| | from 50%FS to 60%FS. |
| | from 50%FS to 40%FS. |

Note 6: KA type with unit change function is only available outside Japan.

■ EVD-1900-C (maximum pressure: 900 kPa)

| Item | EVD-1900-C [*2] [*3]-[*4] [*5]-3 | | |
|-----------------------------|---|---|---|
| Working fluid | Clean compressed air (equivalent to ISO Class 1. 3. 2) | | |
| Max. working pressure | 1000 kPa | | |
| Min. working pressure | Control pressure +100 kPa | | |
| Proof pressure | Inlet side | 1500 kPa | |
| | Output side | 1350 kPa | |
| Pressure control range | Note 1 | 0 kPa to 900 kPa | |
| Power supply voltage | 24 VDC \pm 10% (stabilized power supply with ripple rate of 1% or less) | | |
| Current consumption | Note 2 | 0.15 A or less (starting current is 0.6 A or less when the power is turned on) (port type A) | |
| Input signal | IO-Link | | |
| Preset input | 8-point (IO-Link) | | |
| Pressure display | Display method | 3-digit 7-segment LED, display accuracy: \pm 2%F.S. or less | |
| | Display range | 0 kPa to 900 kPa | |
| | Display resolution | 1 kPa | |
| Direct memory setting | 9 kPa to 900 kPa (Min. set width 1 kPa/set resolution 2 kPa) | | |
| Hysteresis | Note 3 | 0.5%FS or less | |
| Linearity | Note 3 | \pm 0.3%FS or less | |
| Resolution | Note 3 | 0.2%FS or less | |
| Repeatability | Note 3 | 0.3%FS or less | |
| Temperature characteristics | Zero drift | \pm 0.15%FS/ $^{\circ}$ C or less | |
| | Span drift | \pm 0.07%FS/ $^{\circ}$ C or less | |
| Max. flow rate (ANR) | Note 4 | 400 L/min | |
| Step response | Note 5 | No load | 0.2 sec. or less |
| | | With 1000 cm ³ load | 0.8 sec. or less |
| Vibration resistance | 98 m/s ² or less | | |
| Ambient temperature | 5 $^{\circ}$ C to 50 $^{\circ}$ C | | |
| Fluid temperature | 5 $^{\circ}$ C to 50 $^{\circ}$ C | | |
| Port size [*2] | For [*2] = 08, Rc1/4 For [*2] = 08G, G1/4 For [*2] = 08N, NPT1/4 | | |
| Unit change [*3] | Note 6 | Blank | Without unit change function |
| | | KA | Unit change kPa / psi / bar (accessory: unit label sticker psi / bar) |
| Mounting orientation | No restriction | | |
| Weight (body) | 250 g | | |
| Protection circuit | Power reverse connection protection | | |

Note 1: There is 1%F.S. or less residual pressure when the input signal is 0%. (9 kPa or less)

Note 2: Use the power supply unit that has the power supply capacity sufficiently to each port of IO-Link master.

Note 3: The above characteristics are based on the condition that power supply voltage is 24 VDC \pm 0.1 VDC, working pressure is set to maximum control pressure +100 kPa, and control pressure is 10% to 90% (No load, ambient temperature of 25 $^{\circ}$ C \pm 3 $^{\circ}$ C)

Also, the specified values are only for when the secondary side is a closed circuit and pressure fluctuations will occur if the product is used for blowing or similar applications.

Note 4: The above characteristics are based on the condition that working pressure and control pressure are set to their maximum.

Note 5: The above characteristics are based on the condition that working pressure is set to maximum and the step amount is changed

- from 50%FS to 100%FS.
- from 50%FS to 60%FS.
- from 50%FS to 40%FS.

Note 6: KA type with unit change function is only available outside Japan.

■ EVD-3100-C (maximum pressure: 100 kPa)

| Item | EVD-3100-C [*2] [*3]-[*4] [*5]-3 | |
|-----------------------------|---|--|
| Working fluid | Clean compressed air (equivalent to ISO Class 1. 3. 2) | |
| Max. working pressure | 160 kPa | |
| Min. working pressure | Control pressure +50 kPa | |
| Proof pressure | Inlet side | 240 kPa |
| | Output side | 150 kPa |
| Pressure control range | Note 1 | 0 kPa to 100 kPa |
| Power supply voltage | 24 VDC \pm 10% (stabilized power supply with ripple rate of 1% or less) | |
| Current consumption | Note 2 | 0.15 A or less (starting current is 0.6 A or less when the power is turned on) (port type A) |
| Input signal | IO-Link | |
| Preset input | 8-point (IO-Link) | |
| Pressure display | Display method | 3-digit 7-segment LED, display accuracy: \pm 2%F.S. or less |
| | Display range | 0 kPa to 100 kPa |
| | Display resolution | 1 kPa |
| Direct memory setting | 1 kPa to 100 kPa (min. set width 1 kPa/set resolution 1 kPa) | |
| Hysteresis | Note 3 | 0.5%FS or less |
| Linearity | Note 3 | \pm 0.3%FS or less |
| Resolution | Note 3 | 0.2%FS or less |
| Repeatability | Note 3 | 0.3%FS or less |
| Temperature characteristics | Zero drift | \pm 0.15%FS/ $^{\circ}$ C or less |
| | Span drift | \pm 0.07%FS/ $^{\circ}$ C or less |
| Max. flow rate (ANR) | Note 4 | 700 L/min |
| Step response | Note 5 | No load |
| | | With 1000 cm ³ load |
| Vibration resistance | 98 m/s ² or less | |
| Ambient temperature | 5 $^{\circ}$ C to 50 $^{\circ}$ C | |
| Fluid temperature | 5 $^{\circ}$ C to 50 $^{\circ}$ C | |
| Port size [*2] | IN, OUT ports | For [*2] = 08, Rc1/4, and for [*2] = 10, Rc3/8 For [*2] = 08G, G1/4, and for [*2] = 10G, G3/8 For [*2] = 08N, NPT1/4, and for [*2] = 10N, NPT3/8 |
| | Exhaust port | For [*2] = 08 or 10, Rc3/8 For [*2] = 08G or 10G, G3/8 For [*2] = 08N or 10N, NPT3/8 |
| Unit change [*3] | Note 6 | Blank |
| | | KA |
| Mounting orientation | Without unit change function | |
| Weight (body) | Unit change kPa / psi / bar (accessory: unit label sticker psi / bar) | |
| Protection circuit | No restriction | |
| | 470 g | |
| | Power reverse connection protection | |

Note 1: There is 1%F.S. or less residual pressure when the input signal is 0%. (1 kPa or less)

Note 2: Use the power supply unit that has the power supply capacity sufficiently to each port of IO-Link master.

Note 3: The above characteristics are based on the condition that power supply voltage is 24 VDC \pm 0.1 VDC, working pressure is set to maximum control pressure +50 kPa, and control pressure is 10% to 90%. (No load, ambient temperature of 25 $^{\circ}$ C \pm 3 $^{\circ}$ C)

Also, the specified values are only for when the secondary side is a closed circuit and pressure fluctuations will occur if the product is used for blowing or similar applications.

Note 4: The above characteristics are based on the condition that working pressure and control pressure are set to their maximum.

Note 5: The above characteristics are based on the condition that working pressure is set to maximum and the step amount is changed

| | |
|---|-----------------------|
| { | from 50%FS to 100%FS. |
| | from 50%FS to 60%FS. |
| | from 50%FS to 40%FS. |

Note 6: KA type with unit change function is only available outside Japan.

■ EVD-3500-C (maximum pressure: 500 kPa)

| Item | EVD-3500-C [*2] [*3]-[*4] [*5]-3 | |
|-----------------------------|---|--|
| Working fluid | Clean compressed air (equivalent to ISO Class 1. 3. 2) | |
| Max. working pressure | 700 kPa | |
| Min. working pressure | Control pressure +100 kPa | |
| Proof pressure | Inlet side | 1050 kPa |
| | Output side | 750 kPa |
| Pressure control range | Note 1 | 0 kPa to 500 kPa |
| Power supply voltage | 24 VDC \pm 10% (stabilized power supply with ripple rate of 1% or less) | |
| Current consumption | Note 2 | 0.15 A or less (starting current is 0.6 A or less when the power is turned on) (port type A) |
| Input signal | IO-Link | |
| Preset input | 8-point (IO-Link) | |
| Pressure display | Display method | 3-digit 7-segment LED, display accuracy: \pm 2%F.S. or less |
| | Display range | 0 kPa to 500 kPa |
| | Display resolution | 1 kPa |
| Direct memory setting | 5 kPa to 500 kPa (min. set width 1 kPa/set resolution 1 kPa) | |
| Hysteresis | Note 3 | 0.5%FS or less |
| Linearity | Note 3 | \pm 0.3%FS or less |
| Resolution | Note 3 | 0.2%FS or less |
| Repeatability | Note 3 | 0.3%FS or less |
| Temperature characteristics | Zero drift | \pm 0.15%FS/ $^{\circ}$ C or less |
| | Span drift | \pm 0.07%FS/ $^{\circ}$ C or less |
| Max. flow rate (ANR) | Note 4 | 1500 L/min |
| Step response | No load | 0.2 sec. or less |
| | With 1000 cm ³ load | 0.8 sec. or less |
| Vibration resistance | 98 m/s ² or less | |
| Ambient temperature | 5 $^{\circ}$ C to 50 $^{\circ}$ C | |
| Fluid temperature | 5 $^{\circ}$ C to 50 $^{\circ}$ C | |
| Port size [*2] | IN, OUT ports | For [*2] = 08, Rc1/4, and for [*2] = 10, Rc3/8 For [*2] = 08G, G1/4, and for [*2] = 10G, G3/8 For [*2] = 08N, NPT1/4, and for [*2] = 10N, NPT3/8 |
| | Exhaust port | For [*2] = 08 or 10, Rc3/8 For [*2] = 08G or 10G, G3/8 For [*2] = 08N or 10N, NPT3/8 |
| Unit change [*3] | Blank | Without unit change function |
| | KA | Unit change kPa / psi / bar (accessory: unit label sticker psi / bar) |
| Mounting orientation | No restriction | |
| Weight (body) | 470 g | |
| Protection circuit | Power reverse connection protection | |

Note 1: There is 1%F.S. or less residual pressure when the input signal is 0%. (5 kPa or less)

Note 2: Use the power supply unit that has the power supply capacity sufficiently to each port of IO-Link master.

Note 3: The above characteristics are based on the condition that power supply voltage is 24 VDC \pm 0.1 VDC, working pressure is set to maximum control pressure +100 kPa, and control pressure is 10% to 90% (No load, ambient temperature of 25 $^{\circ}$ C \pm 3 $^{\circ}$ C)

Also, the specified values are only for when the secondary side is a closed circuit and pressure fluctuations will occur if the product is used for blowing or similar applications.

Note 4: The above characteristics are based on the condition that working pressure and control pressure are set to their maximum.

Note 5: The above characteristics are based on the condition that working pressure is set to maximum and the step amount is changed

| | |
|---|-----------------------|
| { | from 50%FS to 100%FS. |
| | from 50%FS to 60%FS. |
| | from 50%FS to 40%FS. |

Note 6: KA type with unit change function is only available outside Japan.

■ EVD-3900-C (maximum pressure: 900 kPa)

| Item | EVD-3900-C [*2] [*3]-[*4] [*5]-3 | |
|-----------------------------|---|--|
| Working fluid | Clean compressed air (equivalent to ISO Class 1. 3. 2) | |
| Max. working pressure | 1000 kPa | |
| Min. working pressure | Control pressure +100 kPa | |
| Proof pressure | Inlet side | 1500 kPa |
| | Output side | 1350 kPa |
| Pressure control range | Note 1 | 0 kPa to 900 kPa |
| Power supply voltage | 24 VDC \pm 10% (stabilized power supply with ripple rate of 1% or less) | |
| Current consumption | Note 2 | 0.15 A or less (starting current is 0.6 A or less when the power is turned on) (port type A) |
| Input signal | IO-Link | |
| Preset input | 8-point (IO-Link) | |
| Pressure display | Display method | 3-digit 7-segment LED, display accuracy: \pm 2%F.S. or less |
| | Display range | 0 kPa to 900 kPa |
| | Display resolution | 1 kPa |
| Direct memory setting | 9 kPa to 900 kPa (Min. set width 1 kPa/set resolution 2 kPa) | |
| Hysteresis | Note 3 | 0.5%FS or less |
| Linearity | Note 3 | \pm 0.3%FS or less |
| Resolution | Note 3 | 0.2%FS or less |
| Repeatability | Note 3 | 0.3%FS or less |
| Temperature characteristics | Zero drift | \pm 0.15%FS/ $^{\circ}$ C or less |
| | Span drift | \pm 0.07%FS/ $^{\circ}$ C or less |
| Max. flow rate (ANR) | Note 4 | 1500 L/min |
| Step response | No load | 0.2 sec or less |
| | With 1000 cm ³ load | 0.8 sec or less |
| Vibration resistance | 98 m/s ² or less | |
| Ambient temperature | 5 $^{\circ}$ C to 50 $^{\circ}$ C | |
| Fluid temperature | 5 $^{\circ}$ C to 50 $^{\circ}$ C | |
| Port size [*2] | IN, OUT ports | For [*2] = 08, Rc1/4, and for [*2] = 10, Rc3/8 For [*2] = 08G, G1/4, and for [*2] = 10G, G3/8 For [*2] = 08N, NPT1/4, and for [*2] = 10N, NPT3/8 |
| | Exhaust port | For [*2] = 08 or 10, Rc3/8 For [*2] = 08G or 10G, G3/8 For [*2] = 08N or 10N, NPT3/8 |
| Unit change [*3] | Blank | Without unit change function |
| | KA | Unit change kPa / psi / bar (accessory: unit label sticker psi / bar) |
| Mounting orientation | No restriction | |
| Weight (body) | 470 g | |
| Protection circuit | Power reverse connection protection | |

Note 1: There is 1% F.S. or less residual pressure when the input signal is 0%. (9 kPa or less)

Note 2: Use the power supply unit that has the power supply capacity sufficiently to each port of IO-Link master.

Note 3: The above characteristics are based on the condition that power supply voltage is 24 VDC \pm 0.1 VDC, working pressure is set to maximum control pressure +100 kPa, and control pressure is 10% to 90% (No load, ambient temperature of 25 $^{\circ}$ C \pm 3 $^{\circ}$ C)

Also, the specified values are only for when the secondary side is a closed circuit and pressure fluctuations will occur if the product is used for blowing or similar applications.

Note 4: The above characteristics are based on the condition that working pressure and control pressure are set to their maximum.

Note 5: The above characteristics are based on the condition that working pressure is set to maximum and the step amount is changed

| | |
|---|-----------------------|
| { | from 50%FS to 100%FS. |
| | from 50%FS to 60%FS. |
| | from 50%FS to 40%FS. |

Note 6: KA type with unit change function is only available outside Japan.

1.5 Communication specifications

1.5.1 General

| Item | Details |
|--------------------------------|-------------------|
| Communication protocol | IO-Link |
| Communication protocol version | V1.1 |
| Transmission rate | COM3 (230.4 kbps) |
| Port type | Class A |
| Process data length (input) | 6 byte |
| Process data length (output) | 4 byte |

| Item | Details |
|------------------|--------------------------|
| Min. cycle time | 2 ms |
| Data storage | 1 kbyte |
| SIO mode support | None |
| Device ID | Refer to the table below |

■ Device ID

| Device ID | Product Name | Note |
|-----------|---------------|---------------------------------------|
| 0x215001 | EVD-*100-C | 100 kPa range |
| 0x215002 | EVD-*500-C | 500 kPa range |
| 0x215003 | EVD-*900-C | 900 kPa range |
| 0x215004 | EVD-*100-C-KA | 100 kPa range (unit change available) |
| 0x215005 | EVD-*500-C-KA | 500 kPa range (unit change available) |
| 0x215006 | EVD-*900-C-KA | 900 kPa range (unit change available) |

1.5.2 On demand data

■ Identification

Vendor ID: 855 (decimal) / 357 (hexadecimal)

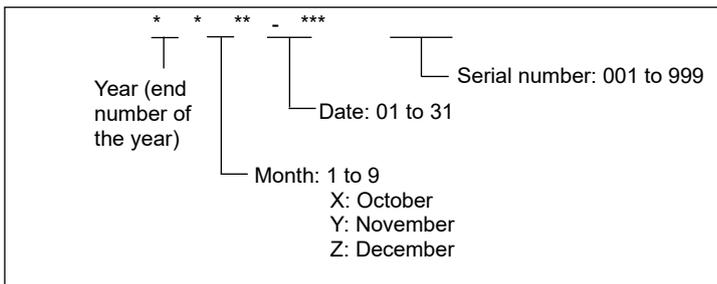
| Index | Sub-index | Item | Value | Access | Data length | Format |
|--------|-----------|--------------------------|---|--------|-------------|--------|
| 0x0010 | 0 | Vendor Name | CKD Corporation | R | 64 byte | String |
| 0x0011 | 0 | Vendor Text | https://www.ckd.co.jp/ | R | 64 byte | String |
| 0x0012 | 0 | Product Name | EVD-*500-C08-****-3 (*1) | R | 40 byte | String |
| 0x0013 | 0 | Product ID | EVD-*500-C (*1) | R | 64 byte | String |
| 0x0014 | 0 | Product Text | Digital Electro-pneumatic Regulator | R | 64 byte | String |
| 0x0015 | 0 | Serial- Number | ****-*** (*2) | R | 16 byte | String |
| 0x0016 | 0 | Hardware Revision | V1.0 (*1) | R | 64 byte | String |
| 0x0017 | 0 | Firmware Revision | V2.0 (*1) | R | 64 byte | String |
| 0x0018 | 0 | Application Specific Tag | * * * | R/W | 32 byte | String |

R: read

R/W: read/write

*1...A reference example is shown.

*2...About serial number



Control pressure range for each model

| Model number | Select unit | Control pressure | | | Note |
|--------------------------------|------------------|---------------------|----------------------------------|---------------------------|-------------------------|
| | | Display (7-segment) | Process data display range (kPa) | Process data output value | |
| EVD-1100-C EVD-3100-C | None (kPa fixed) | 0 to 100 | 0.0 to 100.0 | 0 to 1000 | (Unit change none) |
| EVD-1500-C EVD-3500-C | None (kPa fixed) | 0 to 500 | 0.0 to 500.0 | 0 to 5000 | (Unit change none) |
| EVD-1900-C EVD-3900-C | None (kPa fixed) | 0 to 900 | 0.0 to 900.0 | 0 to 9000 | (Unit change none) |
| EVD-1100-C*KA EVD-3100-C*KA | kPa | 0 to 100 | 0.0 to 100.0 | 0 to 1000 | (Unit change available) |
| | psi | 0 to 14.5 | 0.0 to 14.50 | 0 to 1450 | |
| | bar | 0 to 1.00 | 0.0 to 1.000 | 0 to 1000 | |
| EVD-1500-C*KA EVD-3500-C*KA | kPa | 0 to 500 | 0.0 to 500.0 | 0 to 5000 | (Unit change available) |
| | psi | 0 to 72.5 | 0.0 to 72.50 | 0 to 7250 | |
| | bar | 0 to 5.00 | 0.0 to 5.000 | 0 to 5000 | |
| EVD-1900-C*KA EVD-3900-C*KA | kPa | 0 to 900 | 0.0 to 900.0 | 0 to 9000 | (Unit change available) |
| | psi | 0 to 130 | 0.0 to 130.5 | 0 to 1305 | |
| | bar | 0 to 9.00 | 0.0 to 9.000 | 0 to 9000 | |

1.5.3 Parameter and commands

Common specification

| Index | Sub-index | Item | Value | Access | Data length | Format |
|--------|-----------|-------------------------|--|--------|-------------|-------------------------|
| 0x0002 | 0 | System Command | Refer to the "Table 1" below. | W | 1 byte | UInteger8 |
| 0x000C | 0 | Device Access Locks | 0x0000: No lock 0x0001: Parameter lock 0x0002: Data storage lock | R | 2 byte | Record |
| 0x0020 | 0 | Error Count | 0 | R | 2 byte | UInteger16 |
| 0x0024 | 0 | Device Status | 0 | R | 1 byte | UInteger8 |
| 0x0025 | 0 | Detailed Devices Status | Refer to Diagnosis | R | 33 byte | Array of 3 Octet string |

R: read

W: write

R/W: read/write

Table 1 (System commands)

| Value | Command | Description |
|-------|--------------------------|---|
| 0x82 | Restore Factory Settings | Set the setting value to the shipping state |

■ Individual specification

| Index | Sub-index | Item | Value | Data storage | Access | Data length | Format |
|--------|-----------|---|--|--------------|--------|-------------|------------|
| 0x0100 | 0 | Operation stop function at zero Input signal | 0: OFF 1: ON | ○ | R/W | 2 byte | UInteger16 |
| 0x0101 | 0 | Switch output 1 Mode selection | 0: OFF 1: Mode 1 2: Mode 2 | ○ | R/W | 2 byte | UInteger16 |
| 0x0102 | 0 | Switch output 2 Mode selection | 0: OFF 1: Mode 1 2: Mode 2 | ○ | R/W | 2 byte | UInteger16 |
| 0x0103 | 0 | Switch output 1 Mode 1 Lower limit value | 0 Setting range: 0 to 50 | ○ | R/W | 2 byte | UInteger16 |
| 0x0104 | 0 | Switch output 1 Mode 1 Upper limit value | 0 Setting range: 0 to 50 | ○ | R/W | 2 byte | UInteger16 |
| 0x0105 | 0 | Switch output 1 Mode 2 Lower limit value Note 1 | 0 Setting range: 0 to 90 | ○ | R/W | 2 byte | UInteger16 |
| 0x0106 | 0 | Switch output 1 Mode 2 Upper limit value Note 1 | 100 Setting range: 10 to 100 | ○ | R/W | 2 byte | UInteger16 |
| 0x0107 | 0 | Switch output 2 Mode 1 Lower limit value | 0 Setting range: 0 to 50 | ○ | R/W | 2 byte | UInteger16 |
| 0x0108 | 0 | Switch output 2 Mode 1 Upper limit value | 0 Setting range: 0 to 50 | ○ | R/W | 2 byte | UInteger16 |
| 0x0109 | 0 | Switch output 2 Mode 2 Lower limit value Note 1 | 0 Setting range: 0 to 90 | ○ | R/W | 2 byte | UInteger16 |
| 0x010A | 0 | Switch output 2 Mode 2 Upper limit value Note 1 | 100 Setting range: 10 to 100 | ○ | R/W | 2 byte | UInteger16 |
| 0x010B | 0 | Proportional value setting | 0: OFF 1: Higer proportional value 2: Lower proportional value | ○ | R/W | 2 byte | UInteger16 |
| 0x010C | 0 | Set level when setting to Proportional value down | 1 Setting range: 1 to 10 | ○ | R/W | 2 byte | UInteger16 |
| 0x010D | 0 | Automatic power off setting | 0: OFF 1: ON | ○ | R/W | 2 byte | Integer16 |
| 0x010E | 0 | Key lock setting | 0: Unlock 1: Lock | ○ | R/W | 2 byte | Integer16 |
| 0x010F | 0 | Input setting | 0: Normal Mode 1: Preset Mode 2: Direct Mode | ○ | R/W | 2 byte | Integer16 |

R: read

W: write

R/W: read/write

part: Default value

Note 1 When using Mode 2, set so that $(\text{lower limit value} + 10) \leq \text{upper limit value}$.
If this condition is not satisfied, the SW output will always be OFF.

| Index | Sub-index | Item | Value | Data storage | Access | Data length | Format |
|--------|-----------|--|--|--------------|--------|-------------|------------|
| 0x0110 | 0 | Preset memory 1 | 0 Setting range depends on the pressure range | ○ | R/W | 2 byte | Integer16 |
| 0x0111 | 0 | Preset memory 2 | 0 Setting range depends on the pressure range | ○ | R/W | 2 byte | Integer16 |
| 0x0112 | 0 | Preset memory 3 | 0 Setting range depends on the pressure range | ○ | R/W | 2 byte | Integer16 |
| 0x0113 | 0 | Preset memory 4 | 0 Setting range depends on the pressure range | ○ | R/W | 2 byte | Integer16 |
| 0x0114 | 0 | Preset memory 5 | 0 Setting range depends on the pressure range | ○ | R/W | 2 byte | Integer16 |
| 0x0115 | 0 | Preset memory 6 | 0 Setting range depends on the pressure range | ○ | R/W | 2 byte | Integer16 |
| 0x0116 | 0 | Preset memory 7 | 0 Setting range depends on the pressure range | ○ | R/W | 2 byte | Integer16 |
| 0x0117 | 0 | Preset memory 8 | 0 Setting range depends on the pressure range | ○ | R/W | 2 byte | Integer16 |
| 0x0118 | 0 | Unit switching Note 1 | 0: kPa 1: psi 2: bar | ○ | R/W | 2 byte | UInteger16 |
| 0x0119 | 0 | Decimal point position of data | 1: 1st digit 2: 2nd digit 3: 3rd digit | - | R | 2 byte | UInteger16 |
| 0x011A | 0 | Operation while communication error occurred Note 2 | 0: HOLD 1: CLEAR | ○ | R/W | 2 byte | UInteger16 |

R: read, W: write, R/W: read/write

○ part: Default value

Note 1: 1: psi and 2: bar cannot be set when "Unit change none" is selected.

Note 2: The operation while communication error occurred is as indicated in Table 1.

Table 1 Operation at communication error

| Cause | State | When an error occurs | | | When an error is recovered | | |
|---------------------|---------------|--|--|--|--|--|--|
| | | Normal mode | Preset mode | Direct mode | Normal mode | Preset mode | Direct mode |
| Communication error | Hold setting | Control pressure is held at the Process Data Out setting before the error occurred | Control pressure is held at preset setting before the error occurred | Control pressure is controlled with direct setting value | Control pressure is controlled with Process Data Out setting value | Control pressure is controlled with preset setting value | Control pressure is controlled with direct setting value |
| | Clear setting | Control pressure 0 | Control pressure 0 | Control pressure is controlled with direct setting value | Control pressure is controlled with Process Data Out setting value | Control pressure is controlled with preset setting value | Control pressure is controlled with direct setting value |

* Communication error: A communication error is defined that Process Data Status is invalid or Process Data Out is invalid. When the C/Q line is disconnected, it becomes invalid. If the IO-Link master and its upper network are disconnected, Process Data Out is disabled.
(Depending on the specification of the IO-Link master, Process Data Out may not be disabled even if the wire is disconnected. Please check the specifications of the master.)

* HOLD/CLEAR: This switch controls the operation when an error occurs in the communication function. It can be set using "On-request Data" in IO-Link communication.

1.5.4 Process data IN

| PD | PD0 | | | | | | | | PD1 | | | | | | | |
|------------|--------------|----|----|----|----|----|----|----|-----|----|----|----|----|----|----|-----|
| Bit | 47 | 46 | 45 | 44 | 43 | 42 | 41 | 40 | 39 | 38 | 37 | 36 | 35 | 34 | 33 | 32 |
| | MSB | | | | | | | | | | | | | | | LSB |
| Data name | Set pressure | | | | | | | | | | | | | | | |
| Data range | 2 byte | | | | | | | | | | | | | | | |
| Format | UInteger16 | | | | | | | | | | | | | | | |

| PD | PD2 | | | | | | | | PD3 | | | | | | | |
|------------|------------------|----|----|----|----|----|----|----|-----|----|----|----|----|----|----|-----|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 |
| | MSB | | | | | | | | | | | | | | | LSB |
| Data name | Control pressure | | | | | | | | | | | | | | | |
| Data range | 2 byte | | | | | | | | | | | | | | | |
| Format | UInteger16 | | | | | | | | | | | | | | | |

| PD | PD4 | | | | | | | | PD5 | | | | | | | |
|------------|------------|---------|------------------|----|----|----|---------------|---|------------|---|---|-----|---------------|---|---|------------|
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Data name | Error | WARNING | Normal operation | - | - | - | Switch output | | MSB | | | LSB | Input setting | | - | Start/Stop |
| | | | | | | | 2 | 1 | Error code | | | | | | | |
| Data range | True/False | | | | | | | | 0 to 15 | | | | 0 to 2 | | - | True/False |
| Format | Boolean | | | | | | | | UInteger4 | | | | UInteger2 | | - | Boolean |

1.5.5 Process data OUT

⚠ CAUTION

Start energization to this product after clearing Process Data OUT to "0".
 Unintended pressure may be output.

The setting in this product can be changed with IO-Link communication from the master and key operation on the device (this product).
 The setting that be set at last is reflected as this product's setting because there is no hierarchical relationship and precedence on both sides. In case that the setting is set on the device side, it is synchronized with the master side. But it may not be reflected to the display unless the display is update or the setting is uploaded depending on master. Take care of that.

The value in Process Data OUT can be operated only on the master side.
 The value cannot be reflected in the Process Data OUT value even if the setting is changed with key operation on the device. Confirm Process Data IN and Parameter when confirming the product setting state on the master side.

| PD | PD0 | | | | | | | | PD1 | | | | | | | |
|------------|--------------|----|----|----|----|----|----|----|-----|----|----|----|----|----|----|-----|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 |
| | MSB | | | | | | | | | | | | | | | LSB |
| Data name | Set pressure | | | | | | | | | | | | | | | |
| Data range | 2 byte | | | | | | | | | | | | | | | |
| Format | UInteger16 | | | | | | | | | | | | | | | |

| PD | PD2 | | | | | | | PD3 | | | | | | | | |
|------------|-----|----|----|----|----|---------------|---|-----|---|---|---|---|---|---|---|----------------------|
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Data name | - | - | - | - | - | Preset Note 1 | | | - | - | - | - | - | - | - | Start/Stop Note 2, 3 |
| | | | | | | 3 | 2 | 1 | | | | | | | | |
| Data range | - | - | - | - | - | 0 to 7 | | | - | - | - | - | - | - | - | True/False |
| Format | - | - | - | - | - | UInteger3 | | | - | - | - | - | - | - | - | Boolean |

- Note 1: Refer to "3.3.2 Preset input" for details.
- Note 2: When turning off the power of the EVD, be sure to change the Process Data OUT pressure from zero (Bit16-31 = 0) to stop (Bit0 = 0) before turning off the power. The excessive operation data of solenoid valve are saved when transitioning from start to stop.
- Note 3: In case that controlling is performed using IO-Link communication, set this bit to 1 (True). If this bit is 0 (False), controlling cannot be performed.

1.5.6 Observation

| Index | Sub Index | Item | Value | Access | Data length | Format |
|--------|-----------|---|-------------------------------------|--------|-------------|-----------|
| 0x0400 | 0 | Solenoid valve energizing time *1 Operating Time | 0 to 9,999,999h [0 to 9,999,999] | R | 4 byte | Integer32 |
| 0x0401 | 0 | Excessive operation time of supply solenoid valve *1 | 0 to 9,999,999h | R | 4 byte | Integer32 |
| 0x0402 | 0 | Number of excessive operations of supply solenoid valve | 0 to 9,999,999 times | R | 4 byte | Integer32 |
| 0x0403 | 0 | Excessive operation time of exhaust solenoid valve *1 | 0 to 9,999,999h | R | 4 byte | Integer32 |
| 0x0404 | 0 | Number of excessive operations of exhaust solenoid valve | 0 to 9,999,999 times | R | 4 byte | Integer32 |

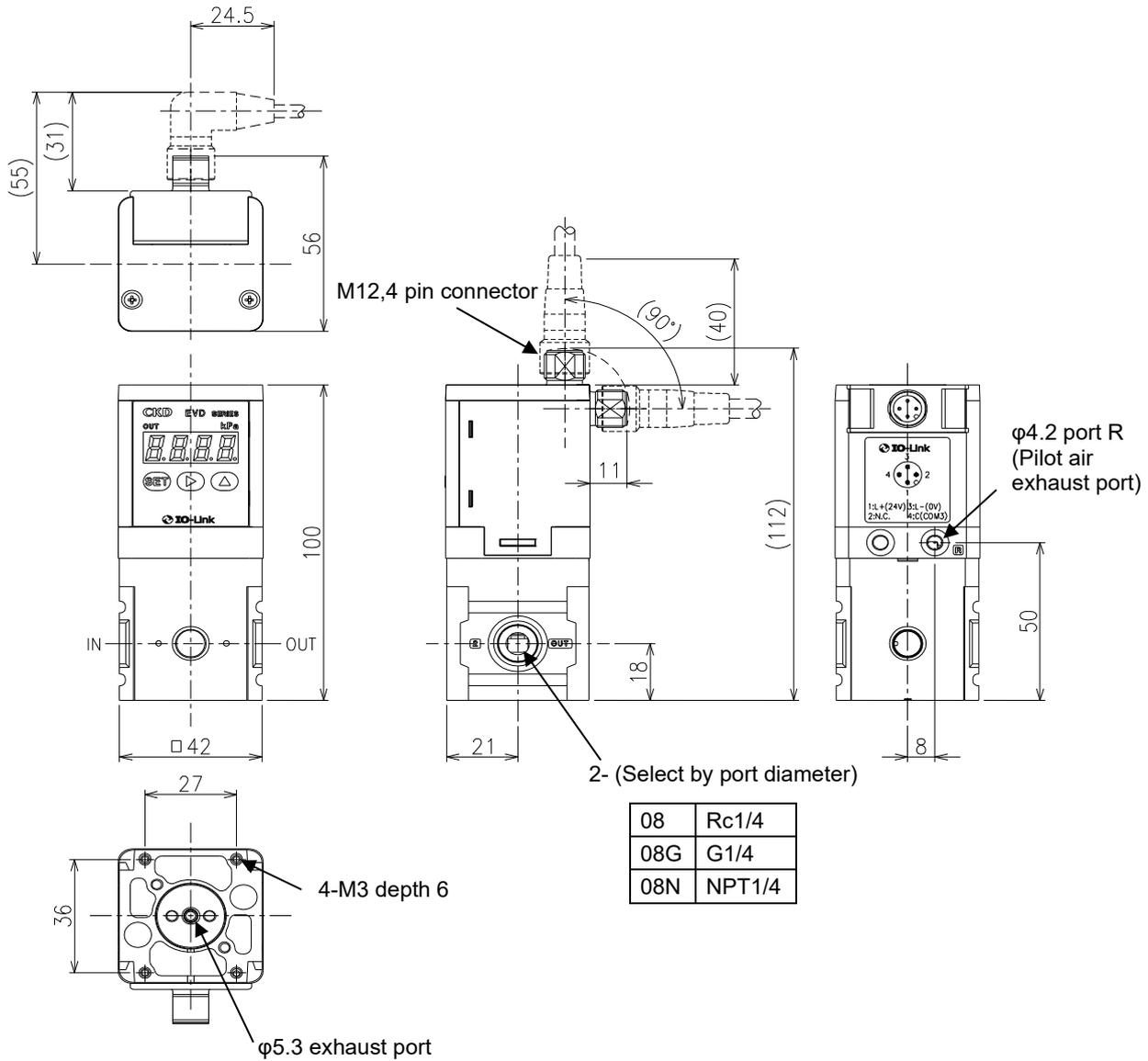
- R: read
- *1 Be able to count more than 10 years of energization time.
 Calculation: 9,999,999h ÷ 7,488h ≈ 1335.5 years
 24 hours/day x 26 days/month x 12 months = 7,488 hours/year
- Note: The excessive operation data of solenoid valve is saved when transitioning Bit0 of Process Data OUT from start to stop. Please save the data periodically on the master side in case of unpredictable situations such as a power failure. When turning off the power of the EVD, be sure to change the Process Data OUT pressure from zero (Bit16-31 = 0) to stop (Bit0 = 0) before turning off the power.

1.5.7 Diagnosis

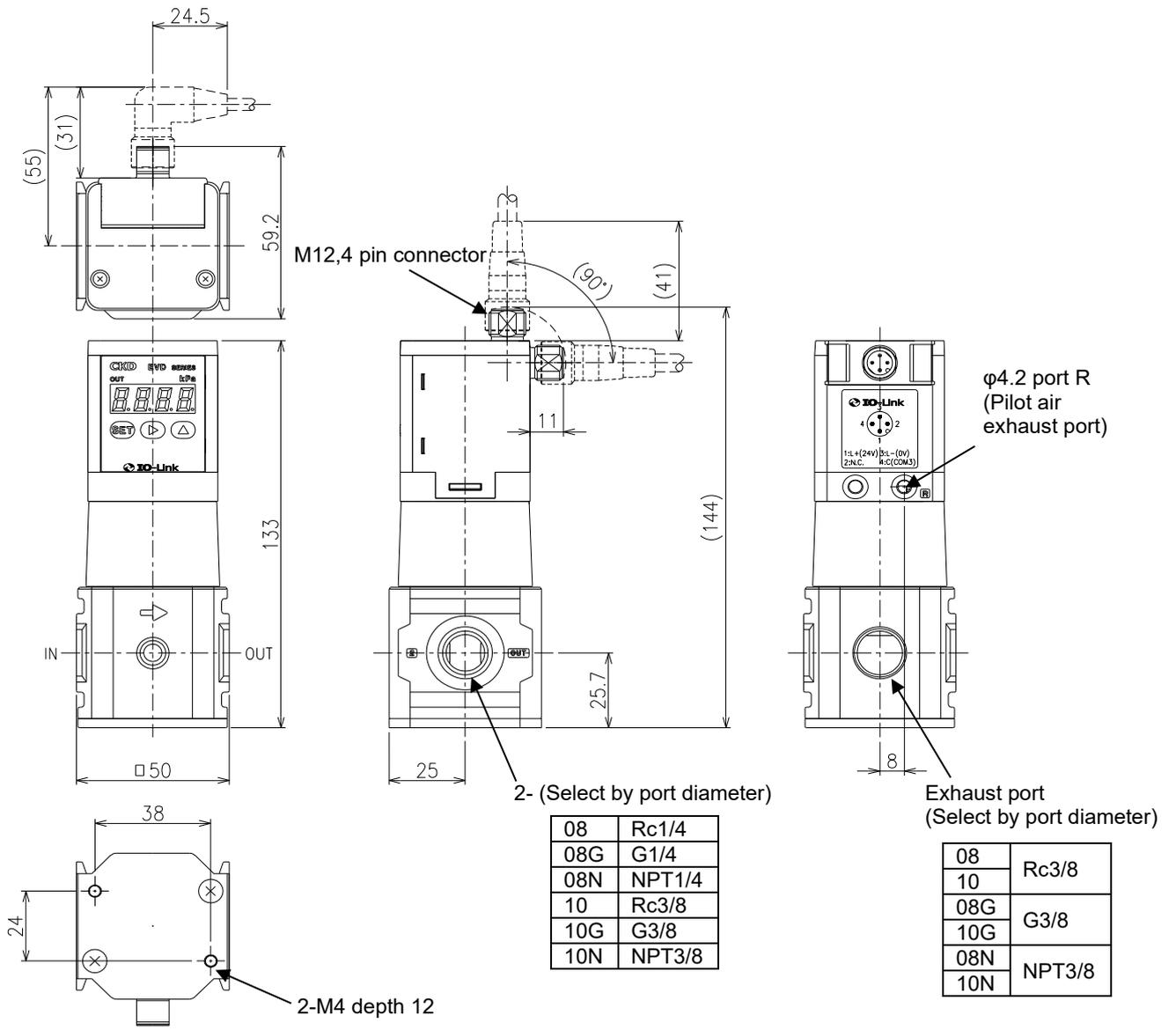
| Event code | Type | Device status | Error code | Cause | Solution |
|------------|---------|----------------------|------------|--|---|
| 0x8D02 | Error | Failure | E 01 | Supplied power voltage is outside the rated range. (Detected at 19.5 VDC or less, detection accuracy $\pm 10\%$ F.S.) | <ul style="list-style-type: none"> • Turn on the power again. |
| 0x8D03 | Error | Failure | E 02 | Input signal exceeds the rated range. | <ul style="list-style-type: none"> • Check the input settings. |
| 0x8D04 | Error | Failure | E 03 | ROM/RAM error | <ul style="list-style-type: none"> • Turn on the power again. |
| 0x8D05 | Error | Failure | E 04 | Memory read/write error | <ul style="list-style-type: none"> • Turn on the power again. |
| 0x8D06 | Error | Failure | E 05 | The pressure does not reach the set value for five or more consecutive seconds. | <ul style="list-style-type: none"> • Check the primary side pressure and set pressure value. • Turn on the power again. • Check that there is no leakage from the pipes, fittings, or other components, correctly connect the pipes and turn on the power again. |
| 0x8D10 | Warning | Out of specification | E 10 | Excessive operation of supply solenoid valve | <ul style="list-style-type: none"> • Check the operating environment. |
| 0x8D11 | Warning | Out of specification | E 11 | Excessive operation of exhaust solenoid valve | <ul style="list-style-type: none"> • Check the operating environment. |
| 0x8D12 | Warning | Out of specification | E 12 | Mode 2 of switch output 1 is set with abnormal threshold. <ul style="list-style-type: none"> • Lower limit > (Upper limit -10) for more than 5 seconds | <ul style="list-style-type: none"> • Check the threshold setting for mode 2 of switch output 1. |
| 0x8D13 | Warning | Out of specification | E 13 | Mode 2 of switch output 2 is set with abnormal threshold. <ul style="list-style-type: none"> • Lower limit > (Upper limit -10) for more than 5 seconds | <ul style="list-style-type: none"> • Check the threshold setting for mode 2 of switch output 2. |
| 0x4210 | Warning | Out of specification | E 14 | Temperature of IO-Link driver is high. | <ul style="list-style-type: none"> • Check the operating environment. |

1.6 Dimensions

■ EVD-1000 Series

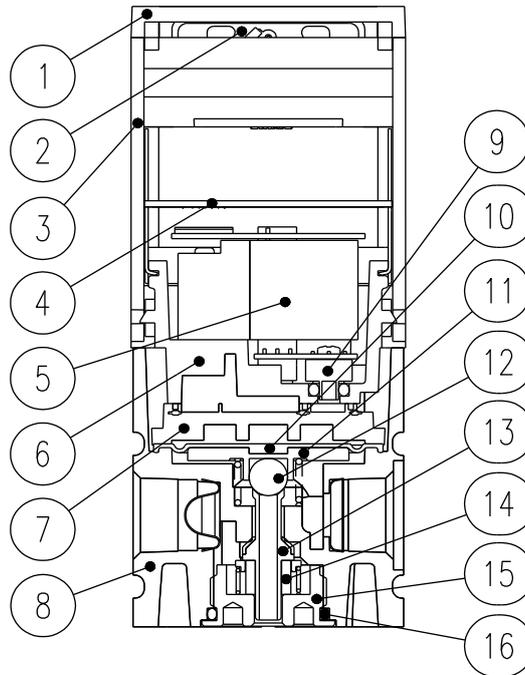


■ EVD-3000 Series



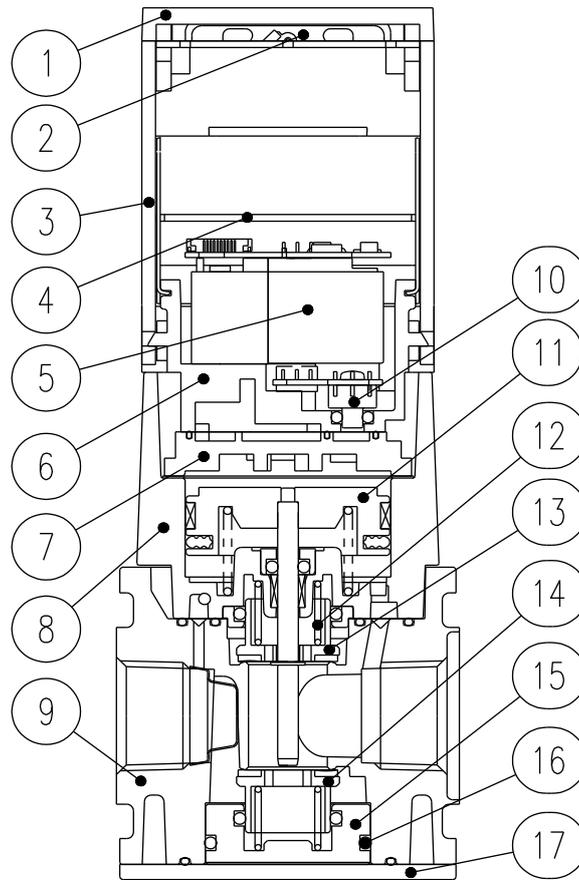
1.7 Internal structure

■ EVD-1000 Series



| No. | Part name | Material |
|------|----------------------------|---|
| [1] | Lid | PBT resin |
| [2] | M12 connector | ----- |
| [3] | Housing | ABS resin |
| [4] | Controller board | ----- |
| [5] | 3-way valve | ----- |
| [6] | Valve base | Polyphenylene sulfide resin |
| [7] | Pilot chamber | Polyphenylene sulfide resin |
| [8] | Body | Aluminum alloy die casting |
| [9] | Pressure sensor | ----- |
| [10] | Diaphragm | Special nitrile rubber |
| [11] | Relief sheet | Aluminum alloy |
| [12] | Steel ball (exhaust valve) | Stainless steel |
| [13] | Valve | Special nitrile rubber, stainless steel |
| [14] | Bottom rubber | Silicone rubber |
| [15] | Bottom plug | Brass, electroless nickel plating |
| [16] | O-ring | Fluoro rubber |

■ EVD-3000 Series



| No. | Part name | Material |
|------|----------------------|---------------------------------------|
| [1] | Lid | PBT resin |
| [2] | M12 connector | ---- |
| [3] | Housing | ABS resin |
| [4] | Controller board | ---- |
| [5] | 3-way valve | ---- |
| [6] | Valve base | Polyphenylene sulfide resin |
| [7] | Pilot chamber | Polyphenylene sulfide resin |
| [8] | Piston body assembly | Aluminum alloy die-casting, etc. |
| [9] | Body | Aluminum alloy die casting |
| [10] | Pressure sensor | ---- |
| [11] | Piston assembly | Aluminum alloy, stainless steel, etc. |
| [12] | Spring | Stainless steel |
| [13] | Top valve | Brass, special nitrile rubber |
| [14] | Bottom valve | Brass, special nitrile rubber |
| [15] | Bottom cap | Brass |
| [16] | O-ring | Nitrile rubber |
| [17] | Base plate | Steel plate |

2. INSTALLATION

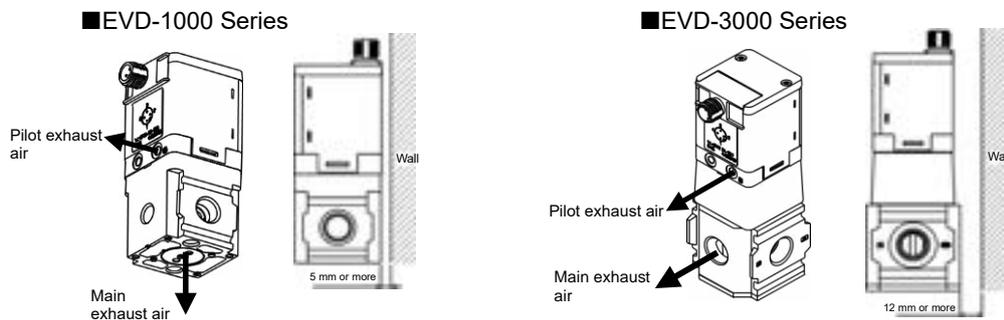
2.1 Installing

⚠ CAUTION

Secure sufficient space around the product for operation, mounting, removing, wiring, and piping.

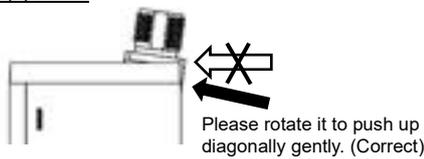
Install a pneumatic filter immediately before the circuit in which pneumatic components are used.

Install the product so that the exhaust port is not blocked and there is sufficient space for exhaust.



When changing the direction of the connector, do not force it in the direction of the arrow. The case may be damaged.

Side to top position

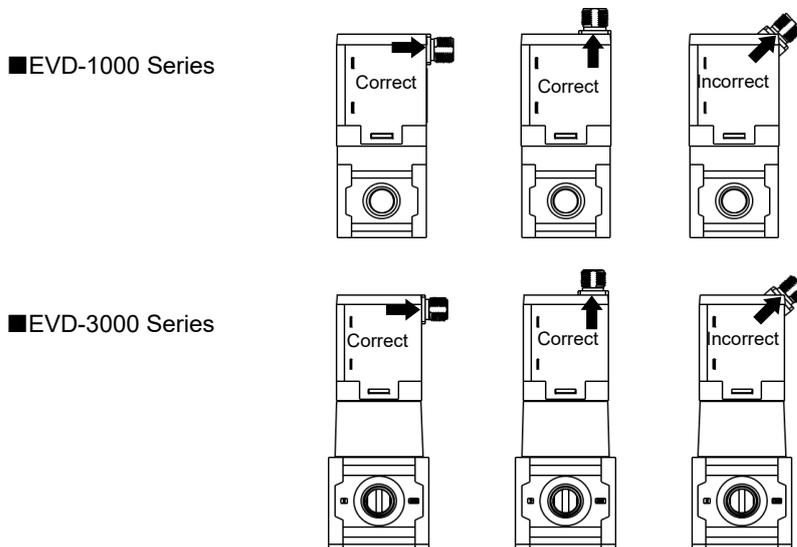


Top to side position



Make sure that the M12 connector faces up or sideways (not diagonally). If the cable can be moved, secure the cable.

The rotating mechanism of the M12 connector is not designed for use with cables that can move.

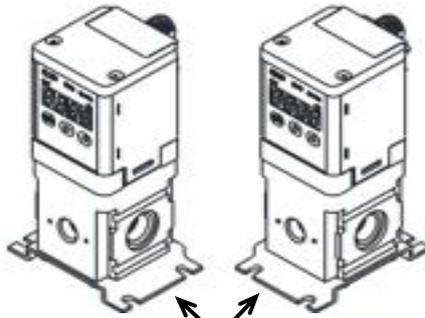


1 Attach the optional bracket to the bottom of the product using supplied mounting screws. For the optional bracket, refer to "6.1 Optional Part Model Number".

■ EVD-1000 Series



Cross headed pan machine screw with spring retainer M3 x 8 (4 screws supplied)



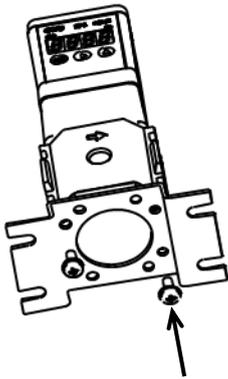
B-type can be installed in both directions.

B-type bracket (Option: -B1)

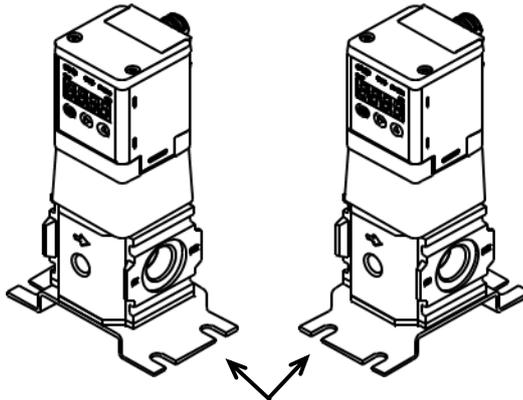


L-type bracket (Option: -L1)

■ EVD-3000 Series

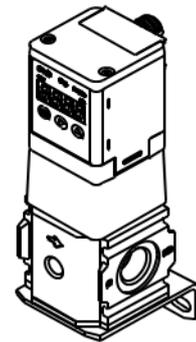


Cross headed pan machine screw with spring retainer M4 x 10 (2 screws supplied)



B-type can be installed in both directions.

B-type bracket (Option: -B3)



L-type bracket (Option: -L3)

2 Install the body to the specified position.

2.2 Piping

⚠ CAUTION

Do not remove the port seal until just before piping.

If the port seal is removed before the piping connection work, foreign matters may enter the interior from the piping ports, causing a failure or malfunction.

Fully flush and clean the air pipe before connection.

Open the exhaust port to the atmosphere.

The pressure cannot be properly controlled if the exhaust port is blocked with a plug.

Tighten the pipes with the appropriate tightening torque.

The purpose is to prevent air leakage and damage to the threads. To prevent damage to the screw threads, first use your hands to lightly tighten the pipe and use a tool to tighten the pipe further.

[Recommended tightening torque]

| Port screw | Tightening torque (N·m) |
|------------|-------------------------|
| 1/4 | 6 to 8 |
| 3/8 | 13 to 15 |

Do not apply high pressure suddenly when supplying the compressed air for the first time after connecting the pipes.

When supplying compressed air for the first time after piping is complete, make sure that there is no air leakage at the joints.

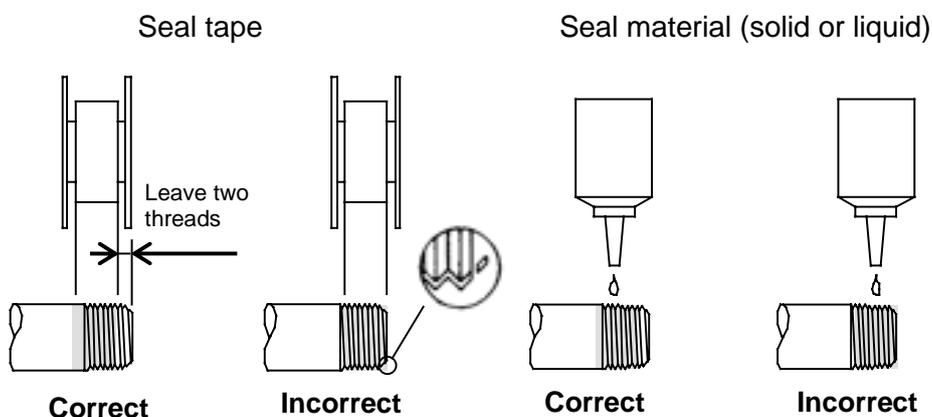
Apply leak detection agent to the joints in the piping using a brush to check for air leakage.

2.2.1 Seal material

Apply a seal tape or seal material at least 2 mm inside the tip of the threaded part. If it is protruding beyond the threaded portion of the piping, a shred of seal tape or residue of seal material may enter inside of the pipes or device and cause a failure.

When using a seal tape, wind it around the screw threads in the direction opposite from the screw threads and press it down with your fingers to attach it firmly.

When using a liquid seal material, be careful not to apply it to the resin parts. It damages the resin parts and causes a failure or malfunction. Also, do not apply it to the internal threads.



2.3 Wiring

WARNING

Check the connector pins and the cable conductor colors before wiring.

Incorrect wiring may cause damage, failure, and malfunctions of the product. Check the wire color described in the Instruction Manual before wiring.

Check the wiring insulation.

Make sure that the wires do not contact other circuits and there is no ground fault and insulation failure between terminals. Overcurrent may flow into the product and result in damage.

Use a DC stabilized power supply for the product that is within the rating and insulated from the AC power.

Uninsulated power may cause an electric shock.

If the power is not stabilized, the peak value may exceed the rating. This may damage the product or lead to poor accuracy.

Stop the control device and the machinery and turn off the power before wiring.

Operating the product suddenly may cause an unexpected behavior and a dangerous situation. Perform an electrical current test with the control device and the machinery stopped and set the required data. Discharge static electricity from your body, tools, and devices before and during work. For movable sections, use wiring material with the same level of bending resistance as the robot wire.

Do not apply AC power.

If AC power (100 VAC) is applied, the product may burst or an electric shock or a fire may occur.

Do not short-circuit the load.

The product may burst or burn.

CAUTION

Insulate unused wires to avoid contact with other wires.

Connecting unused wiring to ground, etc. by mistake may cause damage or malfunctions of the product.

If extending the cable, be less than the cable length of 20 m from the master to the device (this product).

Connecting unused wiring to ground, etc. by mistake may cause damage or malfunctions of the product.

When using a cable other than the optional cable, use a cable that adapts to the IO-Link communication specifications.

Wiring colors and pin assignments are determined by IO-Link communication specifications.

Depending on the cable, the relationship between the wiring color and the pin arrangement may not match, resulting in incorrect wiring.

2.3.1 M12 connector

⚠ CAUTION

Do not rotate the M12 connector.

The L-type cable connector does not rotate. Never turn it.

Turn off the power before inserting or removing the M12 connector.

Be sure to turn off the power before inserting or removing the M12 connector.

Always hold the connector when inserting or removing the M12 connector.

Do not pull on the cable.

When fitting the M12 connector, align the convex part of the main unit side connector terminal with the concave part of the cable connector terminal.

After inserting it securely, hold the knurled part and tighten it clockwise so as not to damage the thread.

Be careful not to over-screw the connector.

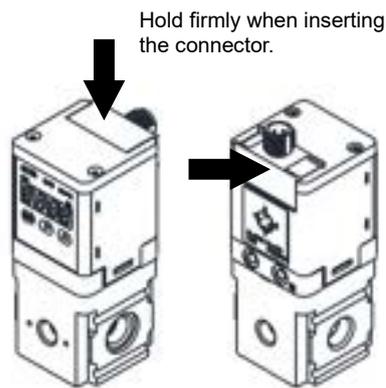
If the connector is screwed excessively, the connector on the main unit may be damaged.

Recommended torque: 0.4 to 0.49 N·m

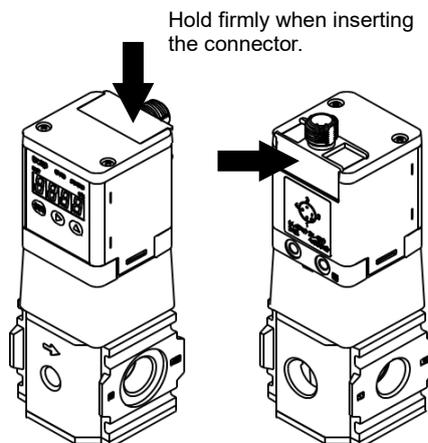
Hold the M12 connector firmly so that it faces up or sideways when inserting it.

The rotating mechanism of the connector housing allows a 90-degree rotation.

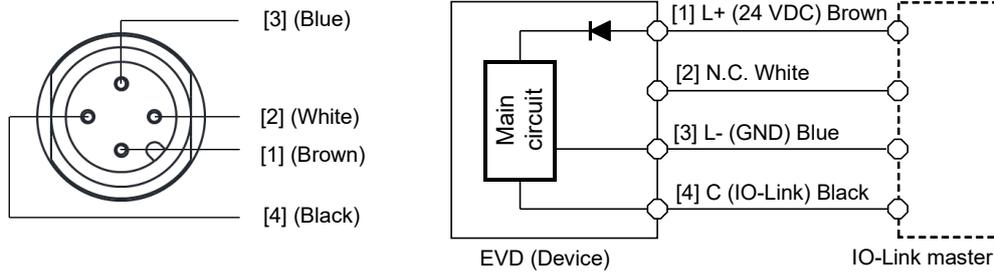
■EVD-1000 Series



■EVD-3000 Series



2.3.2 Cable connection



| Terminal No. | Option cable color | Part Name |
|--------------|--------------------|-------------|
| [1] | Brown | L+ (24 VDC) |
| [2] | White | N.C. |
| [3] | Blue | L- (GND) |
| [4] | Black | C (IO-Link) |

- * **The optional cable for our electro-pneumatic regulator EVR and EVS2 series is M12 connector type and can be connected to the connectors of this product. However, the relationship of terminal number and wiring color is different from the IO-Link cable specifications. Do not use it as it may lead to miswiring.**

Relevant model numbers: EVR-S1 / EVR-S3 / EVR-L1 / EVR-L3 / EV2000-C11 / EV2000-C13

3. USAGE

⚠ CAUTION

Create a program and control circuit that ignores signals for approximately two seconds immediately after energized.

Pressure control will not operate for approximately two seconds immediately after energized for self-diagnosis.

Stop the device before changing the set output value.

Control system devices may operate unintentionally.

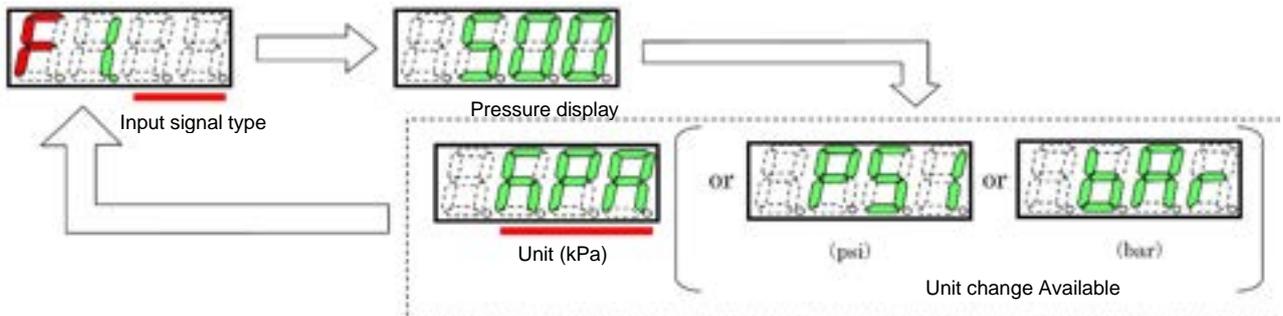
Release the key lock before changing settings.

3.1 Checking the Set Value (RUN Mode)

3.1.1 Input specification setting

The F1 screen shows the input specification and its set value.

The current input specification setting, pressure value and unit are displayed alternately.

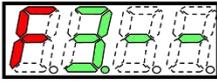


| Input signal type code | Description |
|------------------------|--|
| | IO-Link communication 16bit input 16-bit input via Process Data OUT |
| | Preset memory input Input of 3-bit using Process Data OUT Displays the selected preset No. |
| | Direct memory input |

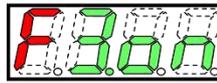
3.1.2 Automatic power off

The F3 screen shows whether the automatic power off is enabled or disabled.

When the function is disabled:



When the function is enabled:

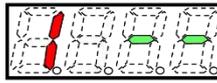
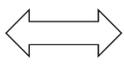
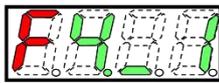


3.1.3 Switch output

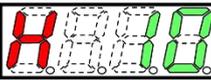
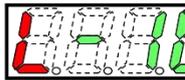
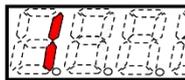
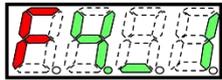
The F4 screen shows whether the switch output is enabled or disabled and its set value.

● Switch output 1

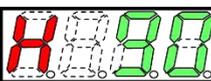
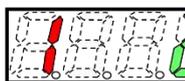
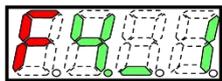
When the function is disabled:



"Mode 1":

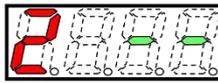
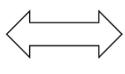
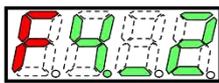


"Mode 2":

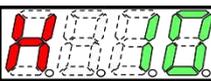
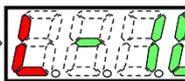
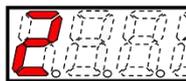
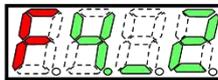


● Switch output 2

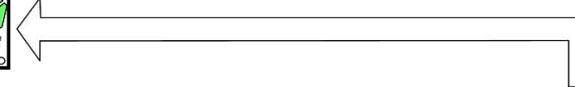
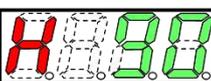
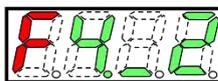
When the function is disabled:



"Mode 1":



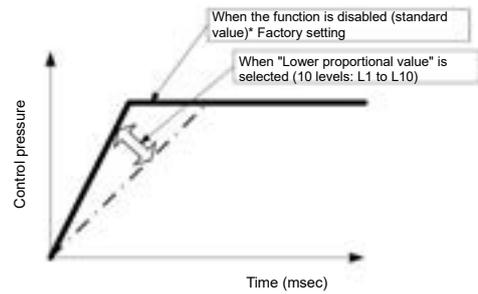
"Mode 2":



3.1.4 Proportional value setting

In the F5 screen, whether the proportional value change is enabled or disabled and its set level can be confirmed.

- When disabled: Controls with standard values (factory setting).
- When enabled: "Higher proportional value" or "Lower proportional value" can be selected. The set value can be selected from 10 levels only when "Lower proportional value" is selected.



Proportional value change function image diagram

Note) The figure above is reference. The actual values will change depending on the piping and load conditions.

■ Effect of increasing the proportional value

A higher accuracy control can be achieved depending on the piping and load capacity conditions.

Note that hunting will occur easily.

■ Effect of decreasing the proportional value

More stable control can be achieved depending on the piping and load capacity conditions. It is effective especially if control pressure fluctuates significantly or hunting occurs.

When the function is disabled



When "Higher proportional value" is selected (H)



When "Lower proportional value" is selected (L)

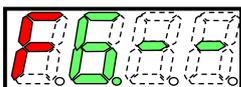


Set level

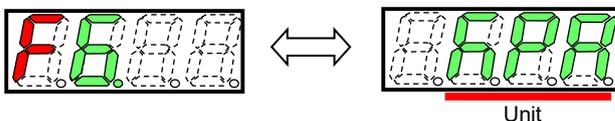
3.1.5 Unit change

The Screen F6 shows the unit.

When the Unit setting none:



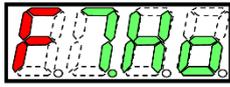
When the Unit setting available:



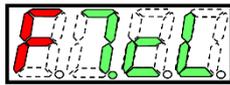
3.1.6 Communication error setting

The screen F7 shows the set value for the communication error setting.

For HOLD:



For CLEAR:



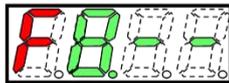
| Cause | State | When an error occurs | | | When an error is recovered | | |
|---------------------|---------------|--|--|--|--|--|--|
| | | Normal mode | Preset mode | Direct mode | Normal mode | Preset mode | Direct mode |
| Communication error | Hold setting | Control pressure is held at the Process Data Out setting before the error occurred | Control pressure is held at preset setting before the error occurred | Control pressure is controlled with direct setting value | Control pressure is controlled with Process Data Out setting value | Control pressure is controlled with preset setting value | Control pressure is controlled with direct setting value |
| | Clear setting | Control pressure 0 | Control pressure 0 | Control pressure is controlled with direct setting value | Control pressure is controlled with Process Data Out setting value | Control pressure is controlled with preset setting value | Control pressure is controlled with direct setting value |

- * Communication error: A communication error is defined that Process Data Status is invalid or Process Data Out is invalid. When the C/Q line is disconnected, it becomes invalid. If the IO-Link master and its upper network are disconnected, Process Data Out is disabled. (Depending on the specification of the IO-Link master, Process Data Out may not be disabled even if it is disconnected. Please check the specifications of the master.)
- * HLD/CLEAR: This switch controls the operation when an error occurs in the communication function. It can be set using "On-request Data" in IO-Link communication.

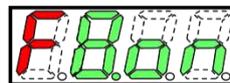
3.1.7 Input zero operation stop function

The screen F8 shows whether the input zero operation stop function is enabled or disabled.

When the function is disabled:



When the function is enabled:



3.2 How to set (Setting mode)

3.2.1 Setting range for each function

| Function | Display | Description | Specifications |
|--|---------|------------------------------|--|
| F1: Input specification setting - For preset mode - "F1.P1" "F1.P8" | | Sets a set value (pressure). | Range: Note 1 1100 / 000 to 100 1500 / 000 to 500 1900 / 000 to 900 Min. set unit: 1 kPa |
| F1: Input specification setting - For direct mode - "F1.dr" | | Sets a set value (pressure). | Range: Note 1 1100 / 000 to 100 1500 / 000 to 500 1900 / 000 to 900 Min. set unit: 1 kPa |
| F3: Automatic power off "F3. " | | Sets enable/disable. | Disable: -- Enable: on |
| F4: Switch output - For mode 1 - * Common to switch output 1 and 2 "1__1", "2__1" | | Sets a "-" set value. | Range: 00 to 50 Min. set unit: 1% |
| | | Sets a "+" set value. | Range: 00 to 50 Min. set unit: 1% |
| F4: Switch output - For mode 2 - * Common to switch output 1 and 2 "1__2", "2__2" | | Sets a lower limit value. | Range: 00 to 90 Note 2 Min. set unit: 1% |
| | | Sets an upper limit value. | Range: 100 to 010 Note 2 Min. set unit: 1% |
| F5: Proportional value setting - For "Higher proportional value" - "F5. H" | | Cannot set a level. | |
| F5: Proportional value setting For "Lower proportional value" "F5. L" | | Sets a level. | Range: 01 to 10 Min. set unit: 1 |
| F6: Unit change *Selection option: KA only "F6. " | | Sets a unit. | kPa (default) psi bar |
| F7: Communication error setting "F7. " | | Sets CLEAR/HOLD. | CLEAR HOLD |
| F8: Input zero operation function "F8. " | | Sets disable/enable. | Disable: -- Enable: on |

Note 1: If a pressure value is set to 1%FS or less, pressure may not be controlled due to residual pressure.

Note 2: The setting range may be limited depending on the set value.

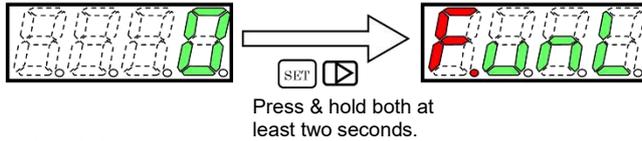
3.2.2 Key lock

Key lock prevents incorrect operation.

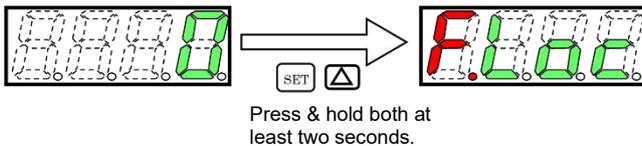
When the power is turned on (including re-turn on), the key is locked. Release the key lock before changing the setting.

How to operate (key operation)

- Release key lock



- Lock key



How to operate (IO-Link communication)

[Parameter settings]

- Release key lock
Write "0:Unlock" to Index: 0x010E.
- Lock key
Write "1:Lock" to Index: 0x010E.

Parameter and Command

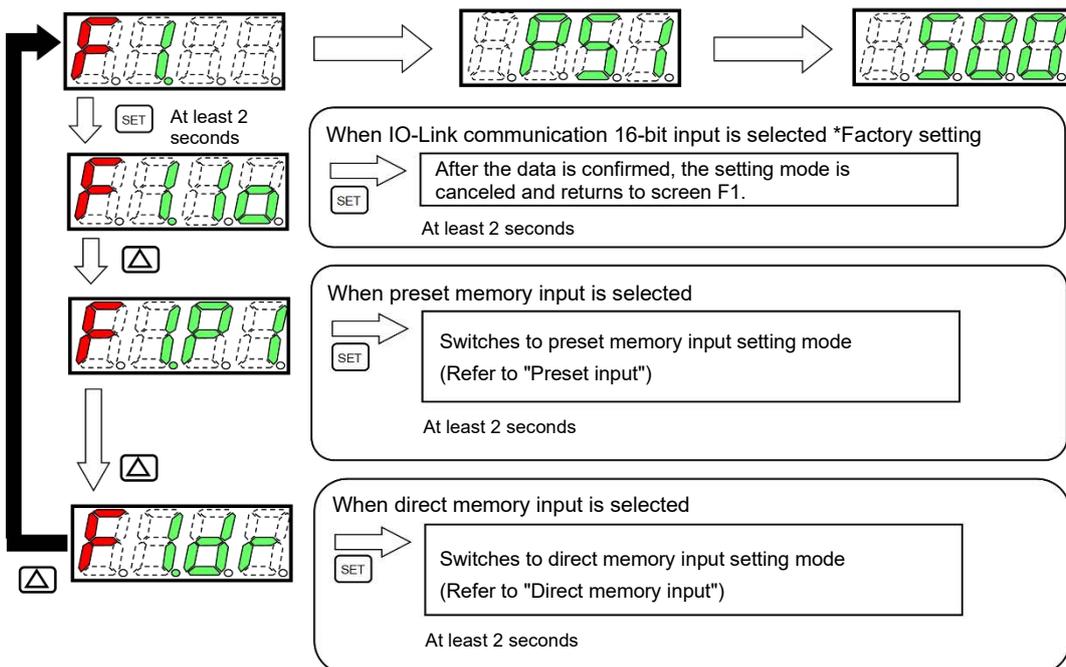
| Index | Sub Index | Item | Value |
|--------|-----------|------------------|----------------------|
| 0x010E | 0 | Key lock setting | 0: Unlock 1: Lock |

3.2.3 Input specification setting

How to operate (key operation)

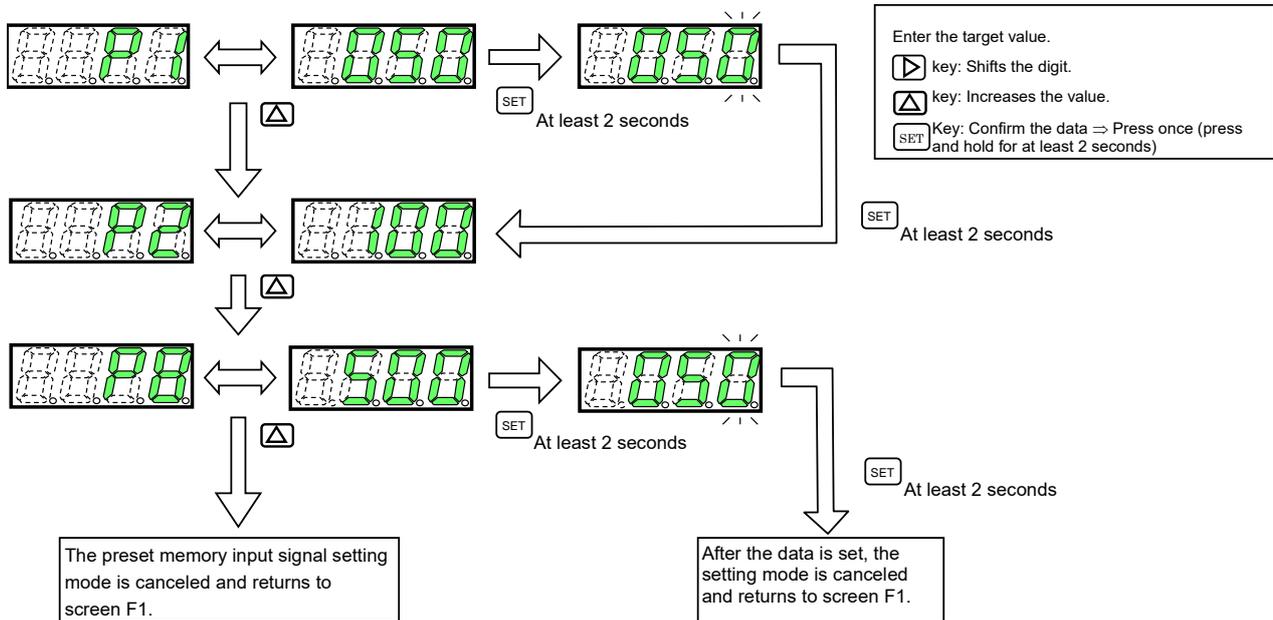
In F1 screen, press and hold the [SET] key at least two seconds to switch to the setting mode. For how to set using IO-Link communication, refer to ("3.3 Control procedure using IO-Link communication").

(Note) The 16-bit value entered using IO-Link communication cannot be changed by key operation.



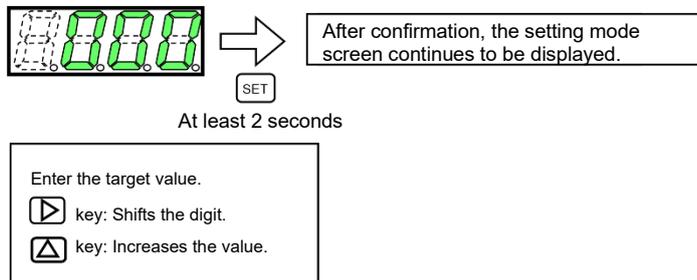
■ Preset input

Press and hold the [SET] key at least two seconds with the preset input selected in F1 screen.



■ Direct memory input

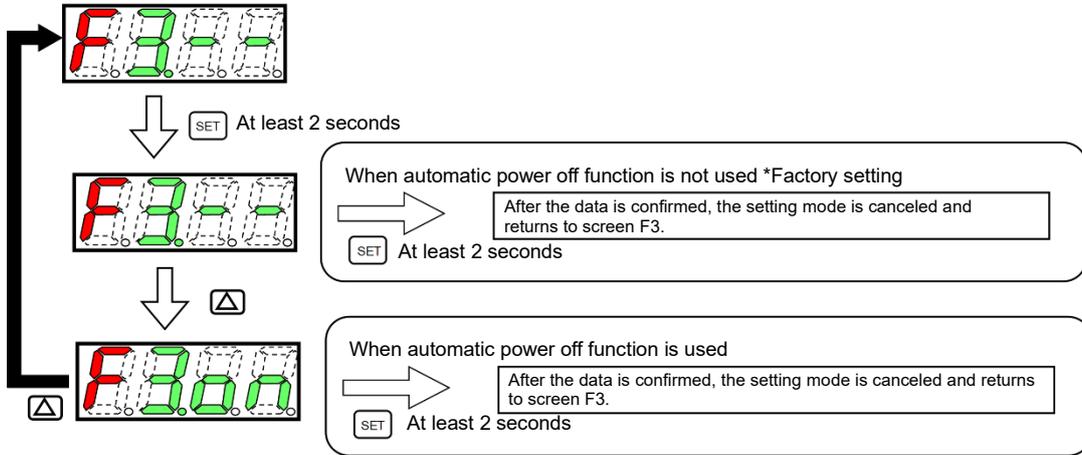
Press and hold the [SET] key at least two seconds with the direct memory input selected in F1 screen.



3.2.4 Automatic power off

How to operate (key operation)

In F3 screen, press and hold the [SET] key at least two seconds to switch to the setting mode.



How to operate (IO-Link communication)

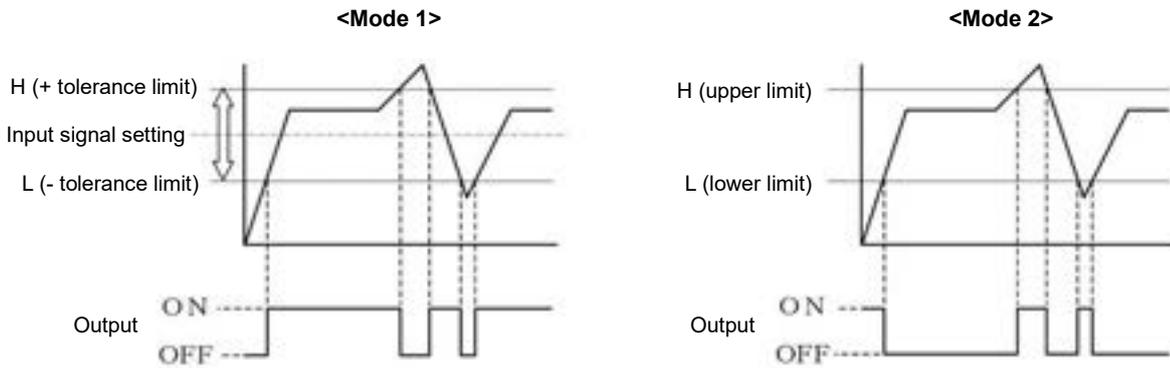
[Parameter settings]

- Automatic power off setting "OFF"
Write "0: OFF" to Index: 0x010D.
- Automatic power off setting "ON"
Write "1: ON" to Index: 0x010D.

Parameter and Command

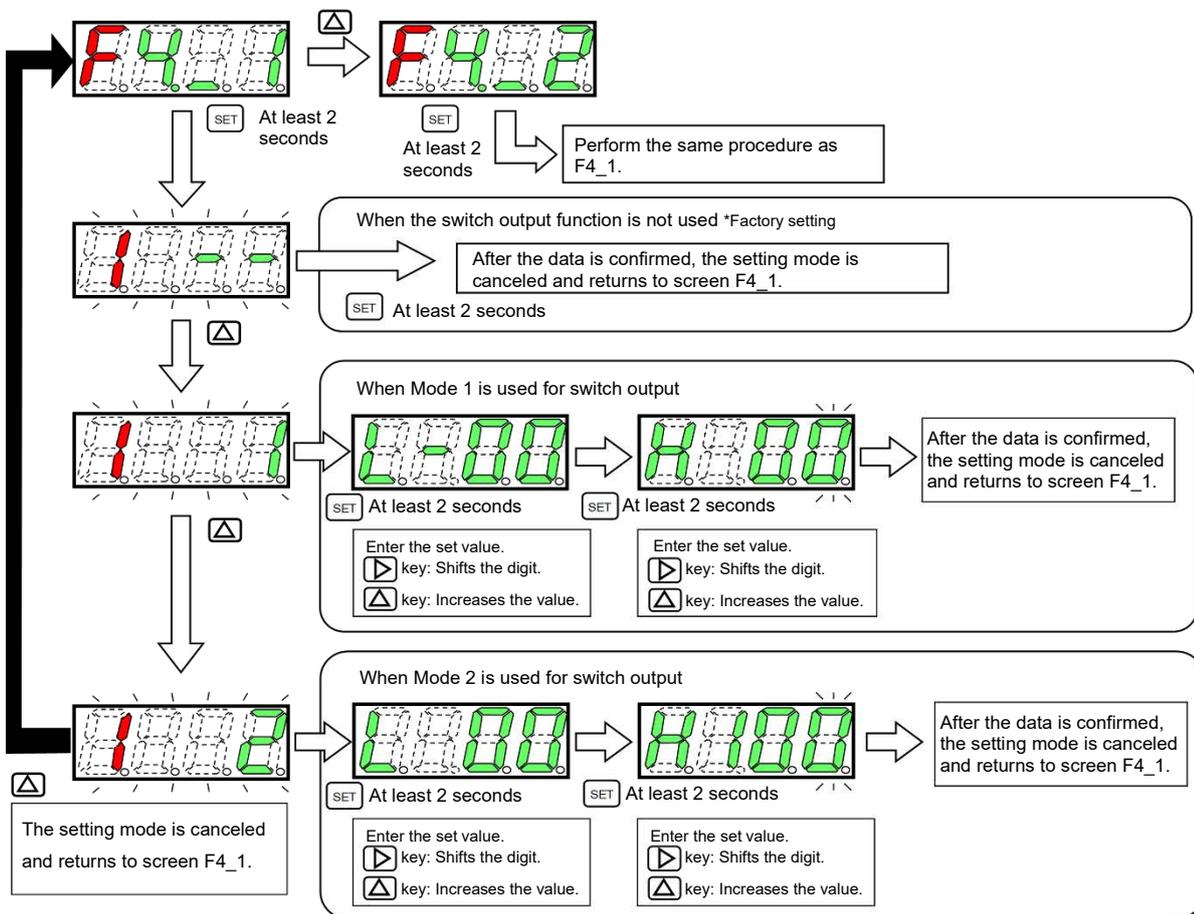
| Index | Sub Index | Item | Value |
|--------|-----------|-----------------------------|-----------------|
| 0x010D | 0 | Automatic power off setting | 0: OFF 1: ON |

3.2.5 Switch output



How to operate (key operation)

In F4_1 and F4_2 screens, press and hold the [SET] key at least two seconds to switch to the setting mode.



■ How to operate (IO-Link communication)

[Parameter settings]

○ **Switch output 1 setting**

• Switch output 1 OFF setting
Write "0: OFF" to Index: 0x0101.

• Switch output 1 mode 1 setting
Write "1: mode 1" to Index: 0x0101.
Write the lower limit value of Mode 1 to Index: 0x0103.
Write the upper limit value of Mode 1 to Index: 0x0104.

• Switch output 1 mode 2 setting Note 2
Write "2: mode 2" to Index: 0x0101.
Write the lower limit value of Mode 2 to Index: 0x0105.
Write the upper limit value of Mode 2 to Index: 0x0106.

Parameter and Command

| Index | Sub Index | Item | Value |
|--------|-----------|--|----------------------------------|
| 0x0101 | 0 | Switch output 1 Mode selection | 0: OFF 1: Mode 1 2: Mode 2 |
| 0x0103 | 0 | Switch output 1 Mode 1 Lower limit value | 0 to 50 Note |
| 0x0104 | 0 | Switch output 1 Mode 1 Upper limit value | 0 to 50 Note |
| 0x0105 | 0 | Switch output 1 Mode 2 lower limit value | 0 to 90 Note |
| 0x0106 | 0 | Switch output 1 Mode 2 upper limit value | 10 to 100 Note |

○ **Switch output 2 setting**

• Switch output 2 OFF setting
Write "0: OFF" to Index: 0x0102.

• Switch output 2 mode 1 setting
Write "1: mode 1" to Index: 0x0102.
Write the lower limit value of Mode 1 to Index: 0x0107.
Write the upper limit value of Mode 1 to Index: 0x0108.

• Switch output 2 mode 2 setting Note 2
Write "2: mode 2" to Index: 0x0102.
Write the lower limit value of Mode 2 to Index: 0x0109.
Write the upper limit value of Mode 2 to Index: 0x010A.

Parameter and Command

| Index | Sub Index | Item | Value |
|--------|-----------|--|----------------------------------|
| 0x0102 | 0 | Switch output 2 Mode selection | 0: OFF 1: Mode 1 2: Mode 2 |
| 0x0107 | 0 | Switch output 2 Mode 1 Lower limit value | 0 to 50 Note |
| 0x0108 | 0 | Switch output 2 Mode 1 Upper limit value | 0 to 50 Note |
| 0x0109 | 0 | Switch output 2 Mode 2 lower limit value | 0 to 90 Note |
| 0x010A | 0 | Switch output 2 Mode 2 upper limit value | 10 to 100 Note |

Note 1: The set value represents a percentage of the full scale (F.S.)
(e.g.) To set a pressure of 100 kPa for 500 kPa type,
set 20 by calculating as follows:
 $100/500 \times 100 = 20$.

Note 2: When using Mode 2, set the value so that (Lower limit value + 10) ≤ Upper limit value.
If this condition is not met, the warning (Bit 14) of PD4 in Process Data IN becomes "1: ON" and the SW output is always OFF. 0x8D12 or 0x8D13 is generated in the Event Code of Diagnosis. 12 or 13 is displayed as the error code (Bit4-7) of PD5. For details, see 1.5.7 Diagnosis and 5.2 Error Code.

[Confirmation]

Process Data IN

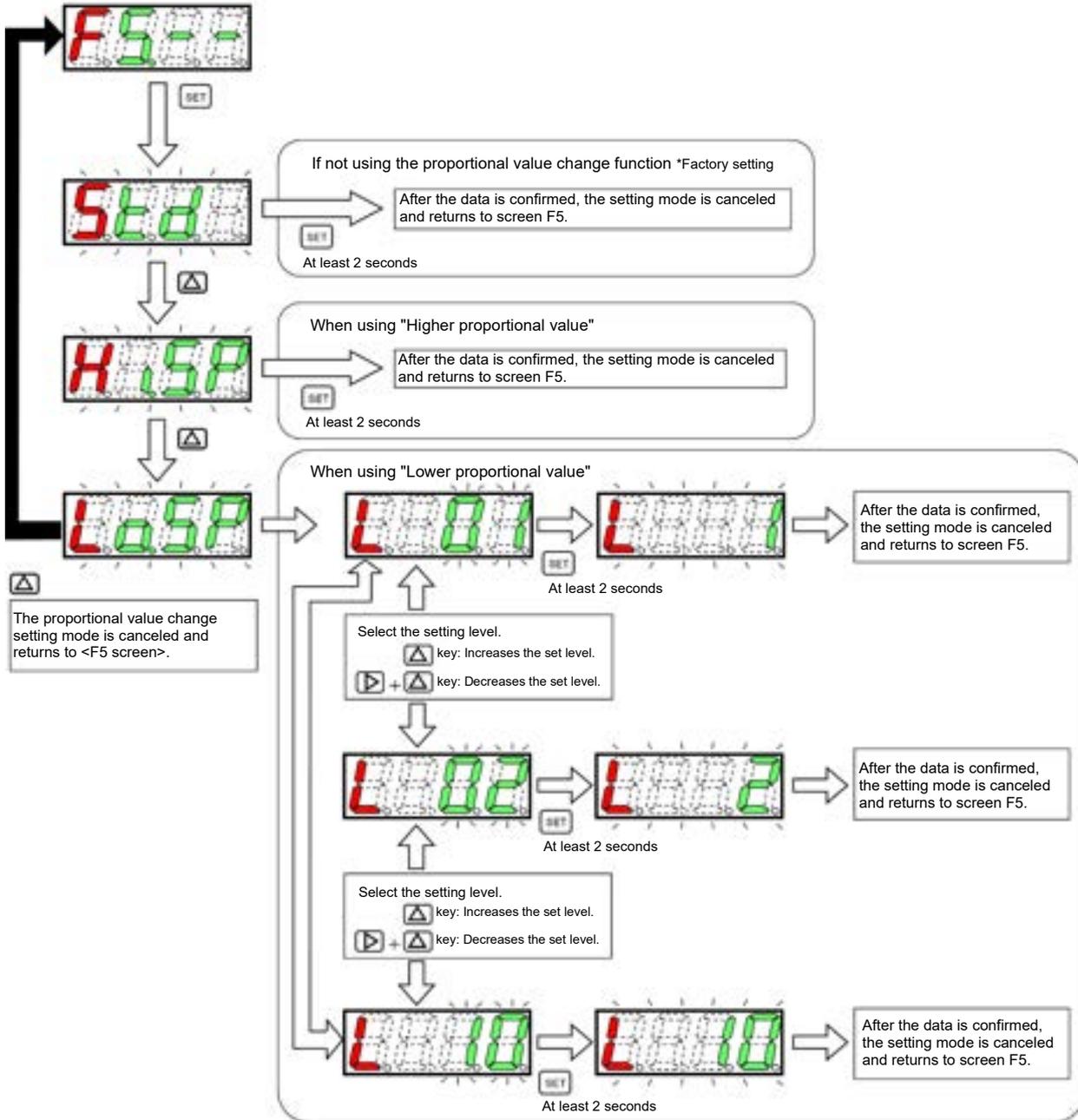
| PD | PD4 | | | | | | | | PD5 | | | | | | | |
|-----------|-------|---------|------------------|----|----|----|---------------|---|------------|---|---|-----|---------------|---|---|------------|
| | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Data name | Error | WARNING | Normal operation | - | - | - | Switch output | | MSB | | | LSB | Input setting | | - | Start/Stop |
| | | | | | | | 2 | 1 | Error code | | | | | | | |

Check the Switch output of the Process Data IN.
Switch output 1 is stored in Bit 8, and Switch output 2 is stored in Bit 9.
For the Output, "0: OFF" and "1: ON".

3.2.6 Proportional value setting

How to operate (key operation)

In the F5 screen, press and hold the [SET] key at least two seconds to switch to the setting mode.



* For "Lower proportional value", operation takes place with the set level displayed on the screen while selecting a set level. When the set level is determined, press and hold the [SET] key at least two seconds to confirm the value.

■ How to operate (IO-Link communication)

[Parameter settings]

- Standard setting for proportional value
Write "0: OFF" to Index: 0x010B.

- Higher proportional value setting
Write "1: Higher proportional value" to Index: 0x010B.

- Lower proportional value setting
Write "2: Lower proportional value" to Index: 0x010B.
Write the "set level" to Index: 0x010C.

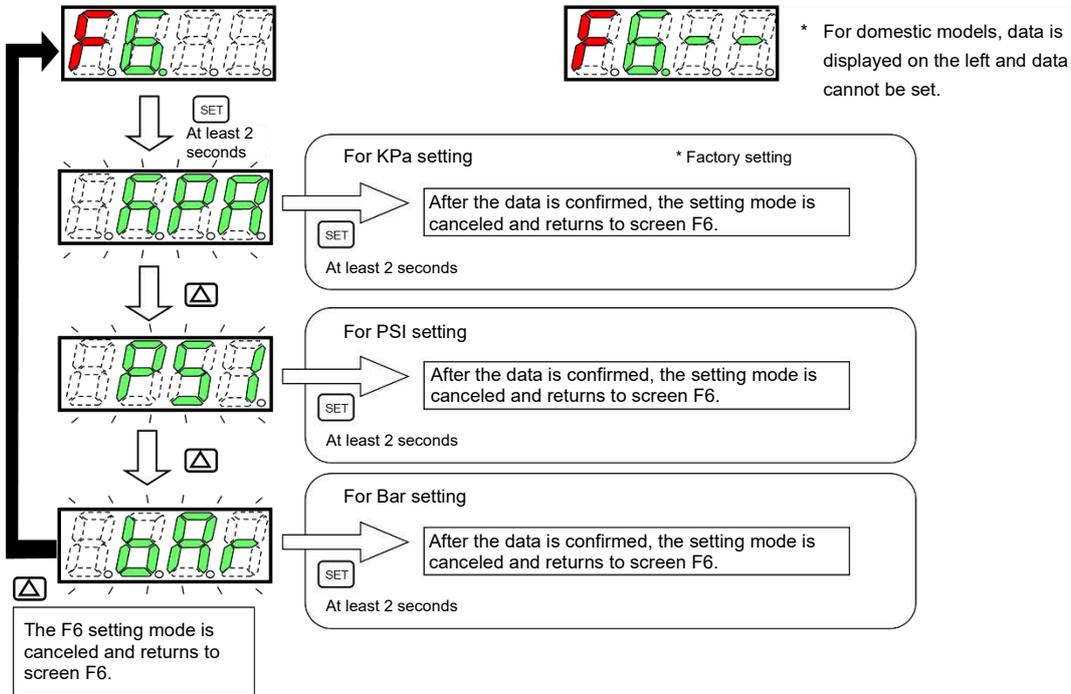
Parameter and Command

| Index | Sub Index | Item | Value |
|--------|-----------|---|---|
| 0x010B | 0 | Proportional value setting | 0: OFF 1: Higher proportional value 2: Lower proportional value |
| 0x010C | 0 | Set level when setting Lower proportional value | 1 to 10 |

3.2.7 Unit change (KA type only)

How to operate (key operation)

In the F6 screen, press and hold the [SET] key at least two seconds to switch to the setting mode.



* When using psi or bar, please use the attached unit seal. (Refer to "1.1 Part Name").

How to operate (IO-Link communication)

[Parameter settings]

- Unit change
Write a desired unit "0: kPa", "1: psi" or "2: bar" to Index: 0x0118.

Parameter and Command

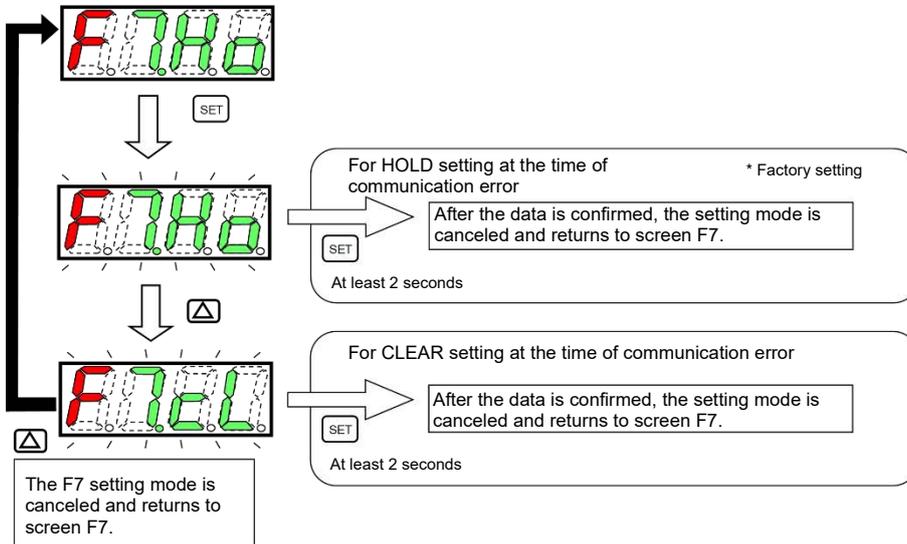
| Index | Sub Index | Item | Value |
|--------|-----------|-------------|----------------------------|
| 0x0118 | 0 | Unit change | 0: kPa 1: psi 2: bar |

* When "Unit change none" is selected, only "0: kPa" is writable. Writing any other value results in a write error.

3.2.8 Operation setting when communication error occurs

How to operate (key operation)

In the F7 screen, press and hold the [SET] key at least two seconds to switch to the setting mode.



How to operate (IO-Link communication)

[Parameter settings]

- Hold settings
Write "0: HOLD" to Index: 0x011A.
- Clear settings
Write "1: CLEAR" to Index: 0x011A.

Parameter and Command

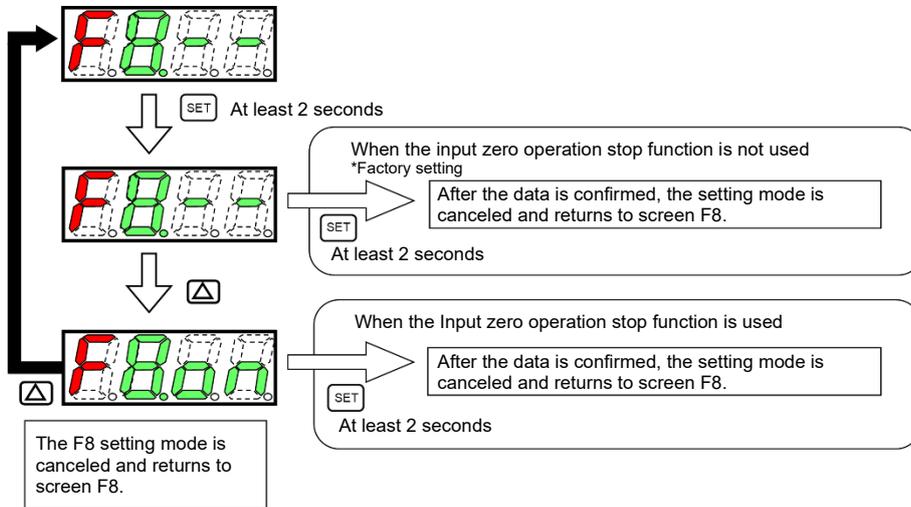
| Index | Sub Index | Item | Value |
|--------|-----------|-----------------------------|---------------------|
| 0x011A | 0 | Communication error setting | 0: HOLD 1: CLEAR |

* The communication error is defined that a Process Data Status is invalid or Process Data Out is invalid. When the C/Q line is disconnected, it becomes invalid. If the IO-Link master and its upper network are disconnected, Process Data Out is disabled. (Depending on the specification of the IO-Link master, Process Data Out may not be disabled even if it is disconnected. Please check the specifications of the master.) This applies only to the Normal and Preset modes. In the Direct mode, the operation continues even if a communication error occurs.

3.2.9 Input zero operation stop setting

How to operate (key operation)

In the F8 screen, press and hold the [SET] key at least two seconds to switch to the setting mode.



How to operate (IO-Link communication)

[Parameter settings]

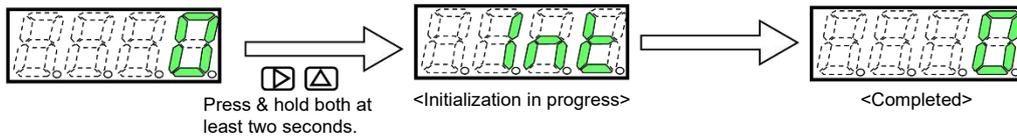
- OFF setting
Write "0: OFF" to Index: 0x0100.
- ON setting
Write "1: ON" to Index: 0x0100.

Parameter and Command

| Index | Sub Index | Item | Value |
|--------|-----------|------------------------------------|-----------------|
| 0x0100 | 0 | Input zero operation stop function | 0: OFF 1: ON |

3.2.10 Factory setting mode (initialization)

How to initialize



Factory setting

| Function | Part Name | Display | Description |
|----------|-------------------------------|---------|--|
| F1 | Input specification setting | | Normal mode |
| F3 | Automatic power off | | Automatic power off disabled |
| F4_1 | Switch output 1 | | Switch output disabled |
| F4_2 | Switch output 2 | | Switch output disabled |
| F5 | Proportional value setting | | Standard setting (Proportional value setting disabled) |
| F6 | Unit switching Note 1 | | kPa setting |
| F7 | Communication error setting | | Hold setting |
| F8 | Input zero operation function | | input zero operation disabled |

Note 1: This function is enabled when "Unit change available" is selected.
 "F6--" is displayed when "Unit change none" is selected.

3.3 Control procedure using IO-Link communication

3.3.1 Normal mode

The pressure can be controlled with the "Set value for pressure" of the Process Data OUT. The set value cannot be changed by key operation.

■ Setting method using IO-Link communication

[Parameter settings]

• Input signal setting

Write "0: Normal Mode" to Index: 0x010F (input setting).

Parameter and Command

| Index | Sub Index | Item | Value |
|--------|-----------|---------------|---|
| 0x010F | 0 | Input setting | 0 : Normal Mode 1 : Preset Mode 2 : Direct Mode |

[Operation]

Process Data OUT

| PD | PD0 | | | | | | | | PD1 | | | | | | | |
|-----------|--------------|----|----|----|----|----|----|----|-----|----|----|----|----|----|----|-----|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 |
| | MSB | | | | | | | | | | | | | | | LSB |
| Data name | Set pressure | | | | | | | | | | | | | | | |

| PD | PD2 | | | | | | | | PD3 | | | | | | | |
|-----------|----------|----|----|----|----|--------|---|---|----------|---|---|---|---|---|---|------------|
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Data name | Not used | | | | | Preset | | | Not used | | | | | | | Start/Stop |
| | | | | | | 3 | 2 | 1 | | | | | | | | |

⇓
"1"

• Setting active state (pressure controlled state)

Set the "Start/Stop" bit of the Process Data OUT to "1" to activate.

Pressure can be controlled by setting the "Set value for pressure" of Process Data OUT.

• Set pressure range for each model and unit

| Model | Select unit | Process Data OUT | Set pressure | Note |
|--------------------------------|-------------|------------------|----------------|-----------------------|
| EVD-1100-C EVD-3100-C | kPa fixed | 0 to 1000 | 0.0 to 100.0 | - |
| EVD-1500-C EVD-3500-C | kPa fixed | 0 to 5000 | 0.0 to 500.0 | - |
| EVD-1900-C EVD-3900-C | kPa fixed | 0 to 9000 | 0.0 to 900.0 | - |
| EVD-1100-C*KA EVD-3100-C*KA | kPa | 0 to 1000 | 0.0 to 100.0 | Unit change available |
| | psi | 0 to 1450 | 0.00 to 14.50 | |
| | bar | 0 to 1000 | 0.000 to 1.000 | |
| EVD-1500-C*KA EVD-3500-C*KA | kPa | 0 to 5000 | 0.0 to 500.0 | Unit change available |
| | psi | 0 to 7250 | 0.00 to 72.50 | |
| | bar | 0 to 5000 | 0.000 to 5.000 | |
| EVD-1900-C*KA EVD-3900-C*KA | kPa | 0 to 9000 | 0.0 to 900.0 | Unit change available |
| | psi | 0 to 1305 | 0.0 to 130.5 | |
| | bar | 0 to 9000 | 0.000 to 9.000 | |



- A pressure setting shall be entered in 4 digits. When you do not use IODD, you do not need to enter a decimal point; when you use IODD, you must include a decimal point.
- Do not enter a value outside the allowable range. User's programs should control the Process Data OUT setting so that it is within the allowable range.

[Confirmation]
Process Data IN

| PD | PD0 | | | | | | | | PD1 | | | | | | | |
|-----------|---|----|----|----|----|----|----|----|-----|----|----|----|----|----|----|-----|
| Bit | 47 | 46 | 45 | 44 | 43 | 42 | 41 | 40 | 39 | 38 | 37 | 36 | 35 | 34 | 33 | 32 |
| | MSB | | | | | | | | | | | | | | | LSB |
| Data name | Set pressure ← The value of the "Set value for pressure" of the Process Data OUT is displayed here. | | | | | | | | | | | | | | | |

| PD | PD2 | | | | | | | | PD3 | | | | | | | |
|-----------|---|----|----|----|----|----|----|----|-----|----|----|----|----|----|----|-----|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 |
| | MSB | | | | | | | | | | | | | | | LSB |
| Data name | Controlled pressure ← EVD's controlled pressure value is displayed here | | | | | | | | | | | | | | | |

| PD | PD4 | | | | | | | | PD5 | | | | | | | |
|-----------|-------|---------|------------------|----|----|----|---------------|---|------------|---|---|-----|---------------|---|---|------------|
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | - | - | - | - | - | - | - | - | - | - | - | - | 0 | 0 | - | 1 |
| Data name | Error | WARNING | Normal operation | - | - | - | Switch output | | MSB | | | LSB | Input setting | | - | Start/Stop |
| | | | | | | | 2 | 1 | Error code | | | | | | | |

The controlled pressure, start/stop status, input setting, and set pressure can be checked with the Process Data IN.
The current set pressure should be checked with the "Set value for pressure" of the Process Data IN.

 When the "Start/Stop" bit of Process Data IN is set to "0" (Stop) and the "Input setting" is not set to "0" (Normal Mode), the pressure is not controlled even when the "Set value for pressure" of the Process Data OUT is set.

3.3.2 Preset input

Switch the set pressure by specifying eight set pressures and using the three bits of the Process Data OUT.

E.g.) To control 0, 50, 100, 150, 200, 300, 400 or 500 kPa with preset inputs, select Preset input for Input setting mode, and set the following respectively;

P1: 0 kPa P2: 50 kPa P3: 100 kPa P4: 150 kPa

P5: 200 kPa P6: 300 kPa P7: 400 kPa P8: 500 kPa

When a signal is input with the Process Data OUT, the pressure is switched to the set pressure stored in memory.

■ How to set Preset input (by key operation)

Set "Input setting" and enter set pressures for "Preset memory" P1 to P8 by key operation.

For the setting method by key operation, refer to pages 37 and 38.

■ How to set preset input (using IO-Link communication)

[Parameter settings]

• Input signal setting

Write "1: Preset Mode" to Index: 0x010F (Input setting).

• Setting preset memory 1 to 8

Write set pressure to Indexes: 0x0110 to 0x0117 (Preset memory 1 to 8).

Parameter and Command

| Index | Sub Index | Item | Value |
|--------|-----------|-----------------|--|
| 0x010F | 0 | Input setting | 0 : Normal Mode 1 : Preset Mode 2 : Direct Mode |
| 0x0110 | 0 | Preset memory 1 | Refer to "• Set pressure range for each model and unit". |
| - | - | - | |
| 0x0117 | 0 | Preset memory 8 | |



- The set pressure shall be entered in 4 digits. When you do not use IO-Link, you do not need to enter a decimal point; when you use IO-Link, you must include a decimal point.
- Do not enter a value outside the allowable range. User's programs should control the pressure so that it is within the allowable range for each model.

[Operation]
Process Data OUT

| PD | PD0 | | | | | | | | PD1 | | | | | | | |
|-----------|--------------|----|----|----|----|----|----|----|-----|----|----|----|----|----|----|-----|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 |
| | MSB | | | | | | | | | | | | | | | LSB |
| Data name | Set pressure | | | | | | | | | | | | | | | |

| PD | PD2 | | | | | | | | PD3 | | | | | | | |
|-----------|----------|----|----|----|----|--------|---|---|----------|---|---|---|---|---|---|------------|
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Data name | Not used | | | | | Preset | | | Not used | | | | | | | Start/Stop |
| | | | | | | 3 | 2 | 1 | | | | | | | | |

• **Setting active state (pressure controlled state)**
Set the "Start/Stop" bit of the Process Data OUT to "1" to activate. Control is performed at the pressure stored in the memory corresponding to the preset memory number.

• **Switching preset memory**
The preset memory number can be switched according to the "Preset" setting of the Process Data OUT. Entering the 3 bits of the "Preset" according to the table on the right will switch to the set pressures stored in the memory.

| "Preset" of Process Data OUT | | | Preset memory number |
|------------------------------|-------|-------|----------------------|
| Bit 3 | Bit 2 | Bit 1 | |
| 0 | 0 | 0 | P1 |
| 0 | 0 | 1 | P2 |
| 0 | 1 | 0 | P3 |
| 0 | 1 | 1 | P4 |
| 1 | 0 | 0 | P5 |
| 1 | 0 | 1 | P6 |
| 1 | 1 | 0 | P7 |
| 1 | 1 | 1 | P8 |

[Confirmation]
Process Data IN

| PD | PD0 | | | | | | | | PD1 | | | | | | | |
|-----------|--|----|----|----|----|----|----|----|-----|----|----|----|----|----|----|-----|
| Bit | 47 | 46 | 45 | 44 | 43 | 42 | 41 | 40 | 39 | 38 | 37 | 36 | 35 | 34 | 33 | 32 |
| | MSB | | | | | | | | | | | | | | | LSB |
| Data name | Set pressure ← The set pressure in the preset memory corresponding to the specified number is displayed. | | | | | | | | | | | | | | | |

| PD | PD2 | | | | | | | | PD3 | | | | | | | |
|-----------|---|----|----|----|----|----|----|----|-----|----|----|----|----|----|----|-----|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 |
| | MSB | | | | | | | | | | | | | | | LSB |
| Data name | Controlled pressure ← EVD's controlled pressure value is displayed here | | | | | | | | | | | | | | | |

| PD | PD4 | | | | | | | | PD5 | | | | | | | |
|-----------|-------|---------|------------------|----|----|----|---------------|---|------------|---|---|-----|---------------|---|---|------------|
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | - | - | - | - | - | - | - | - | - | - | - | - | 0 | 1 | - | 1 |
| Data name | Error | WARNING | Normal operation | - | - | - | Switch output | | MSB | | | LSB | Input setting | | - | Start/Stop |
| | | | | | | | 2 | 1 | Error code | | | | | | | |

The controlled pressure, start/stop status, input setting, and set pressure can be checked with the Process Data IN.
Check the current set pressure with the "Set value for pressure" in Process Data IN.



• When the "Start/Stop" bit of the Process Data IN is set to "0" (Stop) and the "Input setting" is not set to "1" (Preset Mode), the pressure is not controlled even after the "Preset" bit of the Process Data OUT is switched.

3.3.3 Direct memory input

"Input setting" can be changed to the direct memory input mode in the IO-Link communication, but the direct memory value itself cannot be set. To set the value, use key operation. Changing the "Input setting" does not clear the direct memory value. To change the set pressure in IO-Link communication, use the Normal Mode.

[Parameter settings]

• **Input signal setting**

Write "2: Direct Mode" to "Index: 0x010F (Input setting)".

Parameter and Command

| Index | Sub Index | Item | Value |
|--------|-----------|---------------|---|
| 0x0115 | 0 | Input setting | 0 : Normal Mode 1 : Preset Mode 2 : Direct Mode |

[Confirmation]

Process Data IN

| PD | PD0 | | | | | | | | PD1 | | | | | | | |
|-----------|---|----|----|----|----|----|----|----|-----|----|----|----|----|----|----|-----|
| Bit | 47 | 46 | 45 | 44 | 43 | 42 | 41 | 40 | 39 | 38 | 37 | 36 | 35 | 34 | 33 | 32 |
| | MSB | | | | | | | | | | | | | | | LSB |
| Data name | Set pressure ← The value set in the direct memory is displayed. | | | | | | | | | | | | | | | |

| PD | PD2 | | | | | | | | PD3 | | | | | | | |
|-----------|---|----|----|----|----|----|----|----|-----|----|----|----|----|----|----|-----|
| Bit | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 |
| | MSB | | | | | | | | | | | | | | | LSB |
| Data name | Controlled pressure ← EVD's controlled pressure value is displayed here | | | | | | | | | | | | | | | |

| PD | PD4 | | | | | | | | PD5 | | | | | | | |
|-----------|-------|---------|------------------|----|----|----|---------------|---|------------|---|---|-----|---------------|---|---|------------|
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | - | - | - | - | - | - | - | - | - | - | - | - | 1 | 0 | - | 1 |
| Data name | Error | WARNING | Normal operation | - | - | - | Switch output | | MSB | | | LSB | Input setting | | - | Start/Stop |
| | | | | | | | 2 | 1 | Error code | | | | | | | |

The controlled pressure, start/stop status, input setting, and set pressure can be checked with the Process Data IN.

Check the current set pressure with the "Set value for pressure" in Process Data IN.

- When the "Input setting" is not set to "2" (Direct Mode), the pressure is not controlled with the direct memory setting value.
- Regardless of the "Start/Stop" setting of the Process Data OUT, the pressure is controlled in the Direct Mode.

3.4 Monitoring overactive state of solenoid valve

3.4.1 Monitoring overactive state of solenoid valve

The IO-Link communication can be used to monitor the operating status of the two solenoid valves used inside the EVD and obtain data.

An overactive state can occur even when the product is operating normally. Analyze this information on the overactive state to help select a model (EVD-1000 or EVD-3000, etc.) for your system.

For the overactive state, refer to "7. References".

<Example of use that tends to cause the overactive state>

- Blow control
- Filling large tanks with air, etc.

3.4.2 Acquired data

The following parameters are used to inform the status of the solenoid valve.

| Index | Sub Index | Item | Value |
|--------|-----------|--|----------------------|
| 0x0400 | 0 | Solenoid valve energizing time | 0 to 9,999,999h |
| 0x0401 | 0 | Operating time in overactive state of air supply-side solenoid valve | 0 to 9,999,999h |
| 0x0402 | 0 | Number of excessive operations of supply solenoid valve | 0 to 9,999,999 times |
| 0x0403 | 0 | Operating time in overactive state of exhaust-side solenoid valve | 0 to 9,999,999h |
| 0x0404 | 0 | Number of excessive operations of exhaust solenoid valve | 0 to 9,999,999 times |

Solenoid valve energizing time (Index: 0x0400)

Measure time in which the "Start/Stop" bit of the Process Data IN is set to "1".

Reading this index returns solenoid valve energization time in unit of hour (h).

Operating time in overactive state of air supply-side solenoid valve (Index: 0x0401)

Measure time in which the air supply-side solenoid valve is operating in the overactive state.

Reading this index returns the operating time in the overactive state of the air supply-side solenoid valve in unit of hour (h).

Number of operations in overactive state of air supply-side solenoid valve (Index: 0x0402)

Count the number of the operations in overactive state of the air supply-side solenoid valve.

Reading this index returns the number of the operations in overactive state of the air supply-side solenoid valve.

The number of operations is counted when the state is determined to have changed from the non-overactive state to the overactive state.

Operating time in overactive state of exhaust-side solenoid valve (Index: 0x0403)

Measure time in which the exhaust-side solenoid valve is operating in the overactive state.

Reading this index returns the operating time in the overactive state of the exhaust-side solenoid valve in unit of hour (h).

Number of operations in overactive state of exhaust-side solenoid valve (Index: 0x0404)

Count the number of the operations in overactive state of the exhaust-side solenoid valve.

Reading this index returns the number of the operations in overactive state of the exhaust-side solenoid valve.

The number of operations is counted when the state is determined to have changed from the non-overactive state to the overactive state.

Note: The solenoid valve overactive state data is saved when the Start/Stop bit (Bit 0) of the Process Data OUT changes from start to stop. At the end of operation of the EVD, be sure to change the "Set Pressure" from 0 (Bit 16-31 = 0) to Stop (Bit 0 = 0), and then turn off the power. For details, refer to "1.5.5 Process Data OUT".

[Confirmation]
Process Data IN

| PD | PD4 | | | | | | | | PD5 | | | | | | | |
|-----------|-------|---------|------------------|----|----|----|---------------|---|------------|---|---|-----|---------------|---|---|------------|
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Data name | Error | WARNING | Normal operation | - | - | - | Switch output | | MSB | | | LSB | Input setting | | - | Start/Stop |
| | | | | | | | 2 | 1 | Error code | | | | | | | |

When the solenoid valve is operating in the overactive state, the "Warning" flag of the Process Data IN changes to "1: ON" and the code corresponding to the error code is displayed, besides updating the values of the above parameters.

An IO-Link event code is stored in the Detailed Devices Status (Index: 0x0025) of the parameter.

| Error code | Event code | Error description | Control processing (solenoid valve operation) |
|------------|------------|--|---|
| E 10 | 0x8D10 | The air supply-side solenoid valve is in the overactive state. | The pressure control does not stop. |
| E 11 | 0x8D11 | The exhaust-side solenoid valve is in the overactive state. | The pressure control does not stop. |

* The EVD continues the pressure control even if it is determined to be in the overactive state.

3.4.3 How to obtain data

Data on solenoid valve's overactive state can be obtained by reading the index described in "Acquired data".

E.g.) Monitoring of the overactive state of the air supply-side solenoid valve

Checking operating time in overactive state

Read Index: 0x0401.

When a data value of 3 is returned ⇒ The operating time in the overactive state is 3 hours.

Checking the number of operations in overactive state

Read Index: 0x0402.

When data value 10 is returned ⇒ The number of the operations in the overactive state is 10 times.

4. MAINTENANCE AND INSPECTION

WARNING

Turn off the power, stop the supply of compressed air and make sure that there is no residual pressure before maintenance.

CAUTION

Plan and conduct daily and periodic inspections so that maintenance can be managed correctly.

If maintenance is not properly managed, the product's functions may deteriorate significantly and this may lead to faults (such as short service life, damage, and malfunctions) or accidents.

If an abnormality occurs during operation, immediately stop using the product, turn off the power, and shut off the pneumatic pressure source.

Conduct periodic inspections at least once a year to confirm that the product operates properly.

Do not use materials such as solvents, alcohol, or detergent to remove dirt or stains.

The case is made of resin and resin can be damaged by these materials. Use a waste cloth that is soaked in a diluted neutral detergent and wrung out well to wipe off dirt.

4.1 Periodic Inspection

Conduct periodic inspections at least once a year to prevent accidents or problems, such as functional deterioration, short service life, damage, or malfunctions.

■ Pressure of supplied compressed air

- Is the set pressure supplied?
- Does the pressure gauge indicate the set pressure during operation of the device?

■ Pneumatic filter

- Is drainage correctly discharged?
- Is the bowl or element clean enough to use?

■ Leakage of compressed air from piping connections

- Are all connections, especially at movable sections, correctly connected?
(The product may not operate properly if leakage occurs from piping.)

■ Operational status

- Is there any delay in operation?
- Are the valves exhausting properly?

■ Operation of pneumatic actuator

- Are operations smooth?
- Is the actuator reaching the end stop properly?
- Are loads connected properly?

If an abnormality is found, contact your nearest CKD sales office or distributor.

5. TROUBLESHOOTING

5.1 Problems, Causes, and Solutions

If the product does not operate as intended, check the table below for a possible solution.

| Problem | Cause | Solution |
|----------------------------------|--|---|
| Setting cannot be changed. | Key is locked. | Release the key lock according to "3.2.2 Key lock" and change the settings. |
| | Operation keys do not work. | Replace the product. |
| | Communication error occurs. | Check the status of the IO-Link lamp. *When the red dot is lit, communication between the EVD and IO-Link master has not been established. Please check the wiring as there is a possibility of disconnection, etc. Check the status of the green dot on the bottom right. *When the green dot is blinking, Process Data Out is disabled. Check the communication status, as communication may not be established between the IO-Link master and its upper network. |
| Pressure does not display. | Automatic power off function is enabled. | Press any operation key. * If the display turns on and then off after one minute, the automatic power off function is enabled. * Refer to "3.2.4 Automatic power off" to disable the automatic power off. |
| | Power supply is not connected correctly. | Connect the rated power correctly. |
| | There is disconnection inside EVD. | Replace the product. |
| Displayed pressure is abnormal. | Primary side pressure is insufficient. | Maintain the primary side supply pressure so that it is at least the minimum working pressure. |
| | There is leakage on secondary side piping. | Check if there is leakage from piping. |
| | There is a failure in pressure sensor. | Replace the product. Make sure that excessive pressure does not apply on the secondary side due to pressure entering from other pipes. |
| Switch output does not turn ON. | Switch output is disabled. | Refer to "3.2.5 Switch output". |
| | There is a failure in EVD. | Replace the product. |
| Switch output does not turn OFF. | There is a failure in EVD. | Replace the product. |
| Loud noise is generated. | There is significant leakage which is greater than maximum flow rate. | Using the product in this state will shorten the service life extremely. Reconsider the usage. |
| | There is air entering from secondary side piping which exceeds relief performance. | Using the product in this state will shorten the service life extremely. Reconsider the usage. |
| | Power is turned on and input signal is set with no primary side pressure supplied. | Supply the primary side pressure and then turn on the power supply and set the input signal. |
| | Set input signal is greater than primary side pressure. | Maintain the primary side supply pressure so that it is at least the minimum working pressure. |
| | Primary side pressure is less than minimum working pressure. | Maintain the primary side supply pressure so that it is at least the minimum working pressure. |

| Problem | Cause | Solution |
|--|--|---|
| 1%FS or more pressure is output even if power is turned off. | Zero point is increased with zero/span adjustment. | If the zero point is increased, the set pressure is output even when the power is turned off. If atmospheric pressure condition is required, install a 3-way valve on the secondary side. |
| | Power is turned off while input signal is set. | Turn on the power and set the input signal to 0%. |
| | Product has been left with power turned off and with primary side pressure supplied for a long period. | If the product has been left unused for a long period, set the primary side pressure to zero. If the secondary side pressure rises, turn on the power and set the input signal to 0%. |
| | There is a failure in EVD. | Make sure that there is no abnormality in piping and wiring and then replace the product. |
| Primary side pressure is output as it is. | There is a failure in EVD. | Make sure that there is no abnormality in piping and wiring and then replace the product. |
| Pressure cannot be controlled. | Input signal is abnormal. | Check the input signal type. |
| | | Check the setting range. (Refer to "On demand data".) |
| | There is a failure in pressure sensor. | Replace the product. Make sure that excessive pressure does not apply on the secondary side due to pressure entering from other pipes. |
| Pressure is not output. | Primary side pressure is not supplied. | Check that the primary side pressure is at least the minimum working pressure. |
| | Wiring is abnormal. | Check that the wiring is normal. In addition, check that the connector is properly connected. |
| Pressure does not reach set pressure. | Primary side pressure is insufficient. | Maintain the primary side supply pressure so that it is at least the minimum working pressure. |
| Pressure does not drop. | Passage of exhaust port is blocked. | Mount the product so that the air can be exhausted from port R and the exhaust port. |
| Pressure is unstable. | Power supply voltage is unstable. | Use a stabilized power supply that satisfies the product specifications. |
| | Input signal is unstable. | Check whether the noise is affecting the signal. |
| | Primary side pressure is unstable. | Install a regulator on the primary side of the EVD. |
| | There is leakage from piping. | Check leakage from piping on the primary side and secondary side. * Changing the proportional value ("Lower proportional value") may stabilize the pressure (refer to "3.1.4 Proportional value"). |
| Pressure oscillates. | Primary side pressure is too high against control pressure. | Reduce the primary side supply pressure as much as possible but maintain at least the minimum working pressure. |
| | Mismatched piping capacity, leakage, or foreign matter contamination on the secondary side. | Oscillation may be avoided by changing the piping condition. Reconsider the diameter of the piping, increase or decrease the load capacity, or check leakage on the secondary side. * Changing the proportional value ("Lower proportional value") may stabilize the pressure (refer to "3.1.4 Proportional value"). |

5.2 Error Code



Turn off the power, check and correct the cause of the error according to the table below, and then turn on the power again.

| Error indication | Classification | Name of error | Event code (IO-Link) | Error description | Control processing (Solenoid valve operation) |
|--|----------------|--|----------------------|---|---|
| | Error | Power supply voltage error | 0x8D02 | Supplied power voltage is outside the rated range. Detection level is 19.5 V or lower | The pressure control does not stop. |
| | Error | Input signal error | 0x8D03 | Input signal exceeds the rated range. Detection level: Upper limit of specification +10% | The pressure control does not stop. * Controlled with input signals of 110% F.S. |
| | Error | EEPROM data error | 0x8D04 | An error occurred during EEPROM reading or writing. | The pressure control is stopped. |
| | Error | ROM data error | 0x8D05 | An error occurred during memory reading or writing. | The pressure control is stopped. |
| | Error | Controlled pressure error | 0x8D06 | The secondary side pressure continues to remain below the set value for 5 seconds or more. It falls below the set value by 20%F.S. or more. Detection accuracy: ±6% | The pressure control does not stop. |
| 7-segment display is not performed. The error code is "E 10". | Warning | Air supply-side solenoid valve operating in overactive state | 0x8D10 | The air supply-side solenoid valve is in the overactive state. | The pressure control does not stop. |
| 7-segment display is not performed. The error code is "E 11". | Warning | Exhaust-side solenoid valve operating in overactive state | 0x8D11 | The exhaust-side solenoid valve is in the overactive state. | The pressure control does not stop. |
| 7-segment display is not performed. The error code is "E 12". | Warning | Switch output 1 setting error | 0x8D12 | The state of lower limit > (upper limit - 10) continues for more than 5 seconds for the threshold setting of Switch output 1 (Mode 2). | The pressure control does not stop. |
| 7-segment display is not performed. The error code is "E 13". | Warning | Switch output 2 setting error | 0x8D13 | • The state of lower limit > (upper limit - 10) continues for more than 5 seconds for the threshold setting of Switch output 2 (Mode 2). | The pressure control does not stop. |
| 7-segment display is not performed. The error code is "E 14". | Warning | IO-Link driver temperature error | 0x4210 | The temperature of the IO-Link driver is high. | The pressure control does not stop. |

* When any of the errors of the above categories occurs, the "Error" flag of the Process Data IN is set to "1: ON" while displaying the error.

* When any of the warning of the above categories occurs, the "Warning" flag of the Process Data IN is set to "1: ON".

* About resetting of "E 05"

• Can be reset with Preset P1 or direct memory operation. It can also be reset with IO-Link communication. While setting the preset memory or direct memory, pressing and holding down the and keys for 2 seconds or longer during occurrence of error 5 change the screen to the setting entry screen. Pressing and holding the key at least 2 seconds change the set pressure to "0" and reset error 5.

*Note: This operation resets the set pressure to "0" and changes the output pressure to "0". Be sure to check the impact of resetting error 5 on the air pressure equipment before resetting.

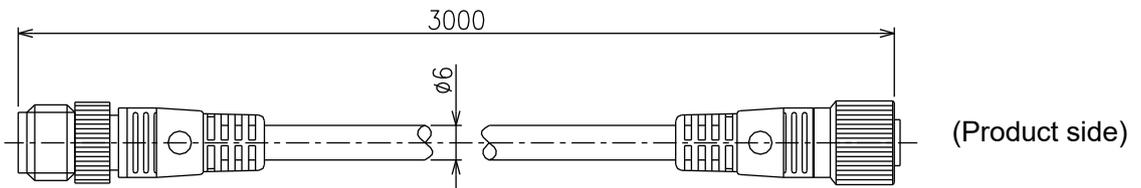
6. OPTION

6.1 Optional Part Model Number

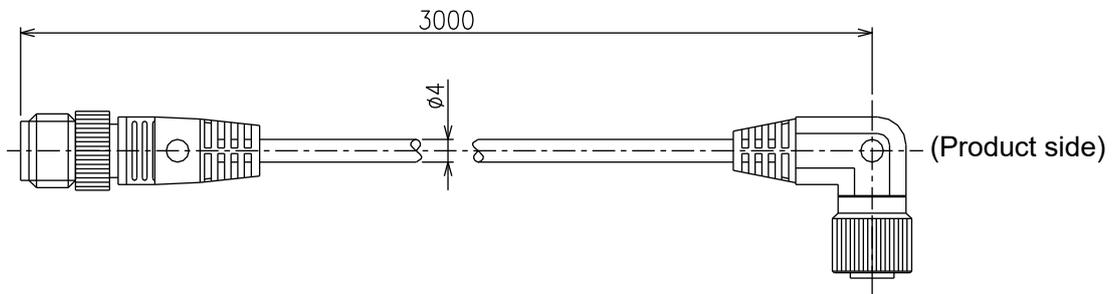
EVD-MS3

| Code | Description |
|---------------------|--|
| Cable option | |
| MS3 | IO-Link Straight (female)/straight (male) 3 m |
| ML3 | IO-Link L-type (female)/straight (male) 3 m |
| MM3 | IO-Link One-side straight (female) 3 m |

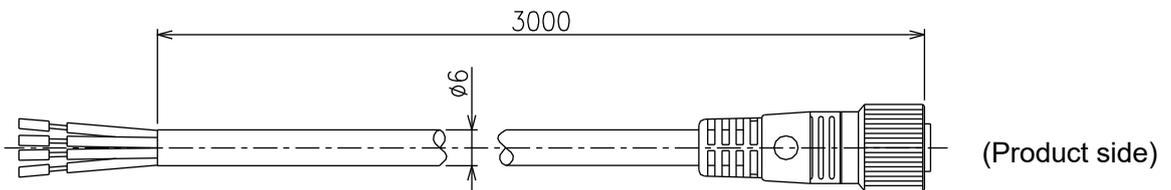
●EVD-MS3



●EVD-ML3



●EVD-MM3



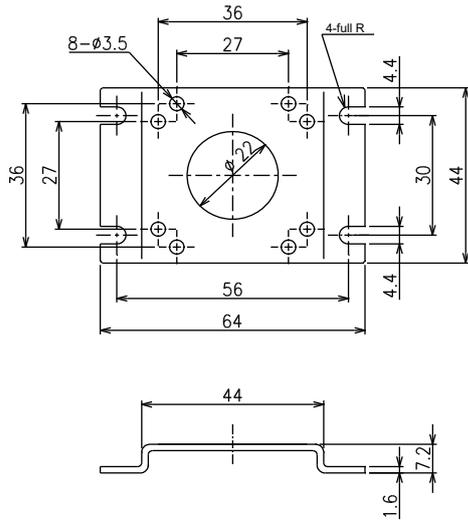
| Cable color | Application |
|-------------|-------------|
| Brown | L+ (24 VDC) |
| White | N.C. * |
| Blue | L- (GND) |
| Black | C (IO-Link) |

* Please insulate to avoid contact with other wires.

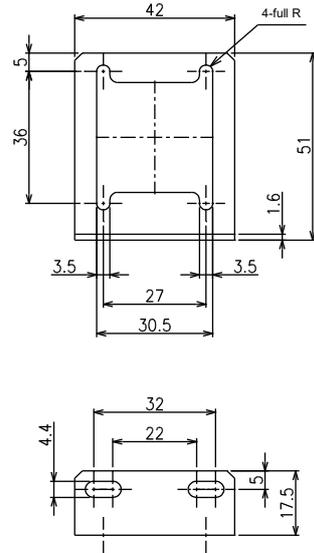
EVD- B1

| Code | Description |
|-----------------------|---|
| Bracket option | |
| B1 | B-type bracket, floor mounted, EVD-1000 |
| L1 | L-type bracket, wall mounted, EVD-1000 |
| B3 | B-type bracket, floor mounted, EVD-3000 |
| L3 | L-type bracket, wall mounted, EVD-3000 |

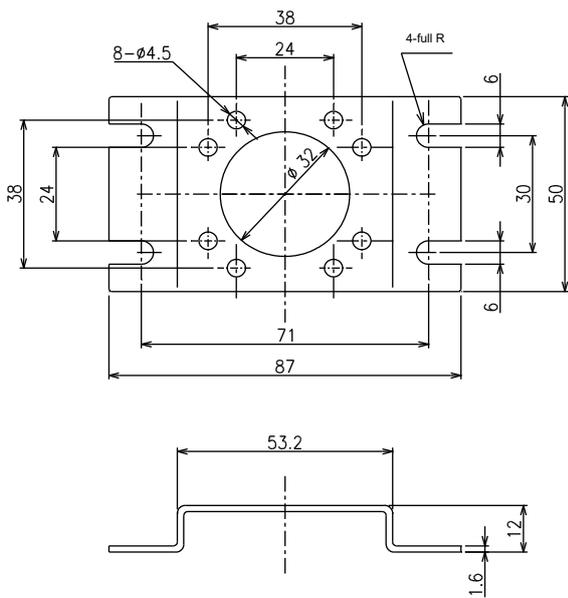
●EVD-B1



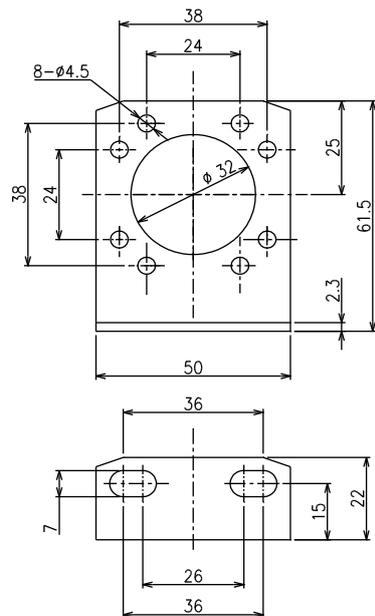
●EVD-L1



●EVD-B3



●EVD-L3



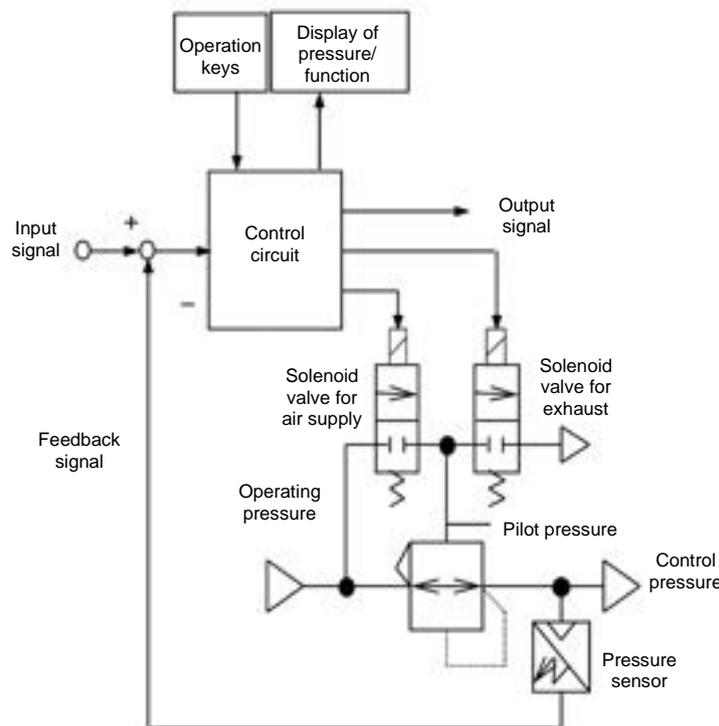
7. REFERENCES

7.1 Operating principle of digital electro-pneumatic regulator

7.1.1 Operating principle

The digital electro-pneumatic regulator performs feedback control to control the pilot pressure by detecting controlled pressure using a pressure sensor and PWM-driving two-port solenoid valves for air supply and exhaust.

■ Configuration of control circuit



■ PWM drive

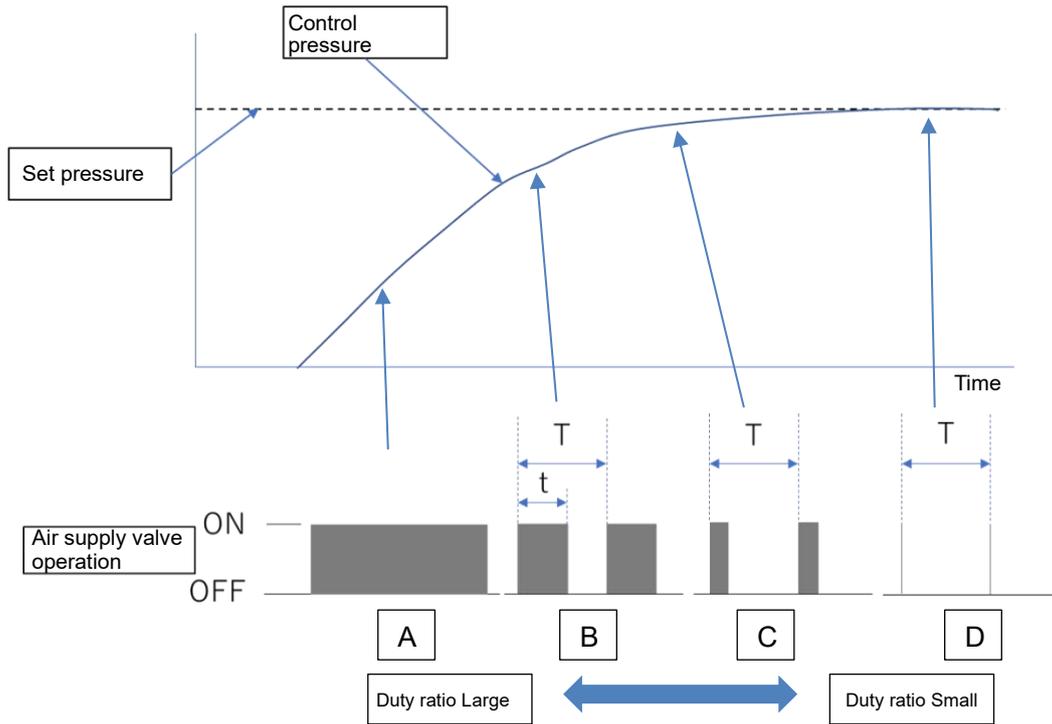
The pulse width modulation (PWM) is a form of electrical signal and controls the ratio of ON pulse width time to OFF pulse width time in a certain period of time (Duty ratio).

$$\text{Duty ratio} = t / T \times 100 (\%)$$

■ Relationship between PWM driving and controlled pressure

The set pressure and the controlled pressure are compared, and the solenoid valve ON time is varied based on the difference between the pressures to control the pilot pressure so that the controlled pressure equals the set pressure. A larger difference increases the Duty ratio and expands the solenoid valve ON time. A smaller difference reduces the Duty ratio and shortens the solenoid valve ON time.

• **Pressure control diagram**



■ **EVD-1000**

The EVD-1000 series includes the pilot control section described above and a booster section for improving the flow characteristics. The booster section includes air supply and exhaust valves and a diaphragm for opening and closing them. The exhaust valve is connected to the diaphragm. The lower chamber of the diaphragm has the same pressure as the controlled pressure. The upper chamber controls the pilot pressure by PWM-driving the solenoid valve. This difference in pressure moves the diaphragm up and down to open and close the valve.

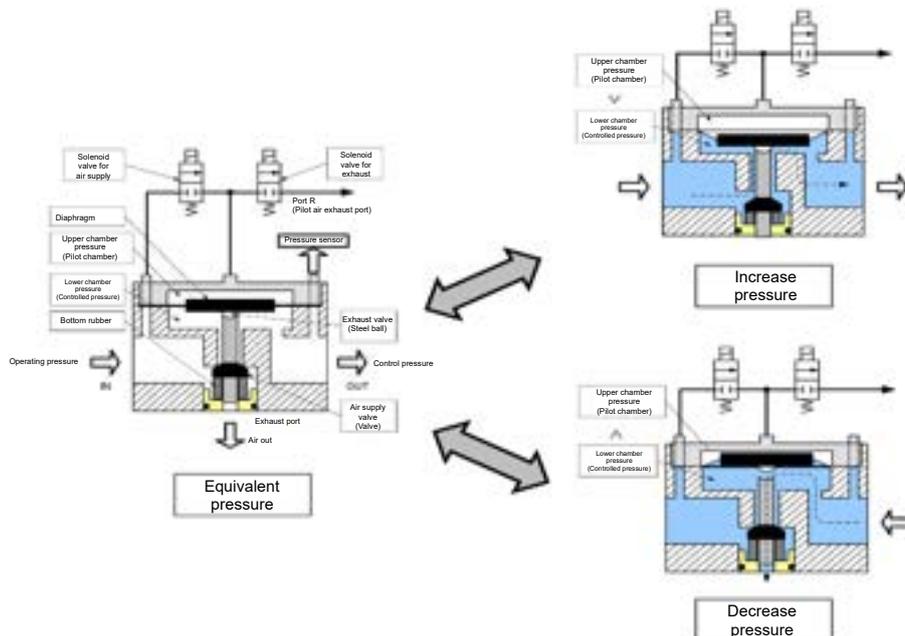
It senses the controlled pressure with a pressure sensor to constantly adjust the pilot pressure as follows for high-precision pressure control:

When the controlled pressure is lower than the set pressure, that is, the controlled pressure is to be boosted;

Upper chamber pressure (pilot pressure) > Lower chamber pressure (controlled pressure)

When the controlled pressure is higher than the set pressure, that is, the controlled pressure is to be reduced;

Upper chamber pressure (pilot pressure) > Lower chamber pressure (controlled pressure)



■ **EVD-3000**

The EVD-3000 series includes the pilot control section described above and a booster section for improving flow characteristics. The booster section includes an air supply valve (top valve), an exhaust valve (bottom valve), and a piston assembly to open and close them. The exhaust valve is connected to the piston assembly.

The lower chamber of the piston assembly has the same pressure as the controlled pressure. The upper chamber controls the pilot pressure by PWM-driving the solenoid valve. This difference in pressure moves the piston assembly up and down to open and close the valve.

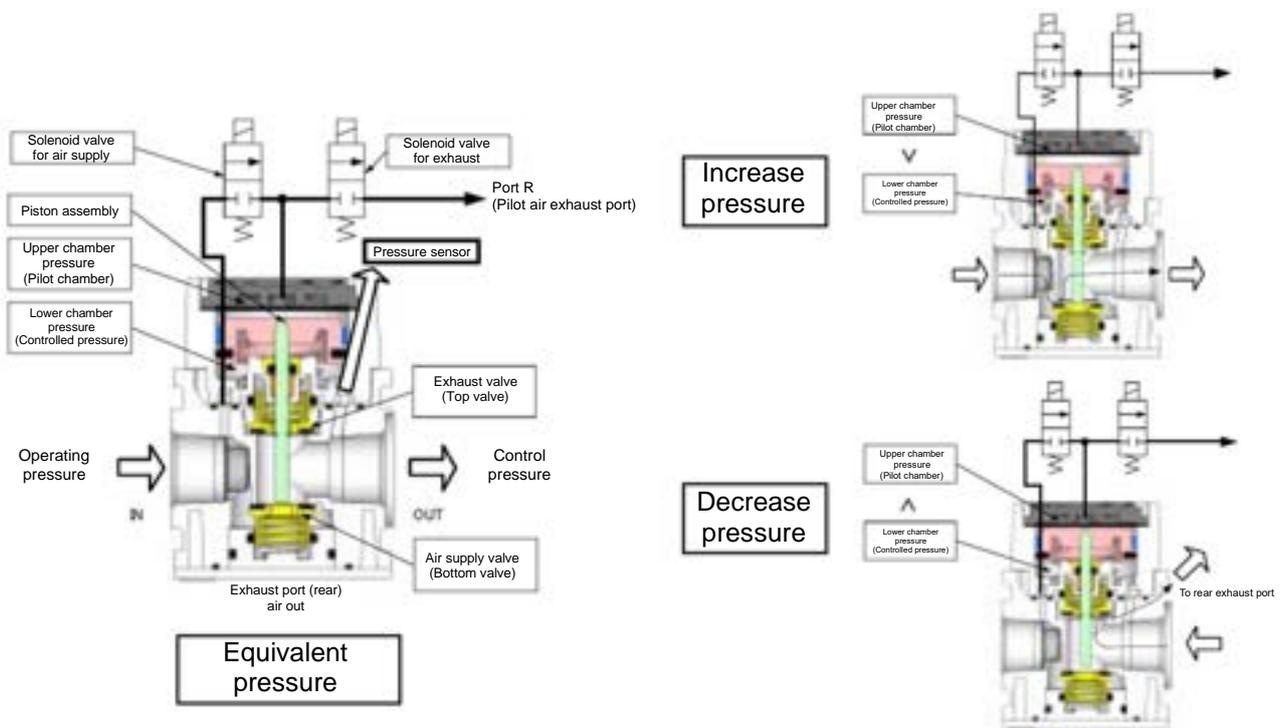
It senses the controlled pressure with a pressure sensor to constantly adjust the pilot pressure as follows for high-precision pressure control:

When the controlled pressure is lower than the set pressure, that is, the controlled pressure is to be boosted;

$$\text{Upper chamber pressure (pilot pressure)} > \text{Lower chamber pressure (controlled pressure)}$$

When the controlled pressure is higher than the set pressure, that is, the controlled pressure is to be reduced;

$$\text{Upper chamber pressure (pilot pressure)} < \text{Lower chamber pressure (controlled pressure)}$$



■ **7.1.2 About overactive state**

Definition of overactive state: The overactive state is defined as a state in which the solenoid valve continues to turn ON and OFF repeatedly like the patterns B and C as shown in "• Pressure control diagram" above.

A continuous ON time like the pattern A or an extremely short ON time like the pattern D will not cause the overactive state.

If this overactive state continues for a long time, the life of the solenoid valve will be greatly affected.

8. WARRANTY PROVISIONS

8.1 Warranty Conditions

■ Warranty coverage

If the product specified herein fails for reasons attributable to CKD within the warranty period specified below, CKD will promptly provide a replacement for the faulty product or a part thereof or repair the faulty product at one of CKD's facilities free of charge.

However, following failures are excluded from this warranty:

- Failure caused by handling or use of the product under conditions and in environments not conforming to those stated in the catalog, the Specifications, or this Instruction Manual.
- Failure caused by incorrect use such as careless handling or improper management.
- Failure not caused by the product.
- Failure caused by use not intended for the product.
- Failure caused by modifications/alterations or repairs not carried out by CKD.
- Failure that could have been avoided if the customer's machinery or device, into which the product is incorporated, had functions and structures generally provided in the industry.
- Failure caused by reasons unforeseen at the level of technology available at the time of delivery.
- Failure caused by acts of nature and disasters beyond control of CKD.

The warranty stated herein covers only the delivered product itself. Any loss or damage induced by failure of the delivered product is excluded from this warranty.

■ Confirmation of product compatibility

It is the responsibility of the customer to confirm compatibility of the product with any system, machinery, or device used by the customer.

■ Others

The terms and conditions of this warranty stipulate basic matters.

When the terms and conditions of the warranty described in individual specification drawings or the Specifications are different from those of this warranty, the specification drawings or the Specifications shall have a higher priority.

8.2 Warranty Period

The product is warranted for one (1) year from the date of delivery to the location specified by the customer.